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   CS 202
   Handout 8 (Class 9)
2
   Therac-25
   1. Software problem #1 (our best guess)
       A. Three threads:
            -- Hand: sets the collimator/turntable position
10
11
12
            --Treat: sets a bunch of other parameters. Part of its job takes
            eight seconds, during which time it's ignoring everything else.
13
14
15
            --Vtkbp (keyboard handler): invoked when user types. It parses
16
            the input, and writes to a two-byte shared variable, "MEOS" (mode/energy
17
            offset)
                --"Treat" reads top byte, sets current and energy
18
19
                --"Hand" reads bottom byte, sets the collimator/turntable position
20
        B. Pseudocode:
21
22
23
            Vtkbp (gets and parses keyboard input):
24
25
                data_completion_flag = 0
26
27
                while (1) {
                    wait_for_keyboard_activity();
28
                    /* there was some keyboard activity; let's check it */
29
30
                    if (cursor_in_bottom_right) {
31
                        parse_the_input();
32
                        set the MEOS variable
33
                        set data_completion_flag = 1;
                        signal hand thread
34
                        signal treat thread
35
                     } else {
37
                         /* operator still typing */
38
                        data_completion_flag = 0;
39
                    yield();
41
42
43
            Hand (sets the turntable position):
44
45
                while (1) {
46
                    wait until signalled
                    read bottom byte of MEOS variable
48
49
                     /* next line executes quickly */
50
                    set turntable position
                    yield();
52
53
            Treat (sets a bunch of parameters and delivers treatment):
54
55
56
                dataent() { /* this is a subroutine that was called */
57
58
                     while (1) {
                        wait until signalled
59
                        read top byte of MEOS variable
60
                        set_energy_and_current();
61
                        set_bending_magnets(); /* this takes eight seconds */
62
                        if (data_completion_flag == 1)
63
64
65
67
                     * now we leave the subroutine and progress to a state in
                     * which the machine will accept a "beam on" command
68
69
70
                    return:
71
72
```

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73 2. Software problem #2 (simplified)
75
       [Simplifying here and condensing to one thread of control; in
       reality, the functions below are spread over two different threads,
76
       but that is not actually the problem, despite what the paper
77
78
       sometimes says. The problem appears to be given by the following
79
       simplified description.]
80
       class3 = 0;
81
82
       while (1) {
83
            if (in field light position) {
85
                increment class3;
87
88
            check whether operator pressed "set"
89
90
91
            if (operator pressed set) {
                if (class3 != 0) {
92
93
                    move turntable out of field light position;
94
95
                break;
96
97
98
99
       What's the issue here? (Hint: class3 is only one byte.)
100
```



