

# Efficient Implementation of Exact Geometric Computations in CGAL

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# Plan

- 1 Introduction
- 2 Some algorithms and their primitives
- 3 Robustness issues
- 4 Arithmetic
- 5 Conclusion

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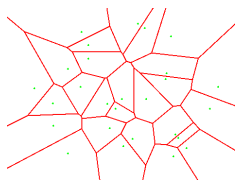
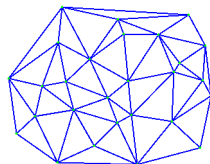
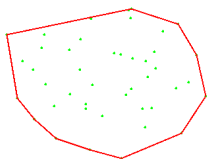
# Computational Geometry

- Active research domain since 30 years
- Algorithms handle large number of geometric objects
- Emphasis on asymptotic complexity (Real-RAM model)

Application domains: CAD/CAM, GIS, molecular biology, medical imaging...

# Examples

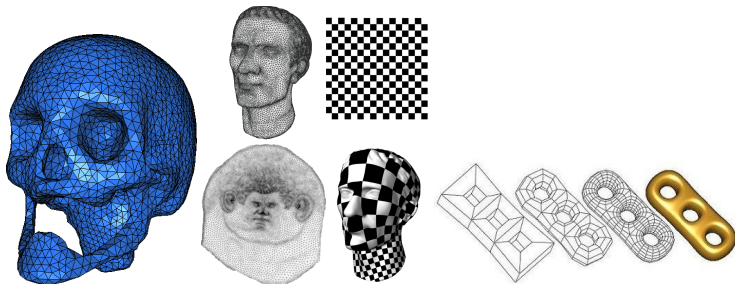
- Convex hulls, triangulations, Voronoi diagrams



- Surface reconstruction, meshing
- Boolean operations on polygons, arrangements
- Geometric optimization
- ...

# Examples : applications

- Surface reconstruction and meshing
- Surface parameterization
- Surface subdivision



# CGAL: *Computational Geometry Algorithms Library*

Since 1995 : implement Computational Geometry algorithms.

- **Criteria : adaptability, efficiency, robustness**
- Contributions are reviewed by an Editorial Board
- Chosen language : C++ (generic programming)
- v3.2 : 100 modules, 500.000 code lines, 10,000 downloads/year
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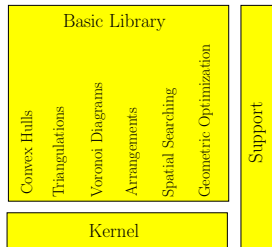
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# CGAL: Architecture

General architecture : kernel, basic library, support library



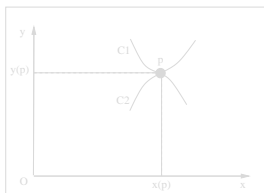
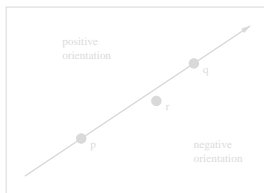
# Kernel of geometric primitives

Algorithms are logically split in :

- a **combinatorial** part (graph building)
- a **numerical** part (needs coordinates)

The later calls primitives gathered in the *kernel* :

- **Basic objects**: points, segments, lines, circles...
- **Predicates**: orientations, coordinate comparisons...
- **Constructions**: intersection and distance computations...



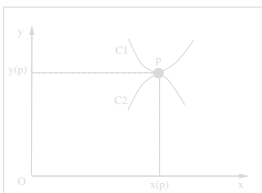
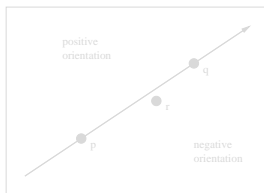
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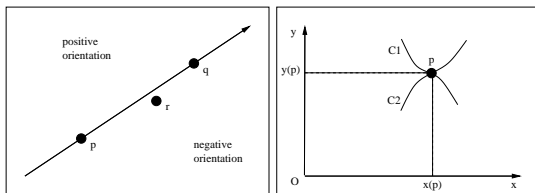
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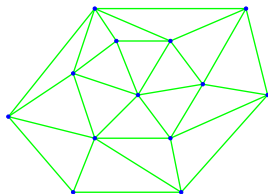
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# Delaunay triangulation

Incremental algorithm in 2 stages: **point location** and **update**.

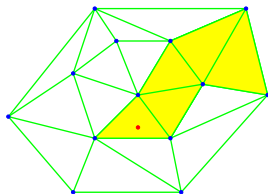


Point location: **orientation**(p, q, r) predicate, sign of:

$$\begin{vmatrix} 1 & p_x & p_y \\ 1 & q_x & q_y \\ 1 & r_x & r_y \end{vmatrix} = \begin{vmatrix} q_x - p_x & q_y - p_y \\ r_x - p_x & r_y - p_y \end{vmatrix}$$

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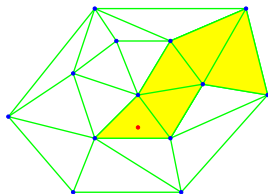


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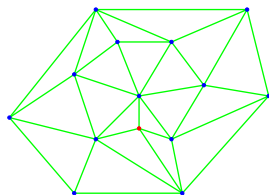
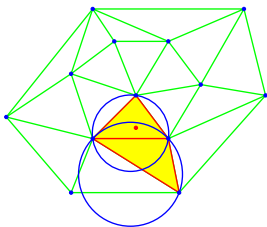


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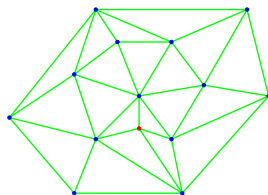
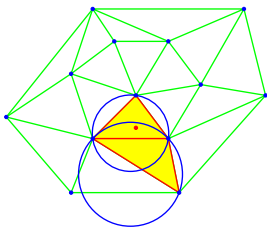


Update: `in_circle(p, q, r, s)` predicate, sign of:

$$\begin{vmatrix} 1 & px & py & px^2 + py^2 \\ 1 & qx & qy & qx^2 + qy^2 \\ 1 & rx & ry & rx^2 + ry^2 \\ 1 & sx & sy & sx^2 + sy^2 \end{vmatrix}$$

# Delaunay triangulation

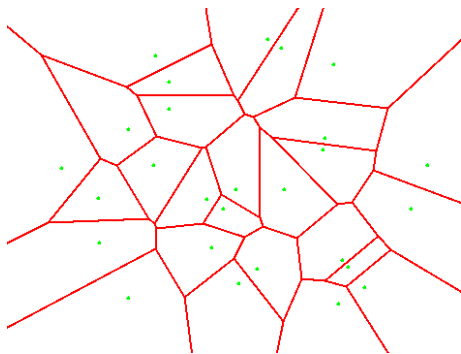
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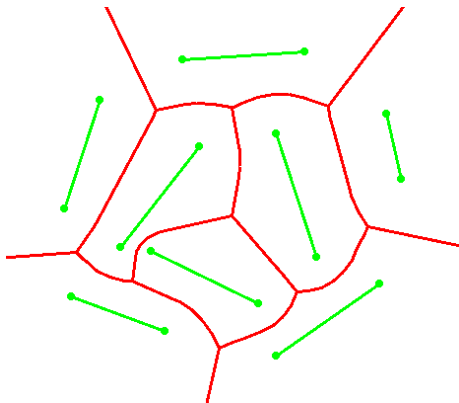
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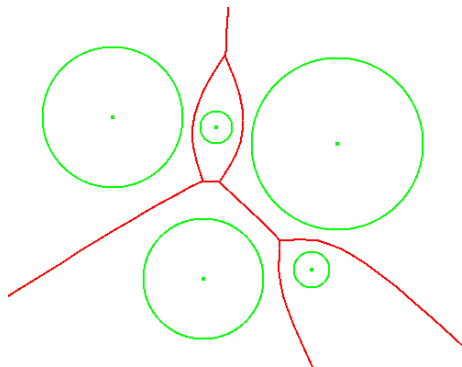
# Voronoi diagrams of points



# Voronoi diagrams of segments

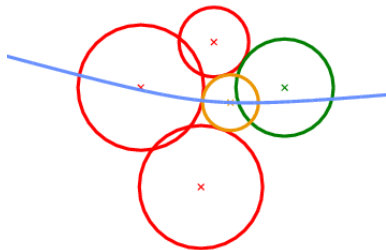


# Voronoi diagrams of circles





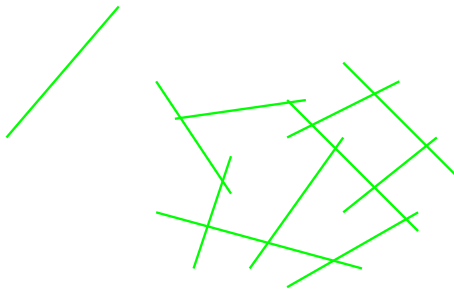
# One of the predicates of the Voronoi diagram of circles



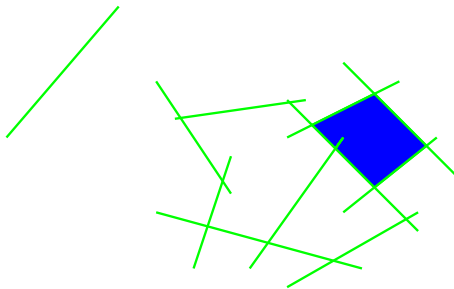
Root comparison techniques

[Karavelas, Emiris: SODA'03]

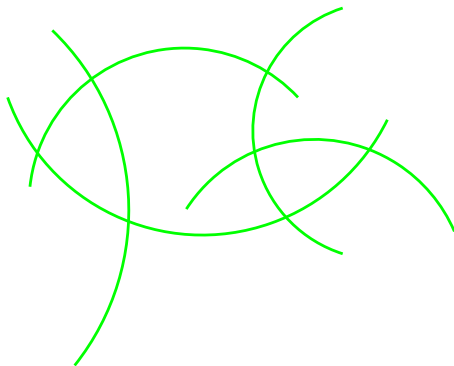
# Arrangements of line segments



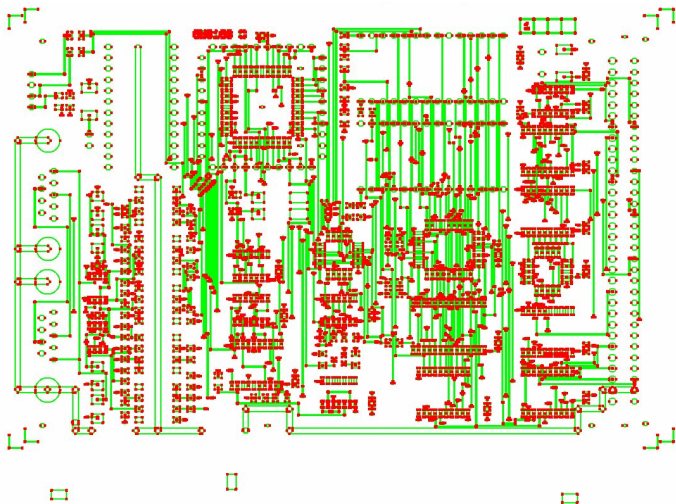
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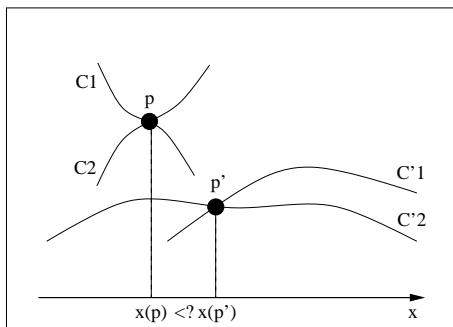
# Arrangements of circular arcs



# Application: union of polygons in VLSI



# Comparison of abscissa of curve intersections



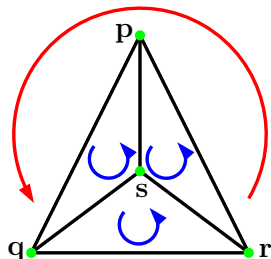
Algebraic curves, comparisons of algebraic numbers

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# Robustness

Algorithms rely on mathematic theorems, like:

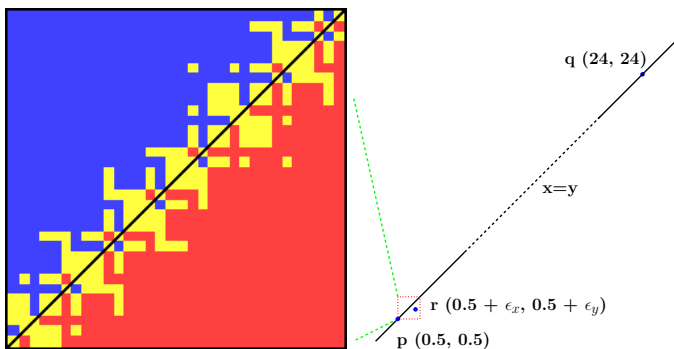


$$\begin{aligned} & \text{ccw}(s, q, r) \\ & \text{ccw}(p, s, r) \quad \Rightarrow \quad \text{ccw}(p, q, r) \\ & \text{ccw}(p, q, s) \end{aligned}$$



# Robustness

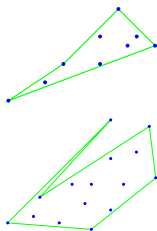
Example where **floating-point geometry** differs from real geometry:  
orientation of almost collinear points.



[Kettner, Mehlhorn, Schirra, P., Yap, ESA'04]

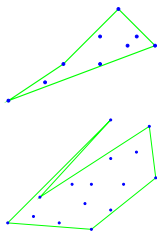
# Possible consequences on the algorithms

- The result can be slightly off
- The result can be completely off
  - The algorithm stops because of an unexpected impossible state
  - The algorithm loops forever



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# Robustness: solutions

- Case by case handling : painful, error prone and not mathematically nice
- Use **exact predicates** (*Exact Geometric Computing*)

## Remarks

- Floating-point computing fails on [nearly] degenerate cases.
- These cases happen often in practice.

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# Number types

Geometric primitives are parameterized by the arithmetic.

- Multi-precision integers
- Multi-precision rationals
- Multi-precision floating-point
- Interval arithmetic (single or multi-precision bounds)

[GMP, MPFR, LEDA...]

Algebraic numbers:

- Numeric evaluation with separation bounds
- Polynomials, Sturm sequences, resultants...

[CORE, LEDA]

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# Generic programming

Parameterization using templates.

```
template < class T >
T min (T a, T b)
{
    if (a < b)
        return a;
    else
        return b;
}
```

...

```
min(1, 2);           // instantiates min() with T = int.
min(1.0, 2.0);      // instantiates min() with T = double.
```

# Generic programming in CGAL

Several levels of parameterization :

- Algorithms parameterized by the geometry (kernel)

```
template < class Traits >  
class Triangulation_3;
```

- Kernels parameterized by the arithmetic (number types)

```
template < class T >  
class Cartesian;
```

Plugging the 2 layers:

```
typedef CGAL::Cartesian<double>          Kernel;  
typedef CGAL::Triangulation_3<Kernel>    Triangulation_3;
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# Filtered predicates

Speed-up exact predicates using a filter:

- floating-point evaluation with a **certificate**
- multi-precision arithmetic only when needed

## Examples

- interval arithmetic (dynamic filters),  
[Burnikel, Funke, Seel – Brönnimann, Burnikel, P'98]
- or code analysis (static filters) [Fortune'93... Melquiond, P'05]

Implementation issues:

- automatic generation of filtered predicates
- cascading several methods



# Filtered predicates : generic implementation

Predicates as generic functors:

```
template <class Kernel>
class Orientation_2
{
    typedef Kernel::Point_2    Point_2;
    typedef Kernel::FT         Number_type;

    Sign
    operator()(Point_2 p, Point_2 q, Point_2 r) const
    {
        return ...;
    }
};
```

# Filtered predicates : generic implementation

```
template <class EP, class AP, class C2E, class C2A>
class Filtered_predicate
{
    AP    approx_predicate;    C2A    c2a;
    EP    exact_predicate;    C2E    c2e;

    typedef EP::result_type    result_type;

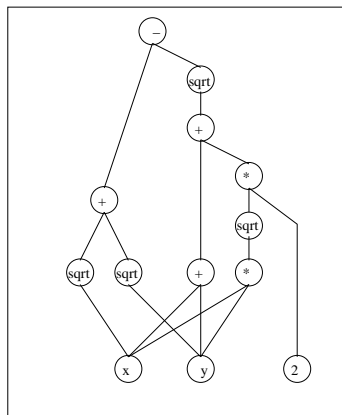
    template <class A1, class A2>
    result_type
    operator()(A1 a1, A2 a2) const
    {
        try {
            return approx_predicate(c2a(a1), c2a(a2));
        } catch (Interval::unsafe_comparison) {
            return exact_predicate(c2e(a1), c2e(a2));
        }
    }
};
```

Something similar is done for constructions (harder)

# Filtered number types

Directed Acyclic Graph (DAG) of operations in memory. Ex:

$$\sqrt{x} + \sqrt{y} - \sqrt{x + y + 2\sqrt{xy}}$$



# Filtered predicates: comparisons

Computation time of a 3D Delaunay triangulation.

	R5	E	M	B	D
double	40.6	41.0	43.7	50.3	loops
MPF	3,063	2,777	3,195	3,472	214
Interval + MPF	137.2	133.6	144.6	165.1	15.8
semi static + Interval + MPF	51.8	61.0	59.1	93.1	8.9
almost static + semi static + Interval + MPF	44.4	55.0	52.0	87.2	8.0
Shewchuk's predicates	57.9	57.5	62.8	71.7	7.2
CORE Expr	570	3520	1355	9600	173
LEDA real	682	640	742	850	125
Lazy_exact_nt<MPF>	705	631	726	820	67

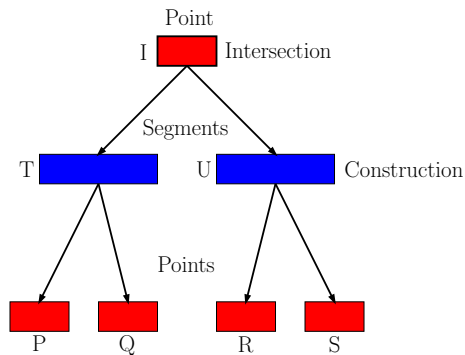
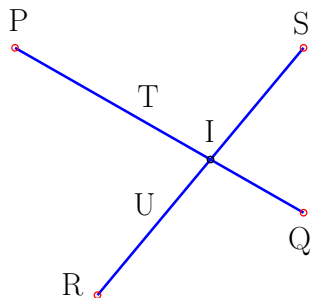
Important criterium: failure rate of filters.

User interface in CGAL: choice of different kernels.

# Filtered constructions

Additional difficulty: memory storage of geometric objects

Goal: regrouping computations, and less memory



# Filtered constructions : benchmarks

Generate 2000 random segments, intersect them, compute all orientations of consecutive intersection points.

Kernel	time g++ 4.1	memory
SC<Gmpq>	70	70
SC<Lazy_exact_nt<Gmpq>>	7.4	501
Lazy_kernel<SC<Gmpq>> (2)	3.6	64
Lazy_kernel<SC<Gmpq>>	2.8	64
SC<double>	0.72	8.3

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# Implementation of EGC

- WIP : Efficient treatment of curved objects of low degree
- WIP : Improvement of the treatment of geometric constructions
- WIP : Geometric rounding with guarantees
- ...

Questions ?