The University of Texas at Austin CS 439 Principles of Computer Systems: Spring 2013

Midterm Exam I

- This exam is **120 minutes**. Stop writing when "time" is called. *You must turn in your exam; we will not collect it*. Do not get up or pack up between 110 and 120 minutes. The instructor will leave the room 123 minutes after the exam begins and will not accept exams outside the room.
- There are **21** problems in this booklet. Many can be answered quickly. Some may be harder than others, and some earn more points than others. You may want to skim all questions before starting.
- This exam is closed book and notes. You may not use electronics: phones, calculators, laptops, etc. You may refer to ONE two-sided 8.5x11" sheet with 10 point or larger Times New Roman font, 1 inch or larger margins, and a maximum of 55 lines per side. Please leave your UT IDs out.
- If you find a question unclear or ambiguous, be sure to write any assumptions you make.
- Follow the instructions: if they ask you to justify something, explain your reasoning and any important assumptions. Write brief, precise answers. Rambling brain dumps will not work and will waste time. Think before you start writing so that you can answer crisply. Be neat. If we can't understand your answer, we can't give you credit!
- There is no credit for leaving questions blank. However, to discourage unfocused responses, we will be grading the clarity of your answer. Moreover, some questions impose sentence limits.
- Don't linger. If you know the answer, give it, and move on.
- Write your name and UT EID on this cover sheet and on the bottom of every page of the exam.
- Circle your TA's name and section meeting day below.

Do not write in the boxes below.

I (xx/27)	II (xx/30	III (xx/23)	IV (xx/20)	Total (xx/100)

TA (circle one):

Sebastian (Tues.)

Parth (Wed.)

Navid (Thurs.)

Name: Solutions

UT EID:

I Processes and so forth (27 points total)

1. [6 points] Recall that a process can be in a number of states: NEW, READY, RUNNING, WAITING, or TERMINATED. When a process is running, it is in the state RUNNING.

Immediately after a process is preempted, which state is it in? You do not need to justify your answer.

READY. Preemption means: "this process does not get to run for the time being", not "this process is waiting on some resource." In other words, "waiting" doesn't mean "waiting for the CPU" but rather "waiting for some resources."

Now, assume that a process is in the WAITING state.

Is this process guaranteed to transition to the READY state eventually? Explain either way, but be brief (no more than two sentences).

It is not guaranteed. The process might starve, or the event that it is waiting on might never happen.

2. [4 points] Circle True or False for each item below:

True / False User-space threads can be preemptively scheduled.

True. As noted in lecture, user-space threads can indeed be scheduled preemptively. Instead of using a hardware timer interrupt, for scheduling, the user-level threading package registers for periodic notification by a timer.

True / False If a priority inversion has happened, then the system has experienced deadlock.

False. They're separate problems.

True / False To avoid deadlock, one must avoid all four of its preconditions.

False. Negating one of the preconditions suffices

True / False Mike Dahlin's commandments do not mention deadlock.

True. The MikeD commandments are all about "safety first." Deadlock is a liveness problem.

3. [3 points] A file descriptor is an example of an abstraction that is ...

Circle the BEST answer:

- A ... provided by modern disks
- ${\boldsymbol{B}}\ \ldots$ provided by the standard C library
- \mathbf{C} ... provided by the hardware's privileged mode
- \mathbf{D} ... provided by Unix
- \mathbf{E} ... provided by the linker

D

Name: Solutions

4. [3 points] Recall that when the shell creates a new process, it first calls fork(), to create a copy of itself, and then, in the child, the shell calls exec(). This call to exec() replaces what state in the process?

Circle ALL that apply:

- A the file descriptor state
- B process memory
- C device drivers
- **D** the kernel
- E the PID

B, only

5. [5 points] Many operating systems give the appearance of executing many applications at once, even on single-CPU machines. Giving this appearance requires the operating system to perform many *context switches*.

What is a context switch? (Answer briefly.) What steps does the operating system perform to execute a context switch? (Write the steps in a bulleted list of four or five brief bullets.)

A context switch changes which process currently has control of the CPU. In a context switch, the OS:

- Saves the state of the previously running process, stashing that state in the process's PCB.
- Restores the state of the previously running process, pulling that state from that process's PCB
- Sets the switched-to process running.

6. [3 points] Which of the following components is responsible for loading the initial value in the program counter (also known as the instruction pointer) for a user-level process before it starts running?

- A The boot loader (aka boot ROM)
- **B** The semaphore up() operation
- ${\bf C}~$ The loader
- **D** The linker
- E The compiler

С

7. [3 points] Consider the following command, executed at the command prompt (also known as the shell) on the UTCS Linux machines:

Name: Solutions

\$ man 2 write

What does the above command do? (Do not use more than one sentence for your answer.) Displays the manual pages for the write system call.

II Concurrency and synchronization (30 points total)

8. [4 points] A thread within a process has its own:

Circle ALL that apply:

A stack

- ${\bf B}$ main() function
- C registers
- **D** global variables
- E program code
- F heap

A, C

9. [3 points] Assume a four-CPU machine. Assume that the system provides a user-level threading package and no kernel-level threading.

How many CPUs can a single process use, if the process has four user-level threads? You do not need to justify your answer.

1

10. [6 points] Recall that the UTCS department requires that you follow the six commandments of thread programming.

Why does UTCS impose these commandments? Do not write more than one or two sentences.

Because in this programming model, the incorrect version of the code is much easier to write than the correct version, and the commandments help avoid common errors.

Name three of the commandments.

11. [4 points] Which of the following statements about semaphores is true?

Circle ALL that apply:

- A Semaphores were a key cause of the Therac-25's errors.
- **B** Semaphores are a program construct that we told you not to use in application code.
- C Semaphores are the chief vehicle for explaining deadlock in the Bryant & O'Halloran book
- D Semaphores are a way of abstracting network sockets.
- **E** Semaphores are a way of abstracting OS signals.
- **F** Semaphores atomically increment and decrement a count.

B, C, F.

12. [4 points] Let cv be a condition variable, and let mutex be a mutex. Consider the following pattern:

```
if (!predicate()) {
    wait(&mutex, &cv);
}
// it is an error if code gets to here with the predicate false
```

When is the above pattern correct? Do not write more than one or two sentences.

This pattern is never correct. wait() can wake at any time. We also ruled it out in this class, but even without that, the pattern is not correct, under common threading implementations.

13. [3 points] You decide that you want to implement a concurrency primitive, and you want to do it correctly.

You will need to consult the manuals for which system components?

Compiler, processor (for atomic instructions and memory model).

```
14. [6 points] Consider the following implementation of a spinlock:
```

```
struct Lock {
 int locked;
}
int exchange_value(int* ptr, int val) {
   int was;
   was = *ptr;
   *ptr = val;
   return was:
}
void acquire (Lock *lock) {
   pushcli();
                 /* this disable interrupts */
   while (1) {
   if (exchange_value(&lock->locked, 1) == 0)
        break;
   }
}
void release(Lock *lock){
    exchange_value(&lock->locked, 0);
   popcli(); /* this restores interrupts to the state they were in */
}
```

This implementation differs from the one that we saw in class. Specifically, the one that we saw in class implemented exchange_value() using an assembly instruction, xchg, that performs the exchange atomically.

This question asks whether the code above is correct. Assume that the machine provides sequential consistency. If the lines pushcli() and popcli() are confusing or distracting, then you can ignore them; they are there for completeness.

Is the code correct? If the code is correct, explain what invariant is maintained. If the code is not correct, give a problematic interleaving and explain why it is problematic.

The code is not correct. Assume lock is unlocked, so locked == 0. P1: gets into exchange_value(). Gets to the line "int was = *ptr". P2 gets to the same place. Both set their local variable was = 0. Both set *ptr = 1. Then both threads continue, which means there is no mutual exclusion in this case.

Some of you assumed that there was one CPU, but this assumption is not really reasonable in the context of spinlocks: the whole point to spinlocks is to provide mutual exclusion when there are multiple CPUs (if there is only one CPU, then disabling/enabling interrupts suffices for mutual exclusion).

Some of you thought that sequential consistency meant that the code was correct. But S.C. here just means that you didn't need to reason about out-of-order memory operations, not that memory operations from two different processors couldn't be interleaved.

One way to understand the interplay between S.C., multiple CPUs, spinlocks, and enabling/disabling interrupts is as follows:

Name: Solutions

- S.C. implies that the possible interleavings you could see in the multiple CPU case are those that you could see in the single CPU case, assuming arbitrary preemptions and scheduling in both cases.
- However, not all of these interleavings are ones we are happy about. In particular, we need to rule out some of them if we are to have a hope of writing correct concurrent code. (We need to rule out ones in which "things that should be atomic" don't actually happen atomically.)
- In the single CPU case, one way that we can rule out adverse interleavings is by disabling/enabling interrupts. This ensures that *not* all interleavings that are possible in the memory model actually take place. This in turn means that it's possible to implement a low-level lock correctly (which helps us implement mutexes, using that low-level lock).
- In the multiple CPU case, disabling/enabling interrupts is necessary (for several reasons), but it is not sufficient. It is not sufficient because the *other* CPU is executing. So to provide true mutual exclusion, we need something in addition to disabling/enabling interrupts. That something is a spinlock. In other words, in the multiple CPU case we implement the low-level lock using a spinlock.

Note that the question was testing a number of things: your understanding of the purpose of spinlocks, your comprehension of C, your grasp of concurrency and which difficulties of concurrency call for which primitives, the need for low-level atomic instructions, etc.

For this reason, we gave only a small number of points to answers that explicitly assumed one CPU. Answers of the form "because interrupts are disabled and because we have S.C., the code is correct" did not receive credit, since the answer was either assuming one CPU (in which case the answer shouldn't say "S.C.", since a single CPU is always sequentially consistent), or the answer is assuming multiple CPUs, in which case the code is not correct.

III Scheduling, readings, and lab (23 points total)

15. [4 points] These questions concern various scheduling disciplines.

Circle True or False for each item below.

True / False We showed in class how an implemented scheduler can achieve the optimal average waiting time (also known as response time).

False. The optimal one requires predicting the future and hence cannot be implemented. We showed in class how an implemented scheduler can *approximate* optimal, assuming the past predicts the future.

True / False FCFS (first come first served) optimizes throughput.

False. FCFS pays attention only to CPU utilization, so it may leave resources idle that another discipline would have engaged. Idle resources translates to lower throughput (there was work that could have been done that wasn't).

True / False FCFS (first come first served) optimizes CPU utilization.

True.

True / False Round-robin scheduling ensures no starvation.

True.

16. [3 points] In describing scheduling, Hailperin gives several examples of scheduling decisions that you, the reader, might need to make in real life.

Below, state one of these real-world examples.

17. [4 points] Describe the *symptoms* of one of the radiation injuries inflicted by the Therac-25 (that is, we are asking for more than "the patient ultimately died" or "massive radiation burns"). If you have not read the paper, please skip the question; we do not want to read creative writing here. If you have read the paper, feel free to supply graphic details from the paper.

Describe one of the injuries. Be brief; we will read only the first two sentences. Skip the question to receive half of a point.

18. [4 points] This question concerns your pair programming experience.Write your partner's name:

Describe the worst bug encountered by your team in Lab 2.

19. [5 points] This question is about the boot process in JOS. In lab 3, you were asked to use gdb to step through the process of booting. (Here, the word "process" has its non-technical meaning.) You would have stepped through boot/boot.S, then into bootmain() (in boot/main.c), and then readsect() (also in boot/main.c). In particular, the lab says, "Trace through the rest of readsect() and back out into bootmain(), and identify the begin and end of the for loop that reads the remaining sectors of the kernel from the disk."

How does the boot loader decide how many sectors it must read in order to fetch the entire kernel from disk? Where does it find this information?

20. [3 points] This is to gather feedback. Any answer, except a blank one, will get full credit.

Please state the topic or topics in this class that have been least clear to you.

Many students wrote JOS, spinlocks, implementation of concurrency abstractions.

Please state the topic or topics in this class that have been most clear to you.

Many students wrote "use of concurrency primitives" and the need for the guidelines and commandments: good! We're glad that was clear!

IV Multithreaded programming (20 points total)

21. [20 points] Your three-year old sibling, Kelly, has recently become obsessed with finding pennies. Kelly looks for them everywhere—on the sidewalk, in the parking lot, under the table at the restaurant. These pennies are very dirty! As the loving older sibling, you decide that you will clean them for Kelly using ordinary household liquids. Unfortunately, you don't know which household liquids will be the most effective. Your plan, then, is to use five different household liquids to clean five pennies and see which pennies are the cleanest. Your sibling will (obviously) provide the pennies, and, since you are at your parents' house, a parent will provide the liquids. Once the pennies are finished soaking (you learn they are finished by receiving a signal from an omniscient being), you will remove them and analyze the results. When you have finished your experiment—*which involves five pennies and five liquids*—return the pennies to the penny pile and the liquids to your parent. Kelly is very busy and not waiting for the pennies (so no need to notify Kelly!), but your parents, who are anxious to clean the kitchen, are waiting for you to finish.

In thinking about your plan, you realize that this is really a case of synchronization (you need resources!) and mutual exclusion (no putting away the liquids while you are still using them!), so you decide to model you, your family members, and the omniscient being as threads. Each of you is a thread. However, note that there can be multiple threads of the same type: multiple parents and multiple little siblings (each of whom acts like Kelly).

Each thread executes one of the functions below:

```
void big_sib(); // the function executed by the big sibling thread
void little_sibling() // the function executed by a little sibling thread
void parent(); // the function executed by a parent thread
void omniscient_being(); // the function executed by the omniscient being
```

and each of *those* functions invokes a corresponding method on a monitor, called Expt, defined on the next page. (You can imagine that each of the functions above invokes the corresponding monitor method once.)

Implement the Expt **monitor: write down the state variables, the synchronization objects, and implement the four methods.** Be certain to follow the 439 coding conventions. You may indicate activities other than synchronization and mutual exclusion using angle brackets (for example, <find penny> and <clean pennies>).

Before you get started, you may wish to follow the design approach outlined in class: write down the synchronization constraints (mutual exclusion, scheduling, etc), write down the shared state, etc. However, we will be grading only the implementation of Expt.

```
class Expt {
```

public: // Acquires (and releases!) the appropriate resources and conducts // the experiment. This method should also notify the omniscient // being when the experiment has begun. void BigSibStuff(); // Finds a penny and signals the big sibling void LittleSibStuff(); // Gathers five liquids, notifies the big sibling that the liquids // are ready, and then waits until the sibling is ready for the // liquids to be put away. void ParentStuff(); // This method rests until hearing that the experiments have begun. // It then watches the experiment and notifies the scientist (the // big sibling) when the results are ready void OmnsicientBeingStuff();

private:

// FILL THIS IN

};

- // Here and on the next page, give the implementations of
- // Expt::Expt() [this should initialize all of the shared state],
- // Expt::BigSibStuff(),
- // Expt::LittleSibStuff(),
- // Expt::ParentStuff(),
- // Expt::OmnsicientBeingStuff

```
Space for code and/or scratch paper
```

```
Data members:
    Mutex m;
    // we'll use only one cv (and broadcast). you could use more CVs and
    11
         signal. Note that multiple CVs is a performance
    11
         optimization; correctness is ensured by state variables and
    11
         checking predicates.
    Cond cv;
    int penniesGathered;
    int liquidsGathered;
    bool exptReady;
    bool exptDone;
    bool liquidsReturned;
Methods:
Expt::Expt() :
    penniesGathered(0),
    liquidsGathered(0),
    exptReady(false),
    exptDone(false),
    liquidsReturned(false)
ſ
    m.init();
    cv.init();
}
Expt::LittleSibStuff()
{
    M.acquire();
    while (penniesGathered < 5) {</pre>
        <gather penny>
        ++penniesGathered;
    }
    cv.broadcast(&m);
    M.release();
}
Expt::ParentStuff()
{
```

```
M.acquire();
    while (liquidsGathered < 5) {</pre>
        <gather liquid>
        ++liquidsGathered;
    }
    cv.broadcast(&m);
    while (!liquidsReturned)
        cv.wait(&m);
    M.release();
}
Expt::BigSibStuff()
{
    M.acquire();
    while (penniesGathered < 5 && liquidsGathered < 5) {</pre>
        cv.wait(&m);
    }
    <grab 5 pennies, grab 5 liquids>
    exptReady = true;
    cv.broadcast(&m);
    <start expt>
    while (!exptDone) {
        cv.wait(&m);
    }
    <return pennies to penny pile>
    <return liquids to parent>
    liquidsReturned = true;
    M.release();
}
Expt::OmniscientBeing()
{
    M.acquire();
    while (!exptReady) {
        cv.wait(&m);
    }
```

```
<watch expt>
exptDone = true;
cv.broadcast(&m);
M.release();
}
```

Space for code and/or scratch paper

End of Midterm