

Distributed Systems

Lecture 4

- Finish Linearizability

- CAF

- Replicated State Machine

Checking linearizability / seq cst/...

The rules:

Given: A history

- Total order

Extract a partial order

- Linearizability

$$OP_1 <_H OP_2$$

$$\Leftrightarrow \text{ret } OP_1 < \text{inv } OP_2$$

$$\textcircled{i} <_H \textcircled{ii} [2 < 3]$$

v

vi

- \textcircled{i} 1. p Enq(x) A
2. p OK(x) A
3. q Enq(y) B
4. q OK(y) B
- \textcircled{ii} 5. q Enq(x) A
6. q OK(x) A
7. p Enq(y) B
8. p OK(y) B
- \textcircled{iii} 9. p Deq() A
10. p OK(y) A
11. q Deq() B
12. q OK(x) B

Reminder

Inv: object op proc

Ret: object OK(-) proc

- \textcircled{i} 1. p Enq(x) A
2. p OK(x) A
3. q Enq(y) B
4. q OK(y) B

- seq cst

$$OP_1 \leq_s OP_2$$

\Leftrightarrow OP_1, OP_2 from same process &
ret $OP_1 \leq_{inv} OP_2$

$$i \leq_s iii [A, 2 < 5]$$



- (ii) 3. q Enq(y) B
- 4. q OKC) B
- (iii) 5. q Enq(x) A
- 6. q OKC) A
- (iv) 7. p Enq(y) B
- 8. p OKC) B
- (v) 9. p Deq() A
- 10. p OK(y) A
- (vi) 11. q Deq() B
- 12. q OK(x) B

III Find an extension (SUPERSET) to
partial order that is a total
order on operations & meets
ADT's sequential spec

Linearizability

- i 1. p Enq(x) A
- 2. p OKC) A
- 3. q Enq(y) B
- 4. q OKC) B
- iii 5. q Enq(x) A
- 6. q OKC) A
- iv 7. p Enq(y) B
- 8. p OKC) B
- v 9. p Deq() A
- 10. p OK(y) A
- vi 11. q Deq() B
- 12. q OK(x) B

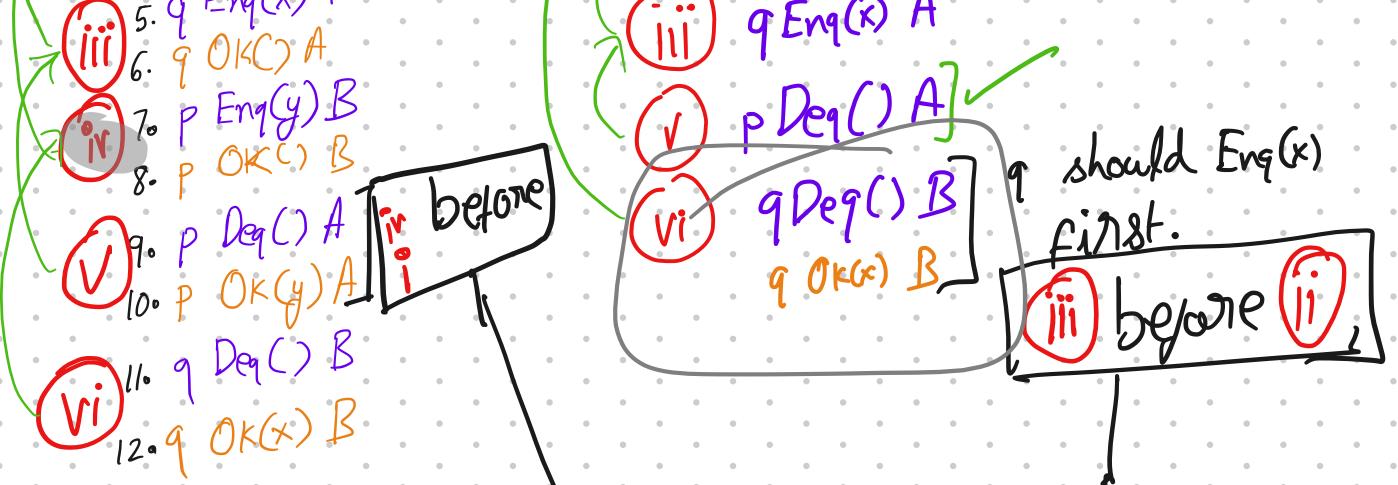
No

p should
enq(y) first

Serializable seq Cst

- i 1. p Enq(x) A
- 2. p OKC) A
- 3. q Enq(y) B
- 4. q OKC) B
- 5. p Enq(x) A

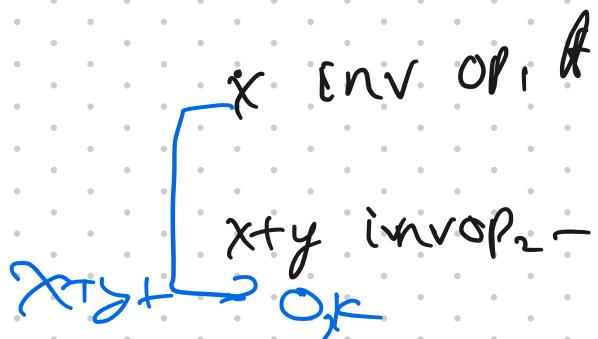
- ii 1. q Enq(y) B
- iv 2. p Enq(y) B
- i 3. p Enq(x) A



Not possible while preserving \prec_s
 \Rightarrow Not Seq cst

Observation - Seq cst - Fine for computed total order to not preserve history total order

Linearizable - Real-Time



Locality

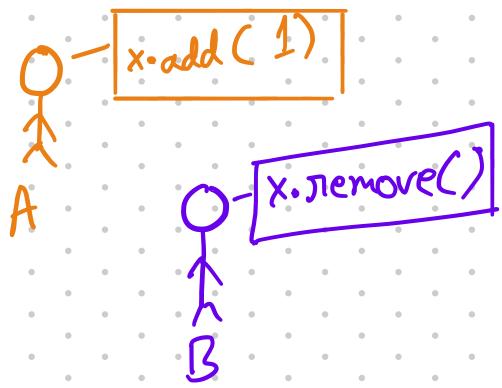
```
add(item) {
    ctr.inc()
    q.enq(item)
    ret OK()
}
```

```
remove() {
    if ctr.count() > 0 {
        ctr.dec()
        return q.deq()
    } else {
        return OK(empty)
    }
}
```

on item

3

3



[ctn]	inc()	A
[ctn]	OK(1)	A
[ctn]	count()	B
[ctn]	OK(1)	B
[ctn]	dec()	B
[ctn]	OK(0)	B
[q]	deq()	B
[q]	OK(1)	B
[q]	enq(1)	A
[q]	OK(2)	A

System with Counter
+ queue:
- Linearizable?

System with new add remove =>
if empty return empty
else

Comparing Consistency Models

A stronger than B

For any history H: $H \vdash A \Rightarrow H \vdash B$
but not $H \vdash B \Rightarrow H \vdash A$

A equivalent to B

$$H \vdash A \Leftrightarrow H \vdash B$$

Linearizability

$$OP_1 <_H OP_2$$

$$\Leftrightarrow \text{ret } OP_1 < \text{inv } OP_2$$

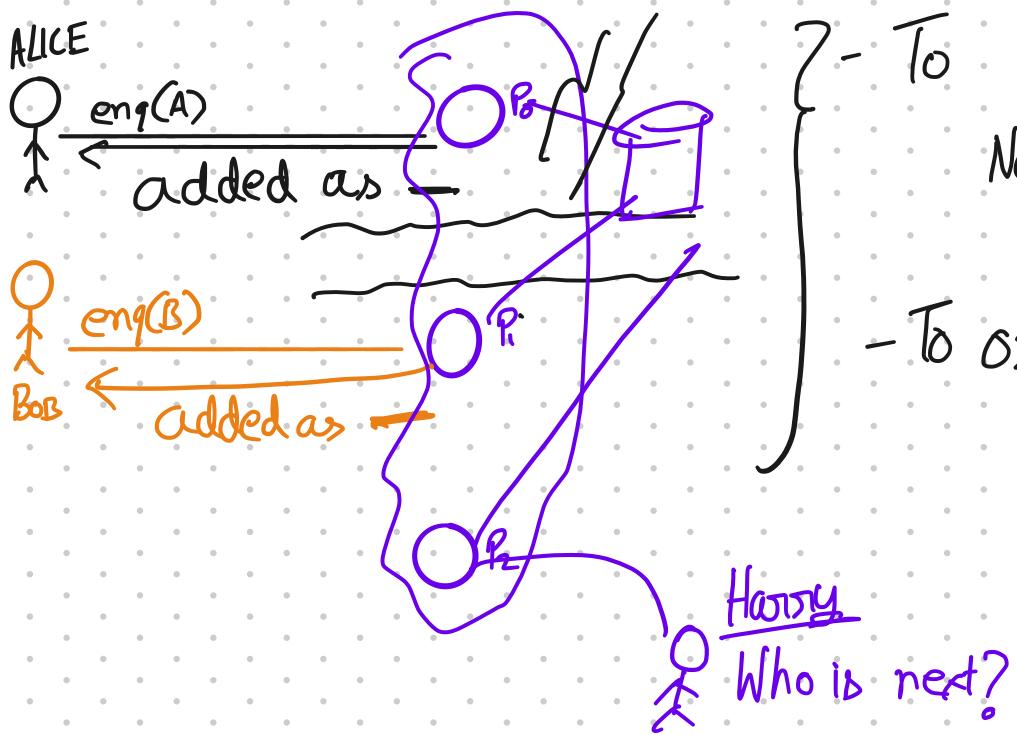
Seq Cst

$$OP_1 <_S OP_2$$

\Leftrightarrow OP_1, OP_2 from same process
ret $OP_1 < \text{inv } OP_2$

CAP

CORE MESSAGE: Linearizability comes at a cost



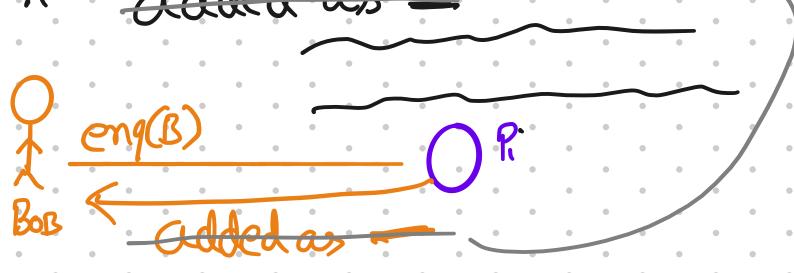
- To be linearizable
Need to order $\text{enq}(A), \text{enq}(B)$
- To order, need to know about the other

Choices

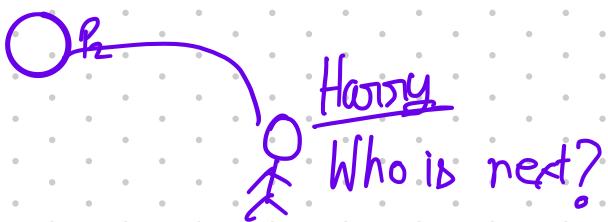
ALICE



Wait \Rightarrow Not available



[Not sure how long it will be]



— — —
Give up on linearizability

Replicated State Machines

- PROBLEM: How To Build A FAULT TOLERANT ???

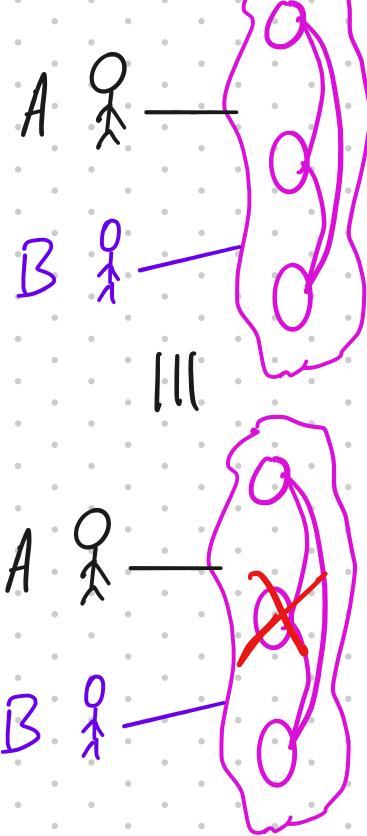
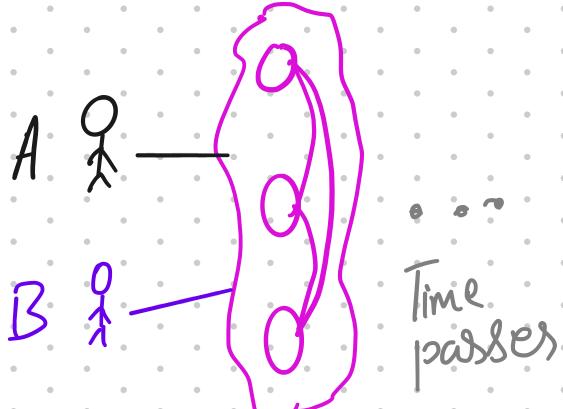
??? ≡ airline reservation system (Lamport)

Key value store (Chubby, Etcd, ...)

Database (...)

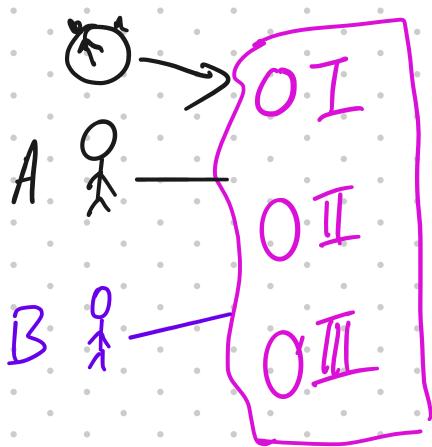
Ice cream stand (...)

What we want



Note: Many possible solutions BUT

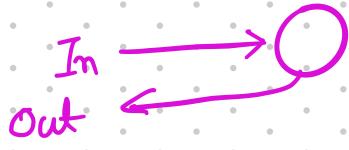
- Hard to design a correct one.
- So instead: identify a recipe.



Make sure I, II and III always have the same state. A behave identically

Same state

Behave identically \circ Deterministic



Out can depend on

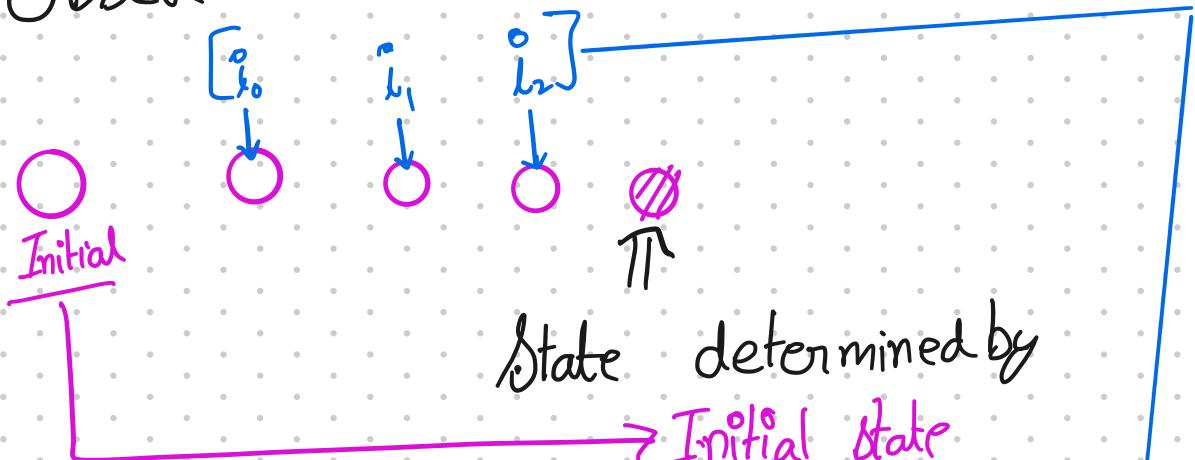
- Current state
- In

- No dependence on time
- No dependence on observation about the world
- No reading /dev/random \uparrow

$\Rightarrow \circ$

Assumed by nearly all fault tolerance mechanisms.

Observe

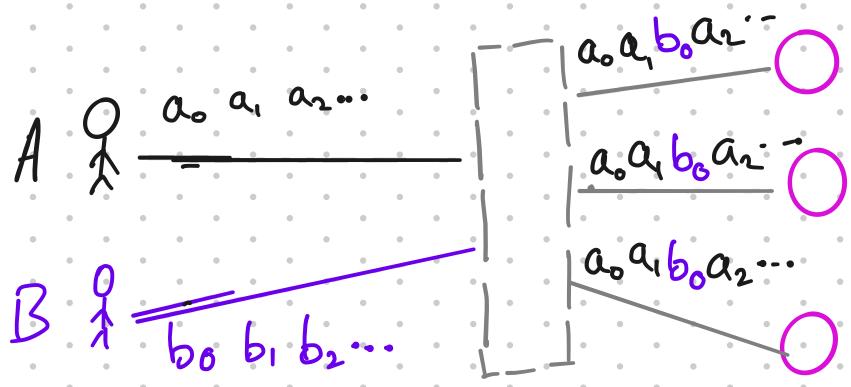


State determined by

Initial state

ORDER OF OPS? $[i_0, i_1, i_2]$

Leads to RSMs

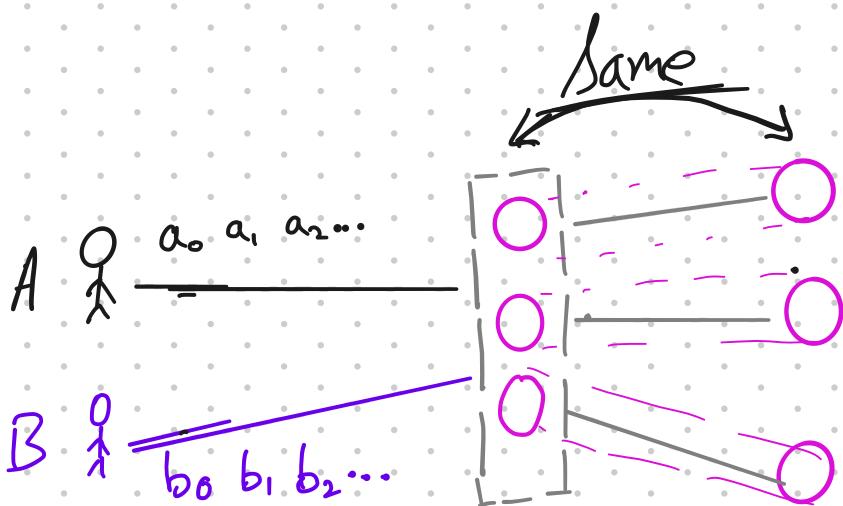


Two requirements

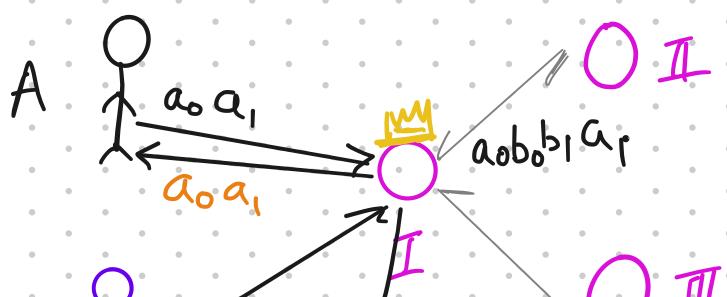
Agreement: All correct processes get the same set of requests (commands)

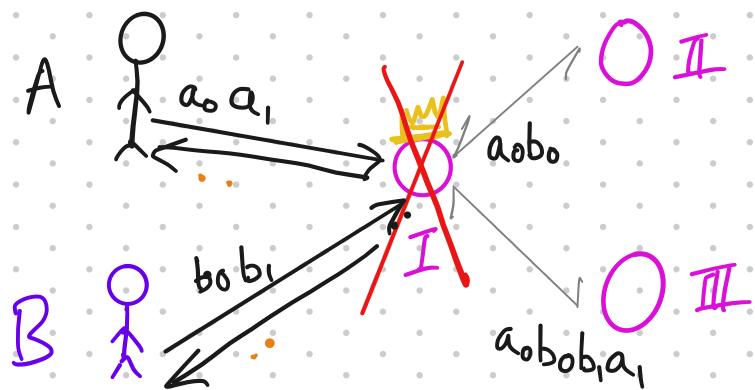
Ordering: All correct processes execute request in the same order.

The asynchronous model makes this hard!
Formally show this later in class



"Leader" based

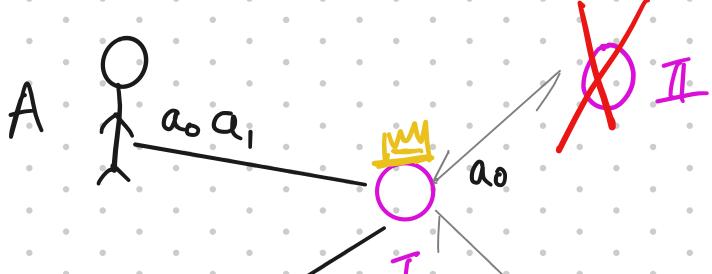




- How to detect leader has failed?
 - Time out

- Who becomes the next leader?
 - Req: At most one active leader.

Agree on leader





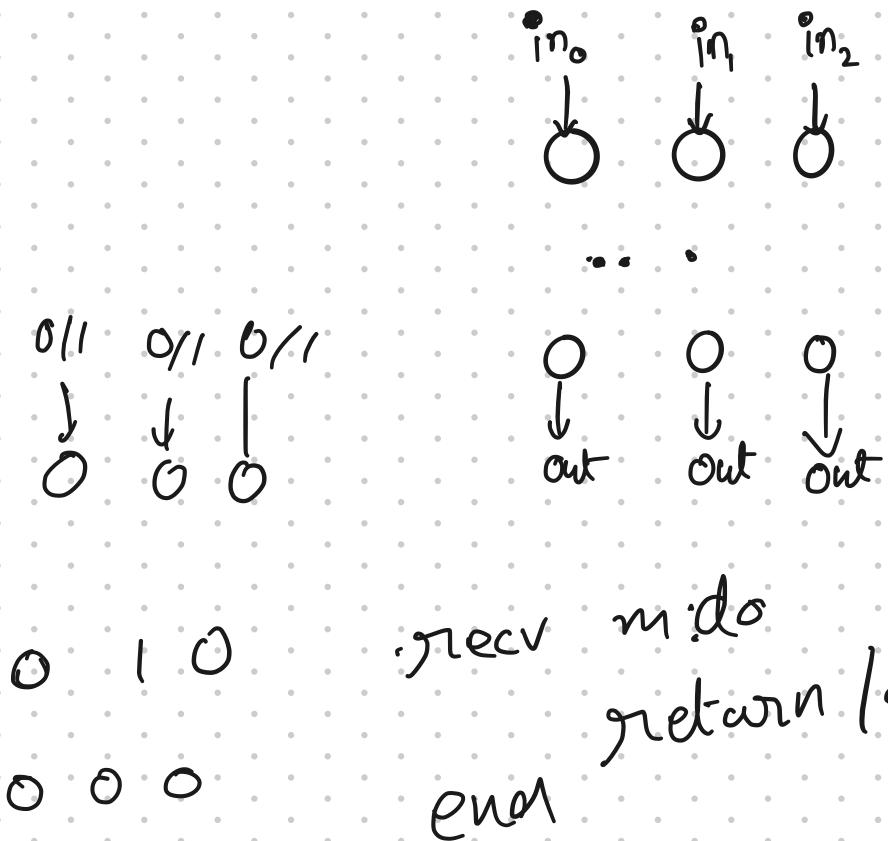
- When is it safe to execute request & return result?

↳ Commit Point

To recover
from
failure

When? Enough processes agree that they know command.

Agreement^o solved by CONSENSUS PROTOCOLS



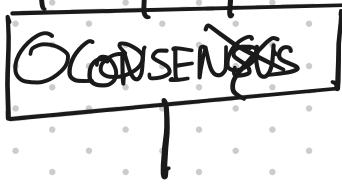
Agreement: If process
 $p \wedge q$ output $v_p \wedge v_q$
then $v_p = v_q$

Validity: If process p
outputs v_p then
 $v_p \in \{in_0, in_1, \dots\}$

```
recv m:do  
    return long all correct processes  
end
```

Termination: Eventually
output a decision

- Leader Election



- Sufficiently Replicated

(idx, π^{eq})

