Mehryar Mohri Foundations of Machine Learning 2024 Courant Institute of Mathematical Sciences Homework assignment 1 Sep 17, 2024 Due: October 01, 2024

# A Probability tools

- 1. Let  $f:(0, +\infty) \to \mathbb{R}_+$  be a function that admits an inverse  $f^{-1}$ , and let X be a random variable. Suppose that for all t > 0, the probability that X exceeds t is bounded by f(t), i.e.,  $\mathbb{P}[X > t] \le f(t)$ . Prove that for any  $\delta > 0$ , with probability at least  $1 \delta$ , the random variable X satisfies  $X \le f^{-1}(\delta)$ .
- 2. Let Z be a discrete random variable that takes non-negative integer values. Prove that  $\mathbb{E}[Z] = \sum_{n\geq 1} \mathbb{P}[Z \geq n]$ . Hint: express  $\mathbb{P}[Z = n]$  as  $\mathbb{P}[Z \geq n] \mathbb{P}[Z \geq n+1]$ .

#### Solution:

- 1. For any  $\delta > 0$ , let  $t = f^{-1}(\delta)$ . Plugging this in  $\mathbb{P}[X > t] \leq f(t)$  yields  $\mathbb{P}[X > f^{-1}(\delta)] \leq \delta$ , that is  $\mathbb{P}[X \leq f^{-1}(\delta)] \geq 1 \delta$ .
- 2. We assume that Z is a bounded random variable to avoid any convergence issues (although the statement is still true in the general case).

By definition of expectation and using the hint, we can write

$$\mathbb{E}[Z] = \sum_{n \ge 0} n \mathbb{P}[Z = n] = \sum_{n \ge 1} n (\mathbb{P}[Z \ge n] - \mathbb{P}[Z \ge n+1]).$$

Note that in this sum, for  $n \ge 1$ ,  $\mathbb{P}[Z \ge n]$  is added n times and subtracted n-1 times, thus  $\mathbb{E}[Z] = \sum_{n\ge 1} \mathbb{P}[Z \ge n]$ .

More generally, by definition of the Lebesgue integral, for any non-negative random variable Z, the following identity holds:

$$\mathbb{E}[Z] = \int_0^{+\infty} \mathbb{P}[Z \ge t] dt.$$

### **B** Label bias

1. Let  $\mathcal{D}$  be a distribution over  $\mathfrak{X}$ , and let  $f: \mathfrak{X} \to \{-1, +1\}$  be a labeling function. Our goal is to approximate the label bias of the distribution  $\mathcal{D}$ , denoted by  $p_+$ , which is defined as:

$$p_+ = \mathbb{P}_{x \sim \mathcal{D}}[f(x) = +1].$$

Let S be a labeled sample of size m, drawn i.i.d. from  $\mathcal{D}$ . Using S, derive an estimate  $\hat{p}_+$  of  $p_+$ . Show that for any  $\delta > 0$ , with probability at least  $1 - \delta$ , the following inequality holds:

$$|p_+ - \hat{p}_+| \le \sqrt{\frac{\log(2/\delta)}{2m}}.$$

Justify each step of the proof carefully.

#### Solution:

1. Let  $\widehat{p}_+$  be the fraction of positively labeled points in  $S = (x_1, \ldots, x_m)$ :

$$\widehat{p}_{+} = \frac{1}{m} \sum_{i=1}^{m} \mathbb{1}_{f(x_i)=+1}$$

Since the points are drawn i.i.d.,

$$\mathbb{E}[\widehat{p}_{+}] = \frac{1}{m} \sum_{i=1}^{m} \mathbb{E}_{S \sim \mathcal{D}^{m}} [1_{f(x_{i})=+1}] = \mathbb{E}_{S \sim \mathcal{D}^{m}} [1_{f(x_{1})=+1}] = \mathbb{E}_{x \sim \mathcal{D}} [1_{f(x)=+1}] = p_{+}.$$

Thus, by Hoeffding's inequality, for any  $\epsilon > 0$ ,

$$\mathbb{P}[|p_+ - \widehat{p}_+| > \epsilon] \le 2e^{-2m\epsilon^2}.$$

Setting  $\delta$  to match the right-hand side yields the result.

## C Learning in the presence of noise

- 1. In Lecture 2, we showed that the concept class of axis-aligned rectangles is PAC-learnable. Consider now the case where the training points received by the learner are subject to the following noise: points negatively labeled are unaffected by noise but the label of a positive training point is randomly flipped to negative with probability  $\eta \in (0, \frac{1}{2})$ . The exact value of the noise rate  $\eta$  is not known to the learner but an upper bound  $\eta'$  is supplied to him with  $\eta \leq \eta' < 1/2$ . Show that the algorithm described in class returning the tightest rectangle containing positive points can still PAC-learn axis-aligned rectangles in the presence of this noise. To do so, you can proceed using the following steps:
  - (a) Using the notation of the lecture slides, assume that  $\mathbb{P}[\mathbb{R}] > \epsilon$ . Suppose that  $R(\mathbb{R}') > \epsilon$ . Give an upper bound on the probability that  $\mathbb{R}'$  misses a region  $r_i, j \in [1, 4]$  in terms of  $\epsilon$  and  $\eta'$ ?
  - (b) Use that to give an upper bound on  $\mathbb{P}[R(\mathbb{R}') > \epsilon]$  in terms of  $\epsilon$  and  $\eta'$  and conclude by giving a sample complexity bound.

#### Solution:

1. (a) The probability that R' misses region  $r_j$  is the product of the probability p for each point  $x_i$  of the training sample to either not fall in  $r_j$  or be positive and fall in  $r_j$  with the label flipped to negative due to noise.

$$p = \mathbb{P}[x \notin r_j \lor (x \in r_j \land x \text{ positive} \land \text{ label of } x \text{ flipped})]$$
  
=  $\mathbb{P}[x \notin r_j \lor (x \in r_j \land \text{ label of } x \text{ flipped})]$   
=  $\mathbb{P}[x \notin r_j] + \mathbb{P}[(x \in r_j \land \text{ label of } x \text{ flipped})]$   
=  $(1 - \mathbb{P}[x \in r_j]) + \eta \mathbb{P}[x \in r_j]$   
=  $(1 - \eta)(1 - \mathbb{P}[x \notin r_j]) + \eta$   
 $\leq (1 - \eta)(1 - \epsilon/4) + \eta$   
=  $(1 - \epsilon/4) + \eta\epsilon/4 \leq 1 - \epsilon(1 - \eta')/4.$ 

(b) The probability that  $\mathbb{P}[R(\mathbf{R}') > \epsilon]$  is upper bounded by the probability that  $\mathbf{R}'$  misses at least one region  $r_j$ . Thus, by the union bound,

$$\mathbb{P}[R(\mathbf{R}') > \epsilon] \le 4 \left(1 - \epsilon(1 - \eta')/4\right)^m \le 4e^{-m\epsilon(1 - \eta')/4}$$

Setting  $\delta$  to match the upper bound leads to the following: with probability at least  $1 - \delta$ , for  $m \geq \frac{4}{(1-\eta')\epsilon} \log \frac{4}{\delta}$ ,  $R(\mathbf{R}') \leq \epsilon$ .