

The ASTRÉE Static Analyzer

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Motivation

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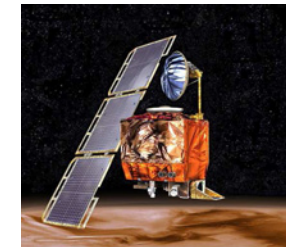
All Computer Scientists Have Experienced Bugs



Ariane 5.01 failure
(overflow)



Patriot failure
(float rounding)



Mars orbiter loss
(unit error)

It is preferable to verify that mission/safety-critical programs do not go wrong before running them.

Static Analysis by Abstract Interpretation

Static analysis: analyze the program at compile-time to verify a program runtime property (e.g. the absence of some categories of bugs)

Undecidability \longrightarrow

Abstract interpretation: effectively compute an abstraction/
sound approximation of the program semantics,

- which is **precise** enough to imply the desired property, and
- coarse enough to be **efficiently computable**.

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Abstract Interpretation, Reminder

Reference

[POPL '77] P. Cousot and R. Cousot. Abstract interpretation: a unified lattice model for static analysis of programs by construction or approximation of fixpoints. In 4th ACM POPL.

[Thesis '78] P. Cousot. Méthodes itératives de construction et d'approximation de points fixes d'opérateurs monotones sur un treillis, analyse sémantique de programmes. Thèse ès sci. math. Grenoble, march 1978.

[POPL '79] P. Cousot & R. Cousot. Systematic design of program analysis frameworks. In 6th ACM POPL.

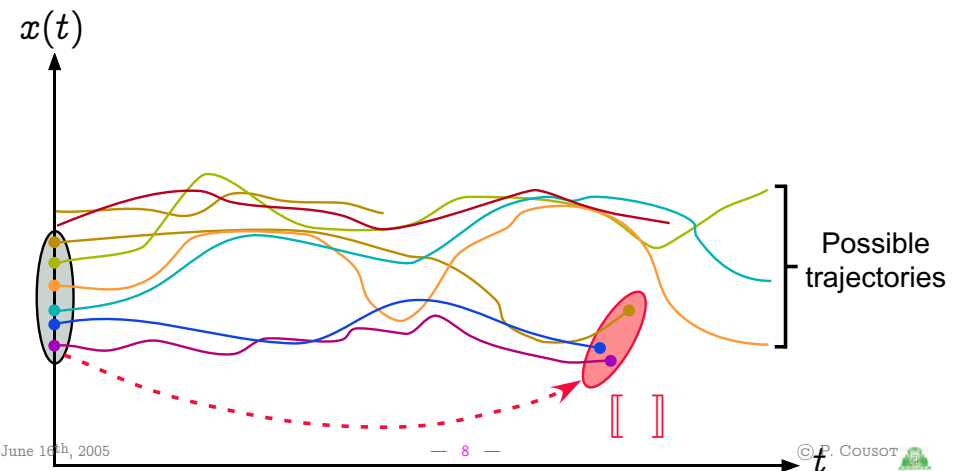
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Syntax of programs

X	variables $X \in \mathbb{X}$
T	types $T \in \mathbb{T}$
E	arithmetic expressions $E \in \mathbb{E}$
B	boolean expressions $B \in \mathbb{B}$
$D ::= T X;$	
$T X ; D'$	
$C ::= X = E;$	commands $C \in \mathbb{C}$
while $B C'$	
if $B C'$ else C''	
$\{ C_1 \dots C_n \}, (n \geq 0)$	
$P ::= D C$	program $P \in \mathbb{P}$

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Postcondition semantics



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States

Values of given type:

$$\mathcal{V}[T] : \text{values of type } T \in \mathbb{T}$$

$$\mathcal{V}[\text{int}] \stackrel{\text{def}}{=} \{z \in \mathbb{Z} \mid \text{min_int} \leq z \leq \text{max_int}\}$$

Program states $\Sigma[P]$ ¹:

$$\Sigma[D \ C] \stackrel{\text{def}}{=} \Sigma[D]$$

$$\Sigma[T \ X;] \stackrel{\text{def}}{=} \{X\} \mapsto \mathcal{V}[T]$$

$$\Sigma[T \ X; D] \stackrel{\text{def}}{=} (\{X\} \mapsto \mathcal{V}[T]) \cup \Sigma[D]$$

Concrete Reachability Semantics of Programs

$$S[X = E;]R \stackrel{\text{def}}{=} \{\rho[X \leftarrow \mathcal{E}[E]\rho] \mid \rho \in R \cap \text{dom}(E)\}$$

$$\rho[X \leftarrow v](X) \stackrel{\text{def}}{=} v, \quad \rho[X \leftarrow v](Y) \stackrel{\text{def}}{=} \rho(Y)$$

$$S[\text{if } B \ C']R \stackrel{\text{def}}{=} S[C'](\mathcal{B}[B]R) \cup \mathcal{B}[\neg B]R$$

$$\mathcal{B}[B]R \stackrel{\text{def}}{=} \{\rho \in R \cap \text{dom}(B) \mid B \text{ holds in } \rho\}$$

$$S[\text{if } B \ C' \ \text{else } C'']R \stackrel{\text{def}}{=} S[C'](\mathcal{B}[B]R) \cup S[C''](\mathcal{B}[\neg B]R)$$

$$S[\text{while } B \ C']R \stackrel{\text{def}}{=} \text{let } \mathcal{W} = \text{lfp}_{\emptyset} \lambda \mathcal{X}. R \cup S[C'](\mathcal{B}[B]\mathcal{X}) \\ \text{in } (\mathcal{B}[\neg B]\mathcal{W})$$

$$S[\{\}]R \stackrel{\text{def}}{=} R$$

$$S[\{C_1 \dots C_n\}]R \stackrel{\text{def}}{=} S[C_n] \circ \dots \circ S[C_1] \quad n > 0$$

$$S[D \ C]R \stackrel{\text{def}}{=} S[C](\Sigma[D]) \quad (\text{uninitialized variables})$$

~~Not computable (undecidability).~~

Abstract Semantic Domain of Programs

$$\langle \mathcal{D}^\sharp[P], \sqsubseteq, \perp, \sqcup \rangle$$

such that:

$$\langle \mathcal{D}[P], \sqsubseteq \rangle \xleftrightarrow[\alpha]{\gamma} \langle \mathcal{D}^\sharp[P], \sqsubseteq \rangle$$

i.e.

$$\forall X \in \mathcal{D}[P], Y \in \mathcal{D}^\sharp[P] : \alpha(X) \sqsubseteq Y \iff X \sqsubseteq \gamma(Y)$$

hence $\langle \mathcal{D}^\sharp[P], \sqsubseteq, \perp, \sqcup \rangle$ is a complete lattice such that $\perp = \alpha(\emptyset)$ and $\sqcup X = \alpha(\cup \gamma(X))$

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Concrete Semantic Domain of Programs

Concrete semantic domain for reachability properties:

$$\mathcal{D}[P] \stackrel{\text{def}}{=} \wp(\Sigma[P]) \quad \text{sets of states}$$

i.e. program properties where \sqsubseteq is implication, \emptyset is false, \sqcup is disjunction.

¹ States $\rho \in \Sigma[P]$ of a program P map program variables X to their values $\rho(X)$

Example 1 of Abstraction

Traces: set of finite or infinite maximal sequences of states for the operational transition semantics

α **Strongest liberal postcondition:** final states s reachable from a given precondition P

$$\alpha(X) = \lambda P. \{s \mid \exists \sigma_0 \sigma_1 \dots \sigma_n \in X : \sigma_0 \in P \wedge s = \sigma_n\}$$

We have (Σ : set of states, \sqsubseteq pointwise):

$$\langle \wp(\Sigma^\infty), \subseteq \rangle \xleftarrow[\alpha]{\gamma} \langle \wp(\Sigma) \xrightarrow{U} \wp(\Sigma), \sqsubseteq \rangle$$

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Example 2 of Abstraction

Traces: set of finite or infinite maximal sequences of states for the operational transition semantics

α_1 **Set of reachable states:** set of states appearing at least once along one of these traces (global invariant)

$$\alpha_1(X) = \{\sigma_i \mid \sigma \in X \wedge 0 \leq i < |\sigma|\}$$

α_2 **Partitionned set of reachable states:** project along each control point (local invariant)

$$\alpha_2(\{\langle c_i, \rho_i \rangle \mid i \in \Delta\}) = \lambda c. \{\rho_i \mid i \in \Delta \wedge c = c_i\}$$

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α_3 **Partitionned cartesian set of reachable states:** project along each program variable (relationships between variables are now lost)

$$\alpha_3(\lambda c. \{\rho_i \mid i \in \Delta_c\}) = \lambda c. \lambda X. \{\rho_i(x) \mid i \in \Delta_c\}$$

α_4 **Partitionned cartesian interval of reachable states:** take min and max of the values of the variables²

$$\alpha_4(\lambda c. \lambda X. \{v_i \mid i \in \Delta_{c,X}\}) = \lambda c. \lambda X. \langle \min\{v_i \mid i \in \Delta_{c,X}\}, \max\{v_i \mid i \in \Delta_{c,X}\} \rangle$$

$\alpha_1, \alpha_2, \alpha_3$ and α_4 , whence $\alpha_4 \circ \alpha_3 \circ \alpha_2 \circ \alpha_1$ are upper-adjoints of Galois connections

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Example 3: Reduced Product of Abstract Domains

To combine abstractions

$$\langle \mathcal{D}, \subseteq \rangle \xleftarrow[\alpha_1]{\gamma_1} \langle \mathcal{D}_1^\#, \sqsubseteq_1 \rangle \text{ and } \langle \mathcal{D}, \subseteq \rangle \xleftarrow[\alpha_2]{\gamma_2} \langle \mathcal{D}_2^\#, \sqsubseteq_2 \rangle$$

the **reduced product** is

$$\alpha(X) \stackrel{\text{def}}{=} \sqcap \{\langle x, y \rangle \mid X \subseteq \gamma_1(x) \wedge X \subseteq \gamma_2(y)\}$$

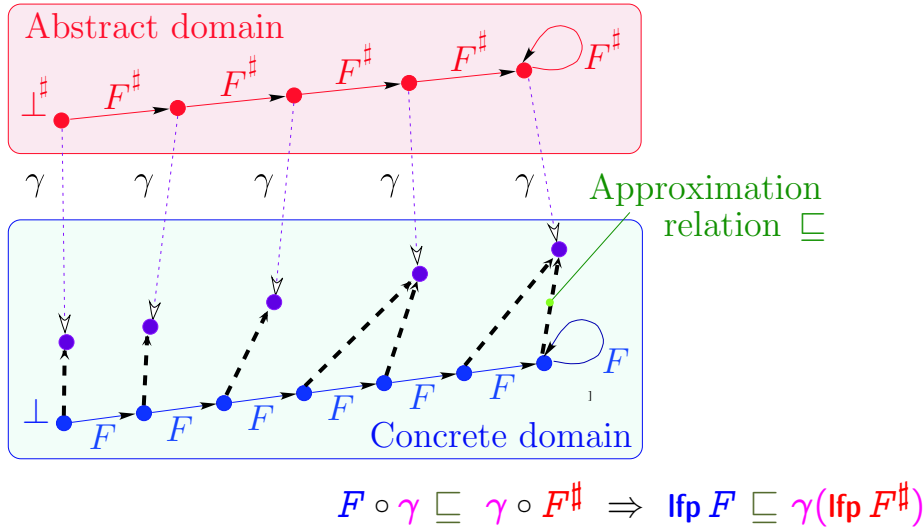
such that $\sqsubseteq \stackrel{\text{def}}{=} \sqsubseteq_1 \times \sqsubseteq_2$ and

$$\langle \mathcal{D}, \subseteq \rangle \xleftarrow[\alpha]{\gamma_1 \times \gamma_2} \langle \alpha(\mathcal{D}), \sqsubseteq \rangle$$

Example: $x \in [1, 9] \wedge x \bmod 2 = 0$ reduces to $x \in [2, 8] \wedge x \bmod 2 = 0$

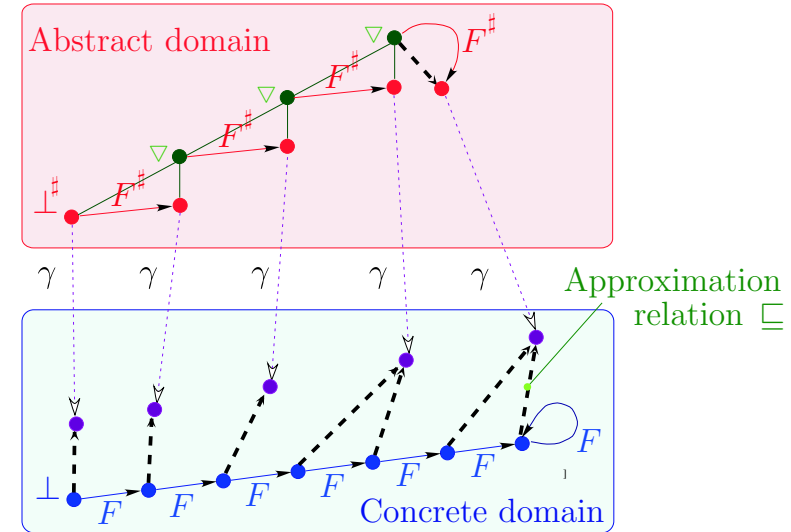
² assuming these values to be totally ordered.

Approximate Fixpoint Abstraction



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Convergence Acceleration with Widening



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Abstract Reachability Semantics of Programs

$$\begin{aligned}
 S^\# \llbracket X = E; \rrbracket R &\stackrel{\text{def}}{=} \alpha(\{\rho[X \leftarrow \mathcal{E}[E]\rho] \mid \rho \in \gamma(R) \cap \text{dom}(E)\}) \\
 S^\# \llbracket \text{if } B \ C' \rrbracket R &\stackrel{\text{def}}{=} S^\# \llbracket C' \rrbracket (\mathcal{B}^\# \llbracket B \rrbracket R) \sqcup \mathcal{B}^\# \llbracket \neg B \rrbracket R \\
 \mathcal{B}^\# \llbracket B \rrbracket R &\stackrel{\text{def}}{=} \alpha(\{\rho \in \gamma(R) \cap \text{dom}(B) \mid B \text{ holds in } \rho\}) \\
 S^\# \llbracket \text{if } B \ C' \text{ else } C'' \rrbracket R &\stackrel{\text{def}}{=} S^\# \llbracket C' \rrbracket (\mathcal{B}^\# \llbracket B \rrbracket R) \sqcup S^\# \llbracket C'' \rrbracket (\mathcal{B}^\# \llbracket \neg B \rrbracket R) \\
 S^\# \llbracket \text{while } B \ C' \rrbracket R &\stackrel{\text{def}}{=} \text{let } \mathcal{W} = \text{lfp}_\perp \lambda \mathcal{X}. R \sqcup S^\# \llbracket C' \rrbracket (\mathcal{B}^\# \llbracket B \rrbracket \mathcal{X}) \\
 &\quad \text{in } (\mathcal{B}^\# \llbracket \neg B \rrbracket \mathcal{W}) \\
 S^\# \llbracket \{\} \rrbracket R &\stackrel{\text{def}}{=} R \\
 S^\# \llbracket \{C_1 \dots C_n\} \rrbracket R &\stackrel{\text{def}}{=} S^\# \llbracket C_n \rrbracket \circ \dots \circ S^\# \llbracket C_1 \rrbracket \quad n > 0 \\
 S^\# \llbracket D \ C \rrbracket R &\stackrel{\text{def}}{=} S^\# \llbracket C \rrbracket (\top) \quad (\text{uninitialized variables})
 \end{aligned}$$

Abstract Semantics with Convergence Acceleration³

$$\begin{aligned}
 S^\# \llbracket X = E; \rrbracket R &\stackrel{\text{def}}{=} \alpha(\{\rho[X \leftarrow \mathcal{E}[E]\rho] \mid \rho \in \gamma(R) \cap \text{dom}(E)\}) \\
 S^\# \llbracket \text{if } B \ C' \rrbracket R &\stackrel{\text{def}}{=} S^\# \llbracket C' \rrbracket (\mathcal{B}^\# \llbracket B \rrbracket R) \sqcup \mathcal{B}^\# \llbracket \neg B \rrbracket R \\
 \mathcal{B}^\# \llbracket B \rrbracket R &\stackrel{\text{def}}{=} \alpha(\{\rho \in \gamma(R) \cap \text{dom}(B) \mid B \text{ holds in } \rho\}) \\
 S^\# \llbracket \text{if } B \ C' \text{ else } C'' \rrbracket R &\stackrel{\text{def}}{=} S^\# \llbracket C' \rrbracket (\mathcal{B}^\# \llbracket B \rrbracket R) \sqcup S^\# \llbracket C'' \rrbracket (\mathcal{B}^\# \llbracket \neg B \rrbracket R) \\
 S^\# \llbracket \text{while } B \ C' \rrbracket R &\stackrel{\text{def}}{=} \text{let } \mathcal{F}^\# = \lambda \mathcal{X}. \text{let } \mathcal{Y} = R \sqcup S^\# \llbracket C' \rrbracket (\mathcal{B}^\# \llbracket B \rrbracket \mathcal{X}) \\
 &\quad \text{in if } \mathcal{Y} \sqsubseteq \mathcal{X} \text{ then } \mathcal{X} \text{ else } \mathcal{X} \nabla \mathcal{Y} \\
 &\quad \text{and } \mathcal{W} = \text{lfp}_\perp \mathcal{F}^\# \quad \text{in } (\mathcal{B}^\# \llbracket \neg B \rrbracket \mathcal{W}) \\
 S^\# \llbracket \{\} \rrbracket R &\stackrel{\text{def}}{=} R \\
 S^\# \llbracket \{C_1 \dots C_n\} \rrbracket R &\stackrel{\text{def}}{=} S^\# \llbracket C_n \rrbracket \circ \dots \circ S^\# \llbracket C_1 \rrbracket \quad n > 0 \\
 S^\# \llbracket D \ C \rrbracket R &\stackrel{\text{def}}{=} S^\# \llbracket C \rrbracket (\top) \quad (\text{uninitialized variables})
 \end{aligned}$$

³ Note: $\mathcal{F}^\#$ not monotonic!

Applications of Abstract Interpretation

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Applications of Abstract Interpretation

- **Static Program Analysis** [POPL '77], [POPL '78], [POPL '79] including **Dataflow Analysis** [POPL '79], [POPL '00], **Set-based Analysis** [FPCA '95], **Predicate Abstraction** [Manna's festschrift '03], ...
- **Syntax Analysis** [TCS 290(1) 2002]
- **Hierarchies of Semantics (including Proofs)** [POPL '92], [TCS 277(1–2) 2002]
- **Typing & Type Inference** [POPL '97]

Applications of Abstract Interpretation (Cont'd)

- **(Abstract) Model Checking** [POPL '00]
- **Program Transformation** [POPL '02]
- **Software Watermarking** [POPL '04]
- **Bisimulations** [RT-ESOP '04]

All these techniques involve **sound approximations** that can be formalized by **abstract interpretation**

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A Practical Application of Abstract Interpretation to the ASTRÉE Static Analyzer

Reference

- [1] <http://www.astree.ens.fr/>

Programs analysed by ASTRÉE

- **Application Domain**: large safety critical embedded real-time synchronous software for non-linear control of very complex control/command systems.
- **C programs**:
 - with
 - basic numeric datatypes, structures and arrays
 - pointers (including on functions),
 - floating point computations
 - tests, loops and function calls
 - limited branching (forward goto, break, continue)

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- without
 - union
 - dynamic memory allocation
 - recursive function calls
 - backward branching
 - conflicting side effects
 - C libraries, system calls (parallelism)

Concrete Operational Semantics

- International **norm of C** (ISO/IEC 9899:1999)
- *restricted by implementation-specific behaviors* depending upon the machine and compiler (e.g. representation and size of integers, IEEE 754-1985 norm for floats and doubles)
- *restricted by user-defined programming guidelines* (such as no modular arithmetic for signed integers, even though this might be the hardware choice)
- *restricted by program specific user requirements* (e.g. assert, execution stops on first runtime error⁴)

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Abstract Semantics

- **Reachable states** for the concrete trace operational semantics
- **Volatile environment** is specified by a *trusted* configuration file.

Requirements:

- **Soundness**: absolutely essential
- **Precision**: few or no false alarm⁵ (full certification)
- **Efficiency**: rapid analyses and fixes during development

⁴ semantics of C unclear after an error, equivalent if no alarm

⁵ Potential runtime error signaled by the analyzer due to overapproximation but impossible in any actual program run.

Implicit Specification: Absence of Runtime Errors

- No violation of the **norm of C** (e.g. array index out of bounds, division by zero)
- **No implementation-specific undefined behaviors** (e.g. maximum short integer is 32767, NaN)
- No violation of the **programming guidelines** (e.g. static variables cannot be assumed to be initialized to 0)
- No violation of the **programmer assertions** (must all be statically verified).

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Example application

- **Primary flight control software** of the Airbus A340 family/A380 fly-by-wire system



- C program, automatically generated from a proprietary high-level specification (à la Simulink/SCADE)
- A340 family: 132,000 lines, **75,000 LOCs** after preprocessing, **10,000 global variables**, over **21,000** after expansion of small arrays
- A380: $\times 3$

The Class of Considered Periodic Synchronous Programs

```
declare volatile input, state and output variables;  
initialize state and output variables;
```

```
loop forever
```

- read volatile input variables,
- compute output and state variables,
- write to output variables;

```
__ASTREE_wait_for_clock ();
```

```
end loop
```

Task scheduling is static:

- **Requirements:** the only interrupts are clock ticks;
- **Execution time of loop body less than a clock tick** [EMSOFT '01].

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Challenging aspects

- **Size:** > 100 kLOC, $> 10\,000$ variables
- **Floating point computations**
including interconnected networks of filters, non linear control with feedback, interpolations...
- **Interdependencies among variables:**
 - Stability of computations should be established
 - Complex relations should be inferred among numerical and boolean data
 - Very long data paths from input to outputs

Characteristics of the ASTRÉE Analyzer

Static: compile time analysis (\neq run time analysis **Rational Purify**, **Parasoft Insure++**)

Program Analyzer: analyzes programs not micromodels of programs (\neq **PROMELA** in **SPIN** or **Alloy** in the **Alloy Analyzer**)

Automatic: no end-user intervention needed (\neq **ESC Java**, **ESC Java 2**)

Sound: covers the whole state space (\neq **MAGIC**, **CBMC**) so never omit potential errors (\neq **UNO**, **CMC** from **coverity.com**) or sort most probable ones (\neq **Splint**)

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Characteristics of the ASTRÉE Analyzer (Cont'd)

Multiabstraction: uses many numerical/symbolic abstract domains (\neq symbolic constraints in **Bane** or the canonical abstraction of **TVLA**)

Infinitary: all abstractions use infinite abstract domains with widening/narrowing (\neq model checking based analyzers such as **VeriSoft**, **Bandera**, **Java PathFinder**)

Efficient: always terminate (\neq counterexample-driven automatic abstraction refinement **BLAST**, **SLAM**)

Characteristics of the ASTRÉE Analyzer (Cont'd)

Specializable: can easily incorporate new abstractions (and reduction with already existing abstract domains) (\neq general-purpose analyzers **PolySpace Verifier**)

Domain-Aware: knows about control/command (e.g. digital filters) (as opposed to specialization to a mere programming style in **C Global Surveyor**)

Parametric: the precision/cost can be tailored to user needs by options and directives in the code

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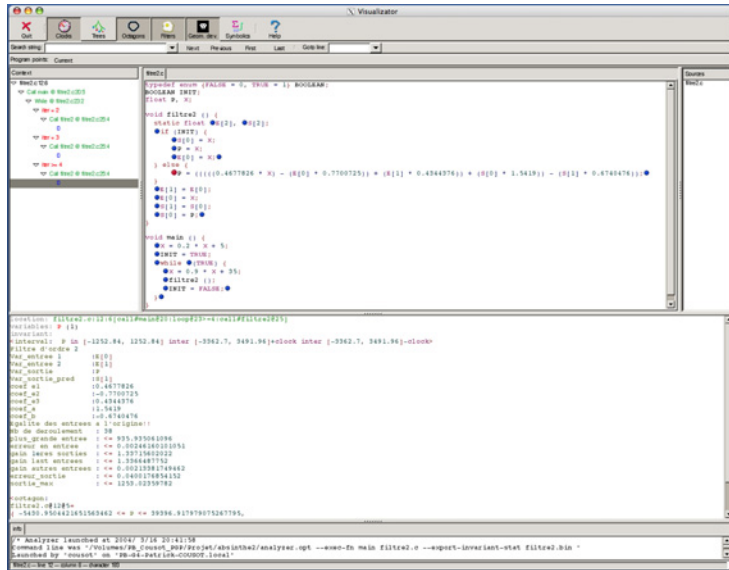
Characteristics of the ASTRÉE Analyzer (Cont'd)

Automatic Parametrization: the generation of parametric directives in the code can be programmed (to be specialized for a specific application domain)

Modular: an analyzer instance is built by selection of **O-CAML** modules from a collection each implementing an abstract domain

Precise: very few or no false alarm when adapted to an application domain \rightarrow it is a **VERIFIER!**

Example of Analysis Session



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(Airbus A380 Primary Flight Control Software)

- 350,000 lines
- 0 alarms (Nov. 2004),
7h⁶ on 2.8 GHz PC,
1 Gigabyte
- A world grand première!

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Benchmarks (Airbus A340 Primary Flight Control Software)

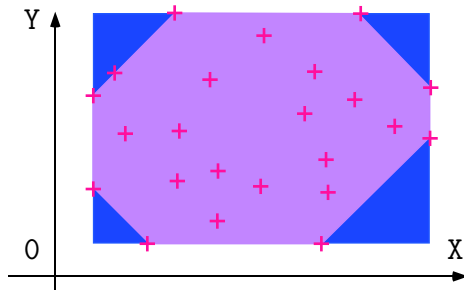
- 132,000 lines, 75,000 LOCs after preprocessing
- Comparative results (commercial software):
4,200 (false?) alarms,
3.5 days;
- Our results:
0 alarms,
40mn on 2.8 GHz PC,
300 Megabytes
- A world première!

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Examples of Abstractions

⁶ We are still in a phase where we favour precision rather than computation costs, and this should go down. For example, the A340 analysis went up to 5 h, before being reduced by requiring less precision while still getting no false alarm.

General-Purpose Abstract Domains: Intervals and Octagons



Intervals:

$$\begin{cases} 1 \leq x \leq 9 \\ 1 \leq y \leq 20 \end{cases}$$

Octagons [10]:

$$\begin{cases} 1 \leq x \leq 9 \\ x + y \leq 77 \\ 1 \leq y \leq 20 \\ x - y \leq 04 \end{cases}$$

Difficulties: many global variables, arrays (smashed or not), IEEE 754 floating-point arithmetic (in program and analyzer) [POPL'77, 10, 11]

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Floating-Point Computations

```
/* float-error.c */
int main () {
    float x, y, z, r;
    x = 1.000000019e+38;
    y = x + 1.0e21;
    z = x - 1.0e21;
    r = y - z;
    printf("%f\n", r);
}
% gcc float-error.c
% ./a.out
0.000000
```

```
/* double-error.c */
int main () {
    double x; float y, z, r;
    /* x = ldexp(1.,50)+ldexp(1.,26); */
    x = 1125899973951487.0;
    y = x + 1;
    z = x - 1;
    r = y - z;
    printf("%f\n", r);
}
% gcc double-error.c
% ./a.out
0.000000
```

$$(x + a) - (x - a) \neq 2a$$

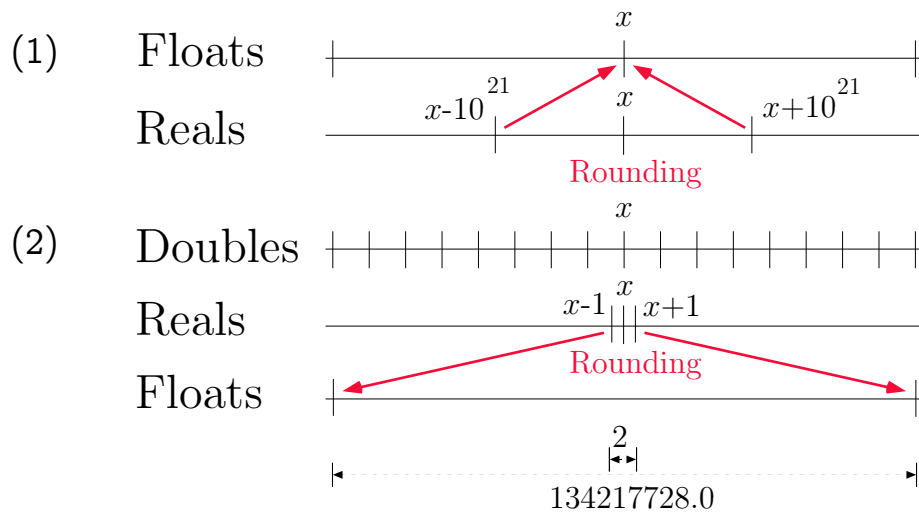
Floating-Point Computations

```
/* float-error.c */
int main () {
    float x, y, z, r;
    x = 1.000000019e+38;
    y = x + 1.0e21;
    z = x - 1.0e21;
    r = y - z;
    printf("%f\n", r);
}
% gcc float-error.c
% ./a.out
0.000000
```

```
/* double-error.c */
int main () {
    double x; float y, z, r;
    /* x = ldexp(1.,50)+ldexp(1.,26); */
    x = 1125899973951488.0;
    y = x + 1;
    z = x - 1;
    r = y - z;
    printf("%f\n", r);
}
% gcc double-error.c
% ./a.out
134217728.000000
```

$$(x + a) - (x - a) \neq 2a$$

Explanation of the huge rounding error



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Floating-point linearization [11, 12]

- Approximate arbitrary expressions in the form $[a_0, b_0] + \sum_k ([a_k, b_k] \times V_k)$
- Example:
 $Z = X - (0.25 * X)$ is linearized as
 $z = ([0.749 \dots, 0.750 \dots] \times X) + (2.35 \dots 10^{-38} \times [-1, 1])$
- Allows **simplification** even in the interval domain
 if $X \in [-1, 1]$, we get $|Z| \leq 0.750 \dots$ instead of $|Z| \leq 1.25 \dots$
- Allows using a **relational abstract domain** (octagons)
- Example of good compromise between cost and precision

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Symbolic abstract domain [11, 12]

- **Interval analysis**: if $x \in [a, b]$ and $y \in [c, d]$ then $x - y \in [a - d, b - c]$ so if $x \in [0, 100]$ then $x - x \in [-100, 100]$!!!
- The **symbolic abstract domain** propagates the symbolic values of variables and performs simplifications;
- Must maintain the **maximal possible rounding error** for float computations (overestimated with intervals);

```
% cat -n x-x.c
1 void main () { int X, Y;
2   __ASTREE_known_fact(((0 <= X) && (X <= 100)));
3   Y = (X - X);
4   __ASTREE_log_vars((Y));
5 }

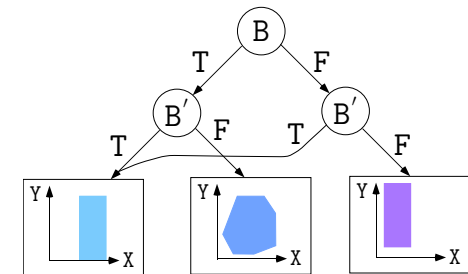
astree -exec-fn main -no-relational x-x.c      astree -exec-fn main x-x.c
Call main@x-x.c:1:5-x-x.c:1:9:                Call main@x-x.c:1:5-x-x.c:1:9:
<interval: Y in [-100, 100]>                  <interval: Y in {0}> <symbolic: Y = (X -i X)>
```

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Boolean Relations for Boolean Control

- **Code Sample:**

```
/* boolean.c */
typedef enum {F=0,T=1} BOOL;
BOOL B;
void main () {
  unsigned int X, Y;
  while (1) {
    ...
    B = (X == 0);
    ...
    if (!B) {
      Y = 1 / X;
    }
    ...
  }
}
```



The boolean relation abstract domain is parameterized by the height of the decision tree (an analyzer option) and the abstract domain at the leaves

Control Partitioning for Case Analysis

– Code Sample:

```

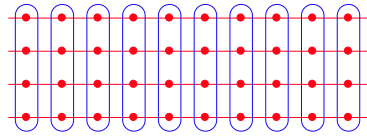
/* trace_partitioning.c */
void main() {
  float t[5] = {-10.0, -10.0, 0.0, 10.0, 10.0};
  float c[4] = {0.0, 2.0, 2.0, 0.0};
  float d[4] = {-20.0, -20.0, 0.0, 20.0};
  float x, r;
  int i = 0;

  ... found invariant -100 ≤ x ≤ 100 ...

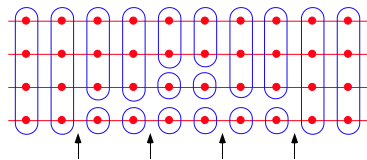
  while ((i < 3) && (x >= t[i+1])) {
    i = i + 1;
  }
  r = (x - t[i]) * c[i] + d[i];
}

```

Control point partitioning:



Trace partitioning:



Delaying abstract unions in tests and loops is more precise for non-distributive abstract domains (and much less expensive than disjunctive completion).

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Filter Example [7]

```

typedef enum {FALSE = 0, TRUE = 1} BOOLEAN;
BOOLEAN INIT; float P, X;

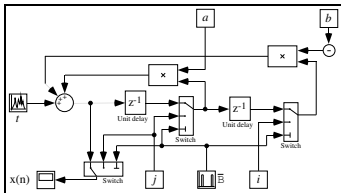
void filter () {
  static float E[2], S[2];
  if (INIT) { S[0] = X; P = X; E[0] = X; }
  else { P = (((((0.5 * X) - (E[0] * 0.7)) + (E[1] * 0.4))
              + (S[0] * 1.5)) - (S[1] * 0.7)); }
  E[1] = E[0]; E[0] = X; S[1] = S[0]; S[0] = P;
  /* S[0], S[1] in [-1327.02698354, 1327.02698354] */
}

void main () { X = 0.2 * X + 5; INIT = TRUE;
  while (1) {
    X = 0.9 * X + 35; /* simulated filter input */
    filter (); INIT = FALSE; }
}

```

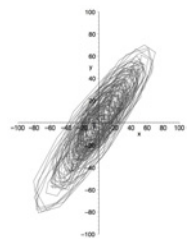
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2^d Order Digital Filter:

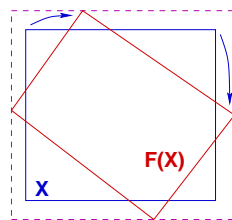


Ellipsoid Abstract Domain for Filters

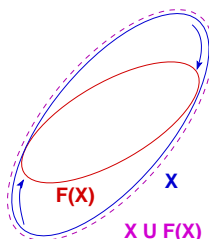
- Computes $X_n = \begin{cases} \alpha X_{n-1} + \beta X_{n-2} + Y_n \\ I_n \end{cases}$
- The concrete computation is bounded, which must be proved in the abstract.
- There is no stable interval or octagon.
- The simplest stable surface is an ellipsoid.



execution trace



$X \cup F(X)$
unstable interval



$X \cup F(X)$
stable ellipsoid

Arithmetic-geometric progressions⁷ [8]

– Abstract domain: $(\mathbb{R}^+)^5$

– Concretization:

$$\gamma \in (\mathbb{R}^+)^5 \mapsto \wp(\mathbb{N} \mapsto \mathbb{R})$$

$$\gamma(M, a, b, a', b') =$$

$$\{f \mid \forall k \in \mathbb{N} : |f(k)| \leq (\lambda x \cdot ax + b \circ (\lambda x \cdot a'x + b')^k) (M)\}$$

i.e. any function bounded by the arithmetic-geometric progression.

⁷ here in \mathbb{R}

Arithmetic-Geometric Progressions (Example 1)

```
% cat count.c
typedef enum {FALSE = 0, TRUE = 1} BOOLEAN;
volatile BOOLEAN I; int R; BOOLEAN T;
void main() {
  R = 0;
  while (TRUE) {
    __ASTREE_log_vars((R));
    if (I) { R = R + 1; } ← potential overflow!
    else { R = 0; }
    T = (R >= 100);
    __ASTREE_wait_for_clock();
  }
}

% cat count.config
__ASTREE_volatile_input((I [0,1]));
__ASTREE_max_clock((3600000));
% astree -exec-fn main -config-sem count.config count.c|grep '|R|'
|R| <= 0. + clock *1. <= 3600001.
```

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Arithmetic-geometric progressions (Example 2)

```
% cat retro.c
typedef enum {FALSE=0, TRUE=1} BOOL;
BOOL FIRST;
volatile BOOL SWITCH;
volatile float E;
float P, X, A, B;

void dev( )
{ X=E;
  if (FIRST) { P = X; }
  else
    { P = (P - (((2.0 * P) - A) - B)
      * 4.491048e-03)); };
  B = A;
  if (SWITCH) {A = P;}
  else {A = X;}
}

void main()
{ FIRST = TRUE;
  while (TRUE) {
    dev();
    FIRST = FALSE;
    __ASTREE_wait_for_clock();
  }
}

% cat retro.config
__ASTREE_volatile_input((E [-15.0, 15.0]));
__ASTREE_volatile_input((SWITCH [0,1]));
__ASTREE_max_clock((3600000));
|P| <= (15. + 5.87747175411e-39
/ 1.19209290217e-07) * (1
+ 1.19209290217e-07)^clock
- 5.87747175411e-39 /
1.19209290217e-07 <=
23.0393526881
```

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(Automatic) Parameterization

- All abstract domains of ASTRÉE are **parameterized**, e.g.
 - variable packing for octagones and decision trees,
 - partition/merge program points,
 - loop unrollings,
 - thresholds in widenings, ...;
- End-users can either **parameterize by hand** (analyzer options, directives in the code), or
- choose the **automatic parameterization** (default options, directives for pattern-matched predefined program schemata).

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The main loop invariant for the A340

A textual file over 4.5 Mb with

- **6,900** boolean interval assertions ($x \in [0; 1]$)
 - **9,600** interval assertions ($x \in [a; b]$)
 - **25,400** clock assertions ($x + \text{clk} \in [a; b] \wedge x - \text{clk} \in [a; b]$)
 - **19,100** additive octagonal assertions ($a \leq x + y \leq b$)
 - **19,200** subtractive octagonal assertions ($a \leq x - y \leq b$)
 - **100** decision trees
 - **60** ellipse invariants, etc ...
- involving over **16,000** floating point constants (only **550** appearing in the program text) \times **75,000** LOCs.

Possible origins of imprecision and how to fix it

- In case of false alarm, the imprecision can come from:
- **Abstract transformers** (not best possible) → improve algorithm;
 - **Automatized parametrization** (e.g. variable packing) → improve pattern-matched program schemata;
 - **Iteration strategy** for fixpoints → fix widening ⁸;
 - **Inexpressivity** i.e. indispensable local inductive invariant are inexpressible in the abstract → add a **new abstract domain** to the reduced product (e.g. filters).

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Conclusion

⁸ This can be very hard since at the limit only a precise infinite iteration might be able to compute the proper abstract invariant. In that case, it might be better to design a more refined abstract domain.

Conclusion

- Most applications of abstract interpretation **tolerate a small rate** (typically 5 to 15%) **of false alarms**:
 - Program transformation → do not optimize,
 - Typing → reject some correct programs, etc,
 - WCET analysis → overestimate;
- Some applications **require no false alarm** at all:
 - **Program verification**.
- **Theoretically possible** [SARA '00], **practically feasible** [PLDI '03]

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The Future & Grand Challenges

Forthcoming (1 year):

- More general memory model (union)

Future (5 years):

- **Asynchronous concurrency** (for less critical software)
- **Functional properties** (reactivity)
- **Industrialization**

Grand challenge:

- **Verification from specifications to machine code** (verifying compiler)
- **Verification of systems** (quasi-synchrony, distribution)

THE END, THANK YOU

More references at URL www.di.ens.fr/~cousot
www.astree.ens.fr.

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