Foundations of Machine Learning Lecture I

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Logistics

- Prerequisites: basics in linear algebra, probability, and analysis of algorithms.
- Workload: homework assignments (4-5) + project (topic of your choice).
- Textbooks: no single textbook covering the material presented in this course, lecture slides will be made available electronically.

Introduction to Machine Learning

Machine Learning

- Definition: computational methods using experience to improve performance [e.g., to make accurate predictions].
- Experience: data-driven task [thus statistics, probability].
- Example: use height and weight to predict gender.
- Computer science: need to design efficient and accurate algorithms, analysis of complexity, theoretical guarantees.

Examples of Learning Tasks

- Optical character recognition
- Text or document classification, spam detection
- Morphological analysis, part-of-speech tagging, parsing
- Speech recognition, speech synthesis, speaker verification
- Image recognition, face recognition
- Fraud detection (credit card, telephone), network intrusion
- Games (chess, backgammon)
- Unassisted control of a vehicle (robots, navigation)
- Medical diagnosis

Some Broad Areas of ML

- Classification: assign a category to each object (OCR, text classification, speech recognition; note: the number of categories may be infinite in some difficult tasks).
- Regression: predict a real value for each object (prediction of stock values, variations of economic variables).
- Ranking: order objects according to some criterion (relevant web pages returned by a search engine).
- Clustering: partition data into homogenous groups (analysis of very large data sets).
- Dimensionality reduction: find lower-dimensional manifold preserving some properties of the data (computer vision).

Objectives of Machine Learning

- Algorithms: design of efficient, accurate, and general learning algorithms to
 - deal with large-scale problems (|data| > 1-10M).
 - make accurate predictions (unseen examples).
 - handle a variety of different learning problems.
- Theoretical questions
 - what can be learned efficiently? Under what conditions?
 - how well can it be learned computationally?
- Other: better understanding of (human or animal) learning? Help human learning? Better learning than humans.

This Course

- Several major and mathematically well-studied algorithms, e.g.,
 - support vector machines (SVMs), kernel methods
 - boosting algorithms
 - automata learning algorithms
- Theoretical foundations
 - analysis of algorithms
 - generalization bounds
- Applications
 - illustration of the use of these algorithms

Topics

- Probability, general bounds
- PAC learning model, error bounds, VC-dimension, bounds on sample complexity
- Support vector machines (SVMs), Perceptron, Winnow
- Kernel methods
- Boosting, generalization error, margin
- On-line learning, halving algorithm, weighted majority algorithm, mistake bounds
- Ranking problems and algorithms
- Empirical evaluation, confidence intervals, comparison of learning algorithms
- Learning automata and transducers, Angluin-type algorithms, other algorithms
- Reinforcement learning

Definitions and Terminology

- Example: an object, instance of the data used.
- Features: the set of attributes, often represented as a vector, associated to an example (e.g., *height* and *weight* for gender prediction).
- Labels: in classification, category associated to an object (e.g., positive or negative in binary classification); in regression real value.
- Training data: data used for training learning algorithm (often labeled data).
- Test data: data used for testing learning algorithm (unlabeled data).
- Unsupervised learning: no labeled data; supervised learning: uses labeled data; semi-supervised learning: intermediate situations.

Example - SPAM Detection

- Problem: classify each e-mail message as SPAM or non-SPAM (binary classification problem)
- Potential data: large collection of SPAM and non-SPAM messages (labeled examples)
- Learning stages:
 - divide labeled collection into training and test data.
 - associate relevant features to examples (e.g., presence or absence of some sequences; importance of *prior knowledge*).
 - use training data and features to train machine learning algorithm.
 - predict labels of examples in test data, evaluate algorithm.

Example

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- It is sometimes difficult to find relevant features
- Knowledge about the problem can be very useful!

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Training		Test data		
n v p d	n	n v d a	-	
dnvd	n	nvnb	-	
anvb	b			
dnvp	n			
danv	b			

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Training		Test data		
n v p d	n	n v d a	-	
anva	n	nvnb	-	
anvb	b			
dnvp	n			
danv	b			

Training data		Test data		
noun verb prep det det noun verb det a noun verb adv det noun verb prep det a noun verb	noun noun adv noun adv	noun verb det a noun verb noun adv	noun adv	

Generalization

- Definition: a learning algorithm is a consistent learner when it commits no error on examples from the training data
- Naive consistent learners are poor predictors, e.g.,
 - Arbitrary linear separation:



 Learning DNF formulas: the disjunction of all positive examples is a consistent learner, but learning k-term DNF is NP-complete!

 $\bigvee_{i=1}^k a_i(X_1) \wedge \cdots \wedge a_i(X_n), \text{ with } a_i(X_j) \in \{X_j, \overline{X_j}, 1\}.$

Problem: poor generalization, closer to memorization, computational complexity.

Probability Review

Probabilistic Model

- Sample space: Ω , set of all outcomes or elementary events possible in a trial, e.g., casting a die or tossing a coin.
- Event: subset $A \subseteq \Omega$ of sample space. The set of all events must be closed under complementation and countable union and intersection.
- Probability distribution: mapping \Pr from the set of all events to [0, 1] such that $\Pr[\Omega] = 1$, and for all mutually exclusive events, n

$$\Pr[A_1 \cup \ldots \cup A_n] = \sum_{i=1} \Pr[A_i].$$

Random Variables

- Definition: a random variable is a function $X: \Omega \to \mathbb{R}$ such that for any interval I, the subset of the sample space $\{A: X(A) \in I\}$ is an event. Such a function is said to be measurable.
- Example: the sum of the values obtained when casting a die.
- Probability density function of random variable X: function $f : x \mapsto f(x) = \Pr[X = x]$.
- Joint probability density function of X and Y: $f: (x, y) \mapsto f(x, y) = \Pr[X = x \land Y = y].$

Conditional Probability and Independence

• Conditional probability of event A given B:

$$\Pr[A \mid B] = \frac{\Pr[A \land B]}{\Pr[B]},$$

when $\Pr[B] \neq 0.$

 \bullet Independence: two events A and B are independent when

$$\Pr[A \wedge B] = \Pr[A] \Pr[B].$$

Equivalently, $\Pr[A \mid B] = \Pr[A]$, when $\Pr[B] \neq 0$.

Some Probability Formulae

• Sum rule:

 $\Pr[A \lor B] = \Pr[A] + \Pr[B] - \Pr[A \land B].$

• Union bound:

$$\Pr[\bigvee_{i=1}^{n} A_i] \le \sum_{i=1}^{n} \Pr[A_i].$$

• Bayes formula:

$$\Pr[X \mid Y] = \frac{\Pr[Y \mid X] \Pr[X]}{\Pr[Y]} \quad (\Pr[Y] \neq 0).$$

Some Probability Formulae

• Chain rule:

$$\Pr[\bigwedge_{i=1}^{n} X_i] = \Pr[X_1] \Pr[X_2 \mid X_1] \Pr[X_3 \mid X_1 \land X_2]$$

...
$$\Pr[X_n \mid \bigwedge_{i=1}^{n-1} X_i].$$

• Theorem of total probability: assume that

 $\Omega = A_1 \cup A_2 \cup \ldots \cup A_n, \text{ with } A_i \cap A_j = \emptyset \text{ for } i \neq j;$

then for any event B,

$$\Pr[B] = \sum_{i=1}^{n} \Pr[B \mid A_i] \Pr[A_i].$$

Application - Maximum a Posteriori

• Problem formulation: given some observation O, determine the most likely outcome out of a set of hypotheses H:

$$\hat{h} = \operatorname*{argmax}_{h \in H} \Pr[h \mid O] = \operatorname*{argmax}_{h \in H} \frac{\Pr[O|h]\Pr[h]}{\Pr[O]} = \operatorname*{argmax}_{h \in H} \Pr[O|h]\Pr[h]$$

Example - medical diagnosis: laboratory test with two results $O = \{Positive, Negative\}$ used to determine if a patient has specific disease d, thus $H = \{d, no-d\}$. Assumptions:

- Pr[d] = .005 (a priori probability of d);
- $\Pr[Positive | d] = .98$ (probability of true positive)
- Pr[Negative | no-d] = .95 (probability of true negative)
- If the test is *Positive*, what should be the diagnosis?

 $Pr[Positive | d] Pr[d] = .98 \times .005 = .0049$

Pr[Positive | no-d] Pr[no-d] = $(1 - .95) \times (1 - .005) = .04975 > .0049$

Expectation

• **Definition**: the expectation (or mean) of a random variable X is

$$\mathbf{E}[X] = \sum_{x} x \Pr[X = x].$$

- Properties:
 - linearity, E[aX + bY] = aE[X] + bE[Y].
 - if X and Y are independent,

$$\mathbf{E}[XY] = \mathbf{E}[X]\mathbf{E}[Y].$$

Expectation

• Theorem (Markov's inequality): let X be a nonnegative random variable with $E[X] < \infty$, then for all t > 0,

$$\Pr[X \ge t \mathbf{E}[X]] \le \frac{1}{t}.$$

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• Proof:

$$\begin{aligned} \Pr[X \ge t \mathbf{E}[X]] &= \sum_{x \ge t \mathbf{E}[X]} \Pr[X = x] \\ &\leq \sum_{x \ge t \mathbf{E}[X]} \Pr[X = x] \frac{x}{t \mathbf{E}[X]} \\ &\leq \sum_{x} \Pr[X = x] \frac{x}{t \mathbf{E}[X]} \\ &= \mathbf{E}[\frac{x}{t \mathbf{E}[X]}] = \frac{1}{t}. \end{aligned}$$

Variance

• **Definition:** the *variance* of a random variable X is

$$Var[X] = \sigma_X^2 = E[(X - E[X])^2].$$

 σ_X is called the standard deviation of the random variable X.

- Properties:
 - $\operatorname{Var}[aX] = a^2 \operatorname{Var}[X].$
 - if X and Y are independent,

$$\operatorname{Var}[X+Y] = \operatorname{Var}[X] + \operatorname{Var}[Y].$$

Variance

- Theorem (Chebyshev's inequality): let X be a random variable with $Var[X] < \infty$, then for all t > 0, $Pr[|X E[X]| \ge t\sigma_X] \le \frac{1}{t^2}$.
- Proof: Observe that
- $\Pr[|X \operatorname{E}[X]| \ge t\sigma_X] = \Pr[(X \operatorname{E}[X])^2 \ge t^2\sigma_X^2].$

The result follows Markov's inequality.

Application

- Experiment: roll a pair of fair dice *n* times. Can we give a good estimate of total value of the *n* rolls?
- Mean: 7n, variance: 35/6 n; thus by Chebyshev's inequality, the final sum will lie between

$$7n - 10\sqrt{\frac{35}{6}n}$$
 and $7n + 10\sqrt{\frac{35}{6}n}$

in at least 99% of all experiments. The odds are better than 99 to 1 that the sum be roughly between 6.976M and 7.024M after 1M rolls.

Weak Law of Large Numbers

• Theorem: let $(X_n)_{n \in \mathbb{N}}$ be a sequence of random variables with the same mean μ and variance $\sigma^2 < \infty$ and let $\overline{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$, then for any $\epsilon > 0$,

$$\lim_{n \to \infty} \Pr[|\overline{X}_n - \mu| \ge \epsilon] = 0.$$

- Proof: Since the variables are independent, $\operatorname{Var}[\overline{X}_n] = \sum_{i=1}^n \operatorname{Var}[\frac{X_i}{n}] = \frac{n\sigma^2}{n^2} = \frac{\sigma^2}{n}.$
- Thus, by Chebyshev's inequality, $\Pr[|\overline{X}_n - \mu| \ge \epsilon] \le \frac{\sigma^2}{n\epsilon^2}.$

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