8 9 A. Three th: 10 11Hand: 12 13Treat 14 eight so 15 16Vtkbp 17 the inp 18 offset) 19"	blem #1 (our best guess) reads: sets the collimator/turntable position : sets a bunch of other parameters. Part of its job takes econds, during which time it's ignoring everything else. (keyboard handler): invoked when user types. It parses ut, and writes to a two-byte shared variable, "MEOS" (mode/	energy	<pre>77 reality, the fur 78 but that is not 79 imply. The probl 80 description.] 81 82 class3 = 0; 83 84 while (1) { 85 86 if (in fiel</pre>	<pre>m #2 (simplified) re and condensing to one thread of control; in nctions below are spread over two different threads actually the problem, despite what the paper may lem appears to given by the following simplified ld light position) { ent class3;</pre>	;,
<pre>3 9 March 2010 4 5 Therac-25 6 7 1. Software pro1 8 9 A. Three th 10 11Hand: 12 13Treat 14 eight s: 15 16Vtkbp 17 the inp 18 offset) 19""</pre>	reads: sets the collimator/turntable position : sets a bunch of other parameters. Part of its job takes econds, during which time it's ignoring everything else. (keyboard handler): invoked when user types. It parses ut, and writes to a two-byte shared variable, "MEOS" (mode/	energy	<pre>76 [simplifying her 77 reality, the fur 78 but that is not 79 imply. The probl 80 description.] 81 82 class3 = 0; 83 84 while (1) { 85 86 if (in fiel 87 increments)</pre>	nctions below are spread over two different threads actually the problem, despite what the paper may lem appears to given by the following simplified ld light position) {	s,
8 9 A. Three th: 10 11Hand: 12 13Treat 14 eight so 15 16Vtkbp 17 the inp 18 offset) 19"	reads: sets the collimator/turntable position : sets a bunch of other parameters. Part of its job takes econds, during which time it's ignoring everything else. (keyboard handler): invoked when user types. It parses ut, and writes to a two-byte shared variable, "MEOS" (mode/	energy	81 82 class3 = 0; 83 84 while (1) { 85 86 if (in fiel 87 increme		
10 11Hand: 12 13Treat 14 eight s 15 16Vtkbp 17 the inp 18 offset) 19"	<pre>sets the collimator/turntable position : sets a bunch of other parameters. Part of its job takes econds, during which time it's ignoring everything else. (keyboard handler): invoked when user types. It parses ut, and writes to a two-byte shared variable, "MEOS" (mode/- </pre>	energy	83 84 while (1) { 85 if (in fiel 87 increme		
12 13Treat 14 eight so 15 16Vtkbp 17 the inp 18 offset) 19"	: sets a bunch of other parameters. Part of its job takes econds, during which time it's ignoring everything else. (keyboard handler): invoked when user types. It parses ut, and writes to a two-byte shared variable, "MEOS" (mode/	energy	85 86 if (in fiel 87 increme		
16 Vtkbp 17 the inp 18 offset) 19 ""	ut, and writes to a two-byte shared variable, "MEOS" (mode/ \star{mode}	energy			
			91	ner operator pressed "set"	
21	Treat" reads top byte, sets current and energy Hand" reads bottom byte, sets the collimator/turntable posi do:	tion	93 if (cla	or pressed set) { ass3 != 0) { ve turntable out of field light mode;	
23			96 }		
25	gets and parses keyboard input): a_completion_flag = 0		97 } 98 99 What's the issu	ue here? (Hint: class3 is only one byte.)	
27 28 whi 29 30 31 32 33 34 35 36 37 38 39 40 41 42 } 43 45 Hand (sultarianti sultarianti sultari	<pre>le (1) { wait_for_keyboard_activity(); /* there was some keyboard activity; let's check it */ if (cursor_in_bottom_right) { parse_the_input(); set the MEOS variable set data_completion_flag = 1; signal hand thread signal treat thread } else { /* operator still typing */ data_completion_flag = 0; } yield(); ets the turntable position): le (1) { wait until signalled() read bottom byte of MEOS variable /* next line executes quickly */ set turntable position yield(); </pre>				
56 57 data	aent() { /* this is a subroutine that was called */				
58 59 60 61 62 63 64 65 66 67 68 69 70 70 71	<pre>while (1) { wait until signalled(); read top byte of MEOS variable set_energy_and_current(); set_bending_magnets(); /* this takes eight seconds */ if (data_completion_flag == 1) break; } /* * now we leave the subroutine and progress to a state in * which the machine will accept a "beam on" command */ return;</pre>				
72 } 73					

