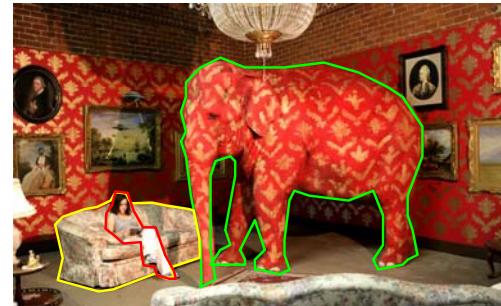


Large Image Databases and Small Codes for Object Recognition

Rob Fergus (NYU)
 Antonio Torralba (MIT)
 Yair Weiss (Hebrew U.)
 William T. Freeman (MIT)

Object Recognition

Pixels → Description of scene contents



Banksy, 2006

Internet contains billions of images



Amazing resource

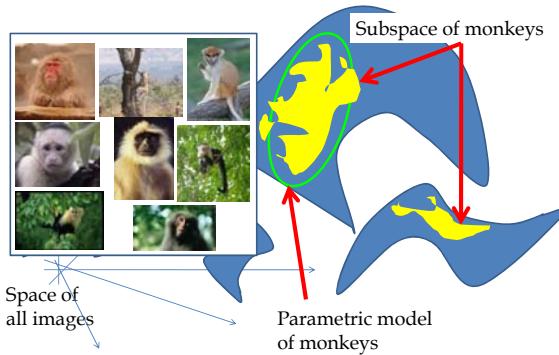
Maybe we can use it for recognition?

But so much data

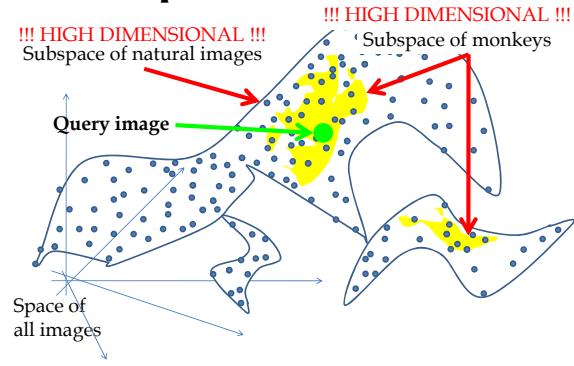
How can we search fast?

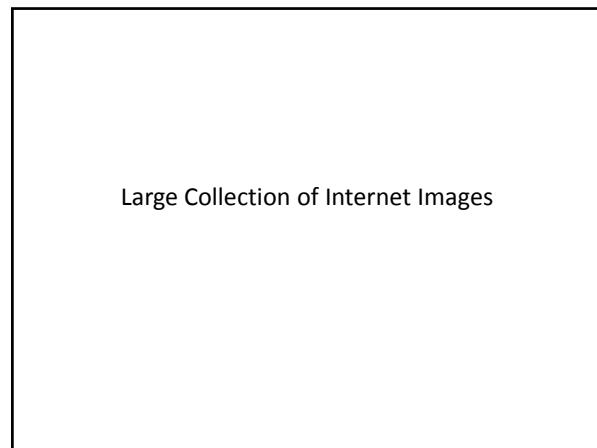
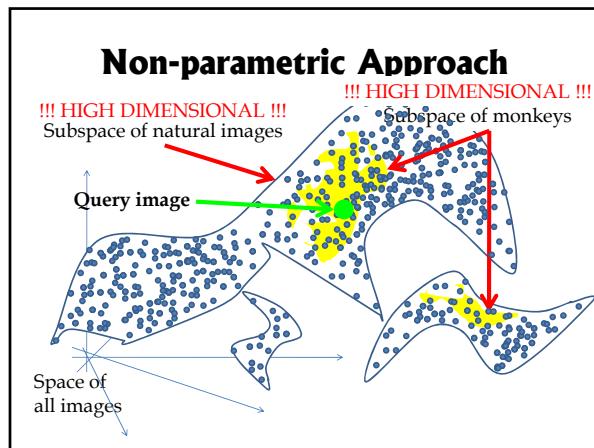
1. Big Data

Parametric models



Non-parametric Approach





Thumbnail Collection Project

- Collect images for ALL objects
 - List obtained from WordNet
 - 75,378 non-abstract nouns in English
- Example first 20:

a-bomb	a_kempis
a-horizon	aalborg
a._conan_doyle	aallii
a._e._burnside	aalost
a._e._housman	aalto
a._e._kennelly	aar
a.e.	aardvark
a.battery	aardwolf
a_cappella_singing	aare
a._horizon	aare_river

Thumbnail Collection

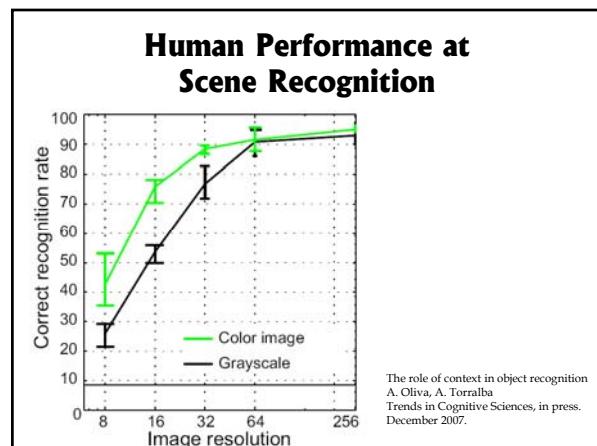
- 7 different search engines

Dataset Statistics

- Overall stats
 - 79,302,017 images
 - 75,062 different words
- Details
 - Two formats: square & rectangular
 - Gathered at 4.5 images/second
 - Downloaded 97,245,098 images
 - 18% duplicate rate
 - Disk usage: ~ 700Gb
 - Collection time: ~ 9 months

32x32 square

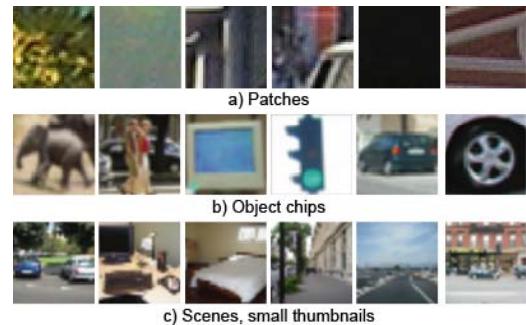
32xN rectangular



Human Labeling of Tiny Scenes



Image Patches vs Tiny Images



Recognition Approach

Non-parametric Classifier

- Nearest-neighbors
- For each query, obtain **sibling set** (neighbors)
- 3 different types of distance metric
- Hand-designed, use whole image



Metric 1 - D_{ssd}

- Sum of squared differences (SSD)

$$D_{ssd}^2 = \sum_{x,y,c} \left[\text{Image 1} - \text{Image 2} \right]^2$$

To give invariance to illumination:
Each image normalized to
be zero mean, unit variance



Comparison of metrics



Sibling Sets with Different Metrics

D_{ssd} D_{shift}

Quality of Sibling Set using D_{shift}

Size of dataset

10^5
 10^6
 10^8

Exploring the Sub-Space of Natural Images

How Many Images Are There?

Cumulative probability of max correlation

Max normalized correlation $\rho = (1 - D_1 / 2)$

Note: $D_1 = D_{SSD}$

Examples

Normalized correlation scores

	(0.94)	(0.74)	(0.74)	(0.72)	(0.70)	(0.65)	(0.60)	(0.50)
skagerak								
catmandu								
noether								

How Many Images Are There?

Cumulative probability of max correlation

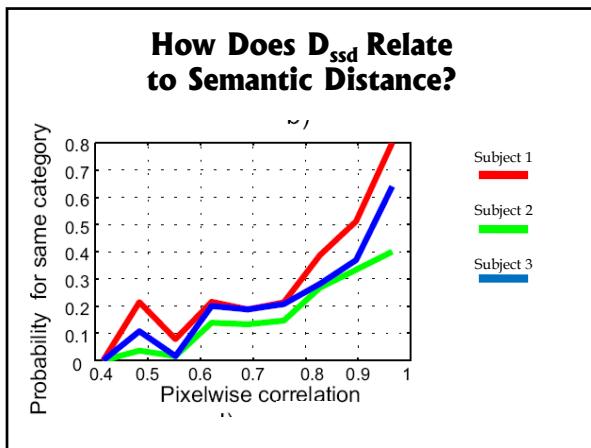
Max normalized correlation $\rho = (1 - D_1 / 2)$

Probability match

$\rho > 0.8$
 $\rho > 0.9$

10^4 10^5 10^6 10^7 number of images

Note: $D_1 = D_{SSD}$



Label Assignment

- Distance metrics give set of nearby images
 - How to compute label?



- Issues:
 - Labeling noise
 - Keywords can be very specific
 - e.g. yellowfin tuna

Wordnet – a Lexical Dictionary

<http://wordnet.princeton.edu/>

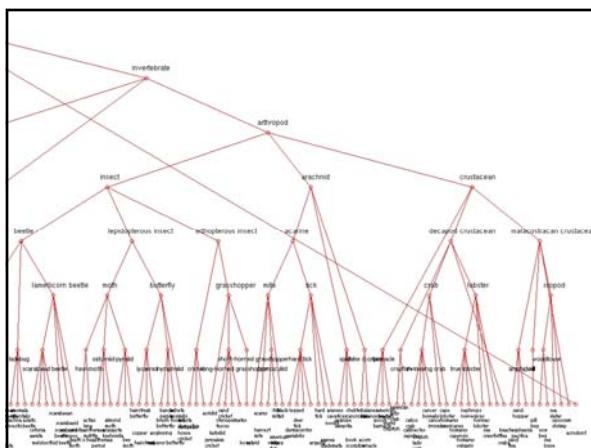
```
Synonyms/Hypernyms (Ordered by Estimated Frequency) of noun aardvark

Sense 1
aardvark, ant bear, anteater, Orycteropus afer
    => placental, placental mammal, eutherian, eutherian mammal
        => mammal
            => vertebrate, craniate
                => chordate
                    => animal, animate being, beast, brute, creature
                        => organism, being
                            => living thing, animate thing
                                => object, physical object
                                    => entity
```

Wordnet Hierarchy

Synonyms/Hypernyms (Ordered by Estimated Frequency) of noun **aardvark**

- Convert graph structure into tree by taking most common meaning



Wordnet Voting Scheme

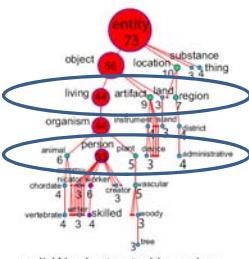


a) Input image



One image - one vote

Classification at Multiple Semantic Levels

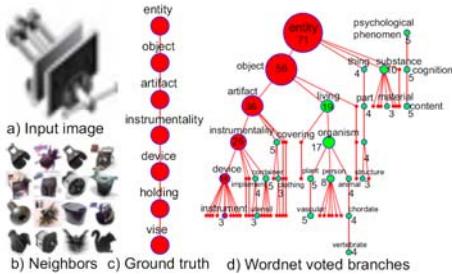


Votes:

Animal	6	44
Artifact	33	9
Plant		3
Region	3	
Administrative	40	
Others	22	

1 d) Wordnet voted branches

Wordnet Voting Scheme



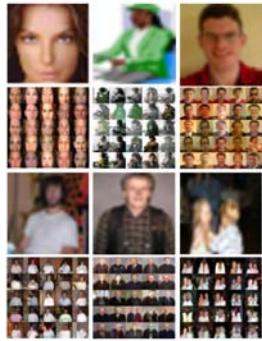
Wordnet Voting

- Overcomes differences in level of semantic labeling:
 - e.g. “person” & “sir arthur conan doyle”
 - Totally incorrect labels form hopefully uniform background noise
 - Assumes semantic and visual consistency are closely related

Recognition Experiments

Person Recognition

- 23% of all images in dataset contain people
 - Wide range of poses: not just frontal faces



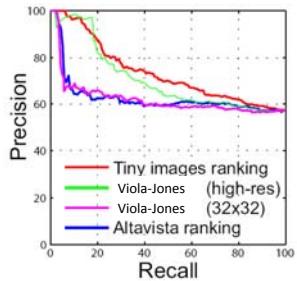
Person Recognition – Test Set

- 1016 images from Altavista using “person” query
 - High res and 32x32 available
 - Disjoint from 79 million tiny images



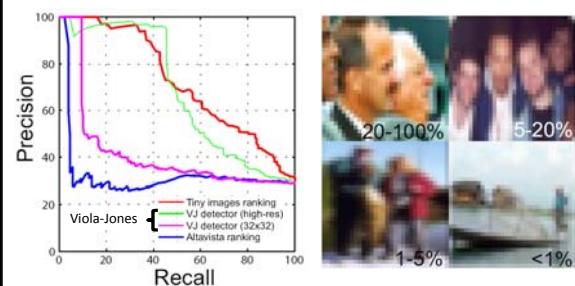
Person Recognition

- Task: person in image or not?

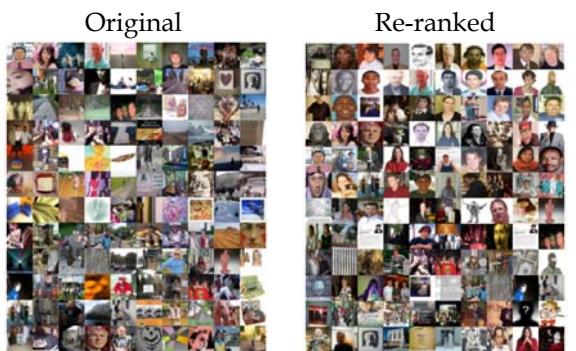


Person Recognition

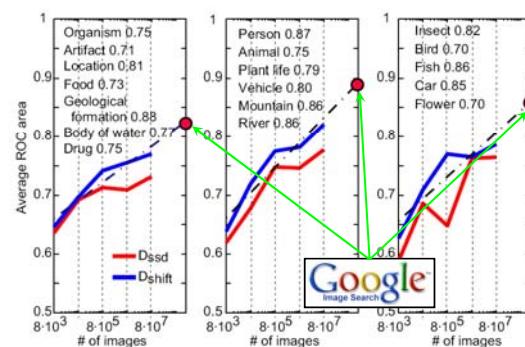
- Subset where face >20% of image



Re-ranked Altavista Images



Object Classification



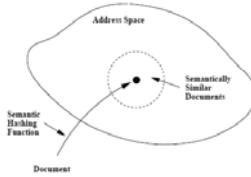
So far....

- Surprising performance from non-parametric methods
- But so slow.....
- ~ 1 Minute to find neighbors in 80 million
 - Essentially a brute force scheme

2. Small codes

Learning to retrieve quickly

- Semantic Hashing
 - Salakhutdinov & Hinton, SIGIR 2007
 - Text documents
- Non-linear dimensionality reduction of data to binary codes
- Preserve semantic distance
- Hamming ball search
 - Hamming distance \rightarrow # different bits
 - Direct memory lookup via bit flips
 - Lookup time **independent** of # data points



Compact Binary Codes

- Google has few billion images (10^9)
 - Big PC has ~ 10 Gbytes (10^{11} bits)
- \rightarrow Budget of 10^2 bits/image
- 1 Megapixel image is 10^7 bits
 - 32x32 color image is 10^4 bits
- \rightarrow Need serious dimensionality reduction!!

Restricted Boltzmann Machine (RBM) architecture

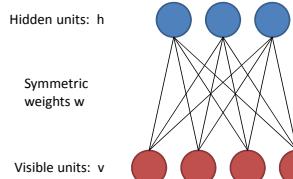
- Network of binary stochastic units
- Hinton & Salakhutdinov, Nature 2006

$$E(\mathbf{v}, \mathbf{h}) = - \sum_{i \in \text{visible}} b_i v_i - \sum_{j \in \text{hidden}} b_j h_j - \sum_{i,j} v_i h_i w_{ij}$$

Parameters: Weights w Biases b

Hidden units: h
Visible units: v

$$p(\mathbf{v}) = \sum_{\mathbf{h}} \frac{e^{-E(\mathbf{v}, \mathbf{h})}}{\sum_{\mathbf{u}, \mathbf{g}} e^{-E(\mathbf{u}, \mathbf{g})}}$$



RBM architecture

- Network of binary stochastic units
- Hinton & Salakhutdinov, Nature 2006

$$E(\mathbf{v}, \mathbf{h}) = - \sum_{i \in \text{visible}} b_i v_i - \sum_{j \in \text{hidden}} b_j h_j - \sum_{i,j} v_i h_i w_{ij}$$

Parameters: Weights w Biases b

Convenient conditional distributions:

$$p(h_j = 1 | \mathbf{v}) = \sigma(b_j + \sum_i w_{ij} v_i)$$

$$p(v_i = 1 | \mathbf{h}) = \sigma(b_i + \sum_j w_{ij} h_j)$$

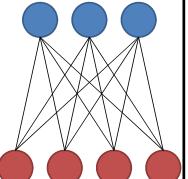
$$\sigma(x) = 1/(1 + e^{-x}), \text{ the logistic function}$$

Learn weights and biases using Contrastive Divergence

Hidden units: h

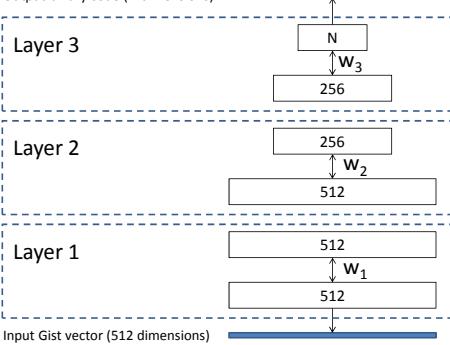
Symmetric weights w

Visible units: v



Multi-Layer RBM architecture

Output binary code (N dimensions)

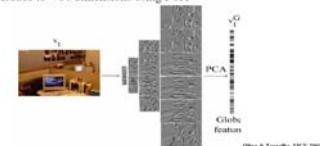


Input to RBM: Gist vectors

- Difficult to train directly on pixels
- Use GIST descriptor instead

Feature vector for an image:
the “gist” of the scene

- Compute $12 \times 30 = 360$ dim. feature vector
- Or use steerable filter bank, 6 orientations, 4 scales, averaged over 4×4 regions = 384 dim. feature vector
- Reduce to ~ 80 dimensions using PCA



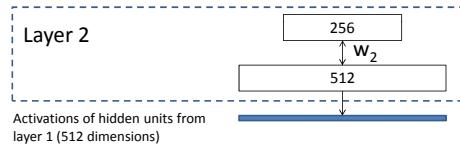
Training RBM models

- Two phases
 1. Pre-training
 - Unsupervised
 - Use Contrastive Divergence to learn weights and biases
 - Gets parameters to right ballpark
 2. Fine-tuning
 - Supervised
 - No longer stochastic
 - Backpropagate error to update parameters
 - Moves parameters to local minimum

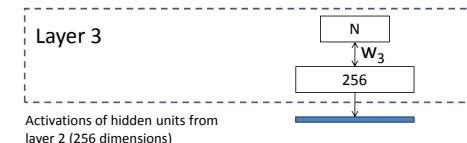
Greedy pre-training (Unsupervised)



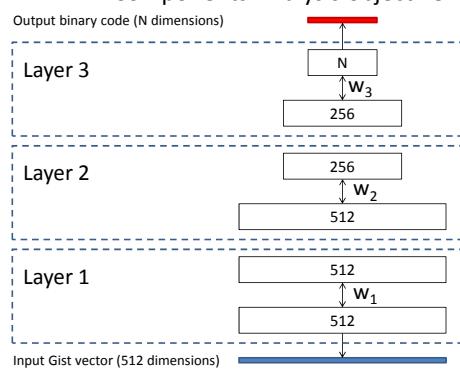
Greedy pre-training (Unsupervised)



Greedy pre-training (Unsupervised)



Backpropagation using Neighborhood Components Analysis objective

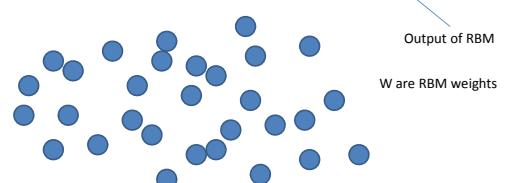


Neighborhood Components Analysis

- Goldberger, Roweis, Salakhutdinov & Hinton, NIPS 2004

$$O_{NCA} = \sum_{k=1}^K \sum_{l: e^k = e^l} p_{kl}$$

$$p_{kl} = \frac{e^{-\|f(\mathbf{x}^k|W) - f(\mathbf{x}^l|W)\|^2}}{\sum_{m \neq l} e^{-\|f(\mathbf{x}^m|W) - f(\mathbf{x}^l|W)\|^2}}$$



Neighborhood Components Analysis

- Goldberger, Roweis, Salakhutdinov & Hinton, NIPS 2004

$$O_{\text{NCA}} = \sum_{k=1}^K \sum_{l: c^k = c^l} p_{kl} \quad p_{kl} = \frac{e^{-||f(\mathbf{x}^k|W) - f(\mathbf{x}^l|W)||^2}}{\sum_{m \neq l} e^{-||f(\mathbf{x}^m|W) - f(\mathbf{x}^l|W)||^2}}$$

Assume K=2 classes

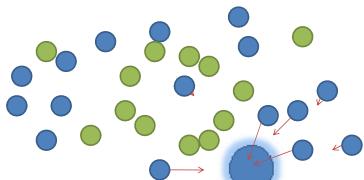


Neighborhood Components Analysis

- Goldberger, Roweis, Salakhutdinov & Hinton, NIPS 2004

$$O_{\text{NCA}} = \sum_{k=1}^K \sum_{l: c^k = c^l} p_{kl} \quad p_{kl} = \frac{e^{-||f(\mathbf{x}^k|W) - f(\mathbf{x}^l|W)||^2}}{\sum_{m \neq l} e^{-||f(\mathbf{x}^m|W) - f(\mathbf{x}^l|W)||^2}}$$

Pulls nearby points
OF SAME CLASS
closer

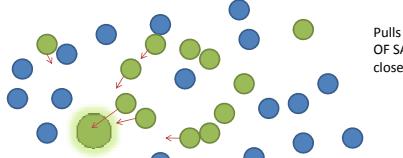


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Pulls nearby points
OF SAME CLASS
closer



Goal is to preserve neighborhood structure of original, high dimensional, space

Two test datasets

- LabelMe

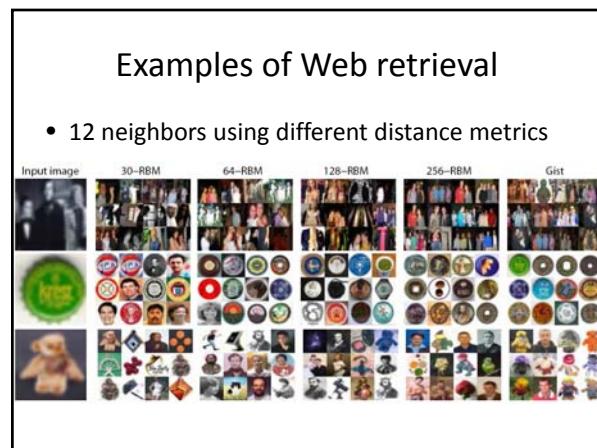
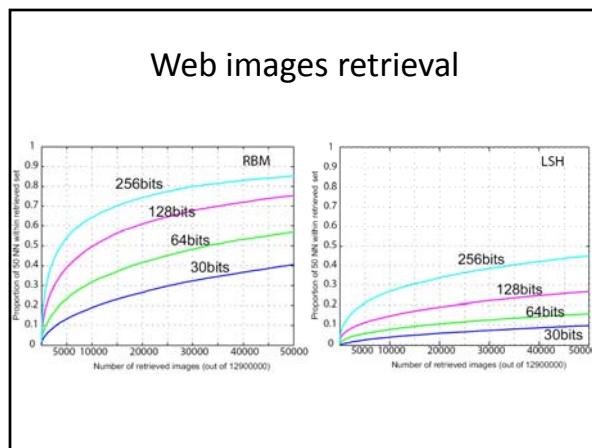
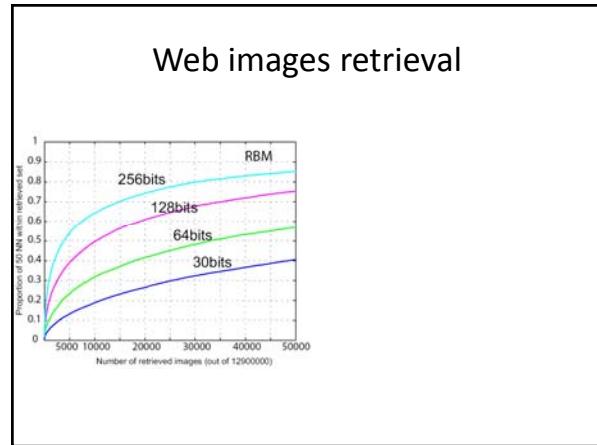
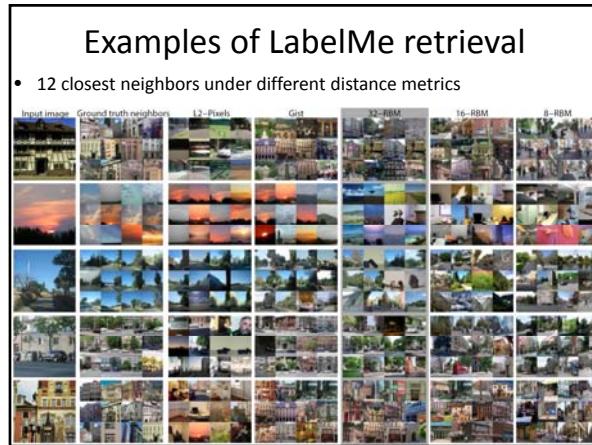
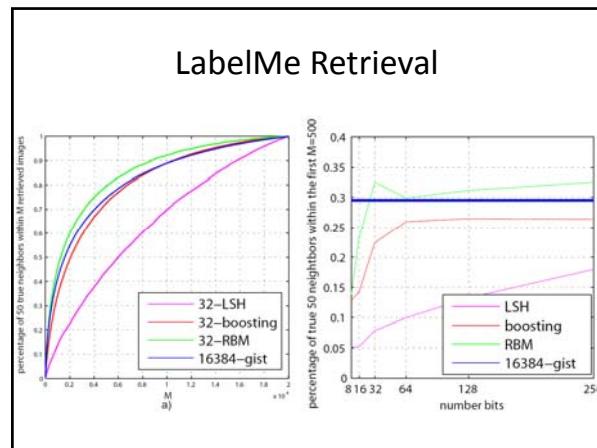
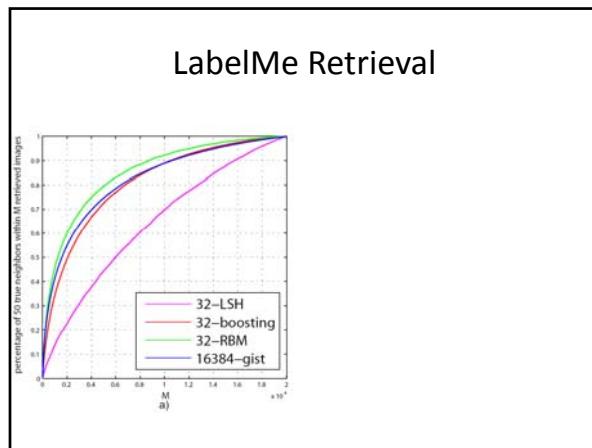
- 22,000 images
 - Ground truth segmentations for all
 - Can define distance btw. images using these segmentations

- Web data

- 12.9 million images
 - Subset of 80 million images
 - No labels, so use L2 distance btw. GIST vectors as ground truth



Retrieval Experiments



Retrieval Timings

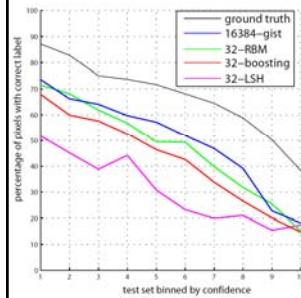
Dataset	LabelMe	Web
# images	2×10^4	1.29×10^7
Gist vector dim.	512	384
Method	Time (s)	Time (s)
Spill tree - Gist vector	1.05	-
Brute force - Gist vector	0.38	-
Brute force - 30 bit binary	4.3×10^{-4}	0.146
" - 30 bit binary, M/T	2.7×10^{-4}	0.074
Brute force - 256 bit binary	1.4×10^{-3}	0.75
" - 256 bit binary, M/T	4.7×10^{-4}	0.23
Hashing - 30 bit binary	6×10^{-6}	6×10^{-6}

Recognition Experiments

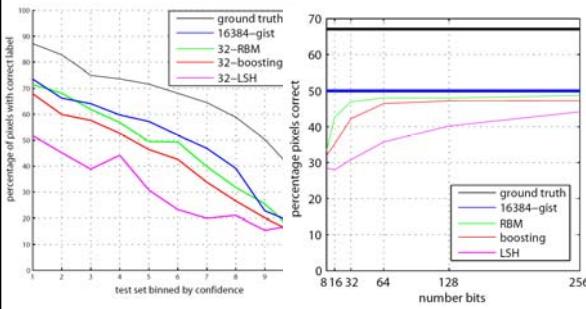
LabelMe Recognition examples



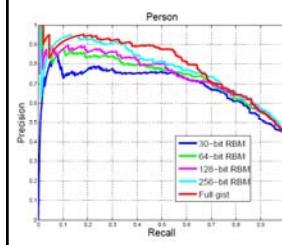
LabelMe Recognition



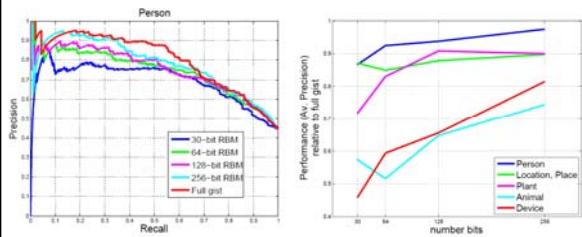
LabelMe Recognition



Web dataset Recognition



Web dataset Recognition



Conclusions

- Can do interesting things with lots of data
 - What would happen with Google's ~ 2 billion images?
- Possible to build compact codes for retrieval
 - Much room for improvement