handout05.txt Feb 13, 20 13:23 Page 1/4 CS 202, Spring 2020 2 Handout 5 (Class 6) The previous handout demonstrated the use of mutexes and condition 4 variables. This handout demonstrates the use of monitors (which combine mutexes and condition variables). 1. The bounded buffer as a monitor // This is pseudocode that is inspired by C++. 10 // Don't take it literally. 11 12 class MyBuffer { 13 14 public: 15 MyBuffer(); 16 ~MyBuffer(); void Enqueue(Item); 17 Item = Dequeue(); 18 19 private: int count; 20 21 int in; int out; 22 23 Item buffer[BUFFER_SIZE]; Mutex* mutex; 24 25 Cond* nonempty; Cond* nonfull; 26 27 28 29 void MyBuffer::MyBuffer() 30 31 32 in = out = count = 0; 33 mutex = new Mutex; nonempty = new Cond; 34 nonfull = new Cond; 35 37 38 MyBuffer::Enqueue(Item item) 39 41 mutex.acquire(); 42 while (count == BUFFER_SIZE) cond_wait(&nonfull, &mutex); 43 44 45 buffer[in] = item; in = (in + 1) % BUFFER_SIZE; 46 ++count; cond_signal(&nonempty, &mutex); 48 49 mutex.release(); 50 52 Item MyBuffer::Dequeue() 53 54 55 mutex.acquire(); 56 while (count == 0) 57 cond_wait(&nonempty, &mutex); 58 59 Item ret = buffer[out]; out = (out + 1) % BUFFER_SIZE; 60 --count; 61 cond_signal(&nonfull, &mutex); mutex.release(); 63 64 return ret; 65

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                                                                              Page 2/4
        int main(int, char**)
68
69
70
            MvBuffer buf:
71
            int dummy;
72
            tid1 = thread create(producer, &buf);
73
            tid2 = thread_create(consumer, &buf);
74
            // never reach this point
75
            thread_join(tid1);
76
            thread_join(tid2);
77
78
            return -1;
79
80
81
        void producer (void* buf)
82
            MyBuffer* sharedbuf = reinterpret_cast<MyBuffer*>(buf);
83
84
            for (;;) {
85
                /* next line produces an item and puts it in nextProduced */
                Item nextProduced = means_of_production();
86
87
                sharedbuf->Enqueue (nextProduced);
88
89
90
        void consumer(void* buf)
92
93
            MyBuffer* sharedbuf = reinterpret_cast<MyBuffer*>(buf);
            for (;;) {
94
                Item nextConsumed = sharedbuf->Dequeue();
95
96
                /* next line abstractly consumes the item */
97
98
                consume_item(nextConsumed);
99
100
101
        Key point: *Threads* (the producer and consumer) are separate from
        *shared object* (MyBuffer). The synchronization happens in the
103
104
        shared object.
105
```

handout05.txt Feb 13, 20 13:23 Page 3/4 2. This monitor is a model of a database with multiple readers and 107 writers. The high-level goal here is (a) to give a writer exclusive 108 access (a single active writer means there should be no other writers 109 and no readers) while (b) allowing multiple readers. Like the previous example, this one is expressed in pseudocode. 111 112 // assume that these variables are initialized in a constructor state variables: 113 AR = 0; // # active readers 114 AW = 0; // # active writers 115 WR = 0; // # waiting readers 116 117 WW = 0; // # waiting writers 118 Condition okToRead = NIL; 119 Condition okToWrite = NIL; 120 121 Mutex mutex = FREE; 122 123 Database::read() { 124 startRead(); // first, check self into the system 125 Access Data 126 doneRead(); // check self out of system 127 128 Database::startRead() { 129 acquire(&mutex); 130 while ((AW + WW) > 0) { 131 132 WR++; wait(&okToRead, &mutex); 133 134 WR--; 135 136 AR++; 137 release (&mutex); 138 139 Database::doneRead() { 140 acquire(&mutex); 141 AR--; 142 143 if (AR == 0 && WW > 0) { // if no other readers still signal(&okToWrite, &mutex); // active, wake up writer 144 145 146 release (&mutex); 147 148 149 Database::write(){ // symmetrical startWrite(); // check in 150 151 Access Data doneWrite(); // check out 152 153 154 Database::startWrite() { 155 156 acquire(&mutex); while ((AW + AR) > 0) { // check if safe to write. 157 158 // if any readers or writers, wait 159 wait (&okToWrite, &mutex); 160 ₩W--; 161 162 163 AW++; 164 release (&mutex); 165 166 Database::doneWrite() { 167 acquire(&mutex); 168 169 if (WW > 0) { 170 171 signal(&okToWrite, &mutex); // give priority to writers 172 } else if (WR > 0) { 173 broadcast (&okToRead, &mutex); 174 175 release (&mutex); 176 177 178 NOTE: what is the starvation problem here?

```
handout05.txt
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                                                                                Page 4/4
180 3. Shared locks
        struct sharedlock {
182
183
          int i;
          Mutex mutex;
184
185
          Cond c;
186
187
        void AcquireExclusive (sharedlock *sl) {
188
189
          acquire(&sl->mutex);
190
          while (sl->i) {
            wait (&sl->c, &sl->mutex);
191
192
193
          s1->i = -1;
194
          release(&sl->mutex);
195
196
197
        void AcquireShared (sharedlock *sl) {
          acquire(&sl->mutex);
198
          while (sl->i < 0) {
199
            wait (&sl->c, &sl->mutex);
200
201
          s1->i++:
202
203
          release(&sl->mutex);
204
205
        void ReleaseShared (sharedlock *sl) {
206
207
          acquire(&sl->mutex);
208
          if (!--sl->i)
            signal (&sl->c, &sl->mutex);
209
210
          release(&sl->mutex);
211
212
        void ReleaseExclusive (sharedlock *sl) {
213
          acquire(&sl->mutex);
214
          sl->i = 0;
215
216
          broadcast (&sl->c, &sl->mutex);
217
          release(&sl->mutex);
218
219
        QUESTIONS:
220
        A. There is a starvation problem here. What is it? (Readers can keep
221
222
           writers out if there is a steady stream of readers.)
        B. How could you use these shared locks to write a cleaner version
223
           of the code in the prior item? (Though note that the starvation
224
225
           properties would be different.)
```

Feb 13, 20 13:23 spinlock-mutex.txt Page 1/3

```
Implementation of spinlocks and mutexes
   1. Here is a BROKEN spinlock implementation:
            struct Spinlock {
             int locked;
           void acquire(Spinlock *lock) {
9
10
                if (lock->locked == 0) { // A}
11
12
                 lock->locked = 1;
13
                 break:
15
16
17
            void release (Spinlock *lock) {
18
19
             lock \rightarrow locked = 0;
20
21
            What's the problem? Two acquire()s on the same lock on different
22
23
            CPUs might both execute line A, and then both execute B. Then
            both will think they have acquired the lock. Both will proceed.
24
25
            That doesn't provide mutual exclusion.
26
```

```
spinlock-mutex.txt
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                                                                            Page 2/3
   2. Correct spinlock implementation
27
        Relies on atomic hardware instruction. For example, on the x86 (32-bit),
29
30
                    "xchq addr, %rax"
31
           does the following:
32
33
            (i) freeze all CPUs' memory activity for address addr
34
            (ii) temp <-- *addr
35
            (iii) *addr <-- %rax
36
37
            (iv) %rax <-- temp
            (v) un-freeze memory activity
38
39
40
        /* pseudocode */
41
        int xchg_val(addr, value) {
            %rax = value;
42
            xchg (*addr), %rax
43
44
45
46
        /* bare-bones version of acquire */
47
        void acquire (Spinlock *lock) {
48
          pushcli();
                        /* what does this do? */
49
          while (1) {
            if (xchg_val(&lock->locked, 1) == 0)
51
             break;
52
53
54
55
        void release(Spinlock *lock) {
56
          xchq_val(&lock->locked, 0);
57
          popcli(); /* what does this do? */
58
59
60
        /* optimization in acquire; call xchq_val() less frequently */
        void acquire(Spinlock* lock) {
62
63
64
            while (xchg_val(&lock->locked, 1) == 1) {
65
                while (lock->locked);
66
67
68
        The above is called a *spinlock* because acquire() spins. The
69
        bare-bones version is called a "test-and-set (TAS) spinlock"; the
70
       other is called a "test-and-test-and-set spinlock".
71
72
73
        The spinlock above is great for some things, not so great for
74
        others. The main problem is that it *busy waits*: it spins,
75
        chewing up CPU cycles. Sometimes this is what we want (e.g., if
76
        the cost of going to sleep is greater than the cost of spinning
77
        for a few cycles waiting for another thread or process to
78
        relinquish the spinlock). But sometimes this is not at all what we
        want (e.g., if the lock would be held for a while: in those
79
80
        cases, the CPU waiting for the lock would waste cycles spinning
81
        instead of running some other thread or process).
82
83
        NOTE: the spinlocks presented here can introduce performance issues
84
        when there is a lot of contention. (This happens even if the
85
        programmer is using spinlocks correctly.) The performance issues
        result from cross-talk among CPUs (which undermines caching and
86
        generates traffic on the memory bus). If we have time later, we will
88
        study a remediation of this issue (search the Web for "MCS locks").
89
        ANOTHER NOTE: In everyday application-level programming, spinlocks
90
        will not be something you use (use mutexes instead). But you should
92
        know what these are for technical literacy, and to see where the
93
        mutual exclusion is truly enforced on modern hardware.
```

spinlock-mutex.txt Feb 13, 20 13:23 Page 3/3 3. Mutex implementation

```
The intent of a mutex is to avoid busy waiting: if the lock is not
available, the locking thread is put to sleep, and tracked by a
queue in the mutex. The next page has an implementation.
```

```
fair-mutex.c
Feb 09, 20 14:51
                                                                            Page 1/1
   #include <sys/queue.h>
   typedef struct thread {
        // ... Entries elided.
        STAILQ_ENTRY(thread_t) qlink; // Tail queue entry.
   } thread t;
   struct Mutex {
        // Current owner, or 0 when mutex is not held.
       thread_t *owner;
11
12
        // List of threads waiting on mutex
       STAILQ(thread_t) waiters;
13
15
        // A lock protecting the internals of the mutex.
16
       Spinlock splock; // as in item 5, above
17 };
19
   void mutex_acquire(struct Mutex *m) {
20
21
       acquire(&m->splock);
22
23
        // Check if the mutex is held, if not current thread gets mutex and returns
24
        if (m->owner == 0) {
25
            m->owner = id_of_this_thread;
           release(&m->splock);
26
27
        } else
            // Add thread to waiters.
28
            STAILQ_INSERT_TAIL(&m->waiters, id_of_this_thread, qlink);
29
30
            // Tell the scheduler to add current thread to the list
31
32
            // of blocked threads. The scheduler needs to be careful
33
            // when a corresponding sched_wakeup call is executed to
34
            // make sure that it treats running threads correctly.
35
            sched_mark_blocked(&id_of_this_thread);
37
            // Unlock spinlock.
38
            release (&m->splock);
39
            // Stop executing until woken.
41
            sched_swtch();
42
43
            // When we get to this line, we are quaranteed to hold the mutex. This
            // is because we can get here only if context-switched-TO, which itself
44
45
            // can happen only if this thread is removed from the waiting queue,
            // marked "unblocked",/ and set to be the owner (in mutex_release()
46
            // below). However, we might actually have held the mutex at line 43 or
48
            // 44 (if we were context-switched out after the spinlock release(),
49
            // followed by being run as a result of another thread's release of the
50
            // mutex). But if that happens, it just means that we are
            // context-switched out an "extra" time before proceeding.
52
53
  void mutex_release(struct Mutex *m) {
56
        // Acquire the spinlock in order to make changes.
57
       acquire(&m->splock);
59
        // Assert that the current thread actually owns the mutex
60
        assert(m->owner == id_of_this_thread);
61
        // Check if anyone is waiting.
       m->owner = STAILQ_GET_HEAD(&m->waiters);
63
64
        // If so, wake them up.
65
66
        if (m->owner) {
67
            sched_wakeone(&m->owner);
68
            STAILQ_REMOVE_HEAD(&m->waiters, qlink);
69
70
        // Release the internal spinlock
71
        release(&m->splock);
```

98

99

100

101

72