

CS202 (-002) LECTURE 5

• LAST CLASS

- SHELL

- FILE DESCRIPTORS, FILES AS AN ABSTRACTION

- THREADS

↳ In response to a question after class

t1

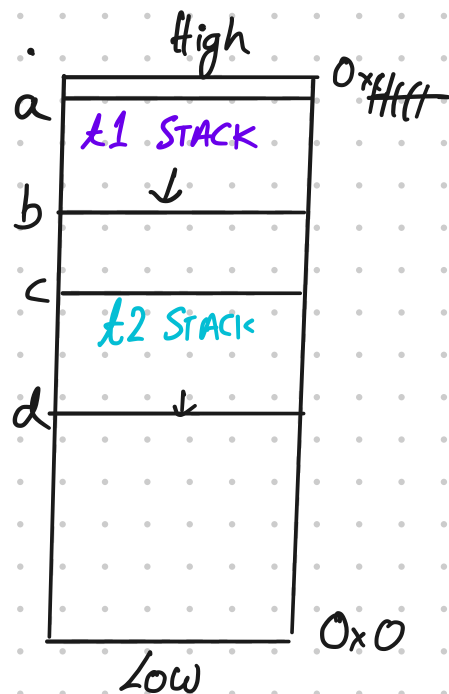
RBP

RSP

t2

RBP

RSP



(Figure 26.1 in last week's reading)

TODAY: CONCURRENCY.

How do threads affect program correctness.

```
uint64_t x = 3 ← GLOBAL  
int main (...) {
```

```
    ...  
    tid1 = thread_create(t1, NULL);  
    tid2 = thread_create(t2, NULL);  
    thread_join(tid1); thread_join(tid2);  
    ← What is the value of x?
```

}

t1

t2

```
void t1(void*) {
```

① $x = x * 2;$

② $x = x + 7$
thread-exit();

}

```
void t2(void*) {
```

① $x = x + 6;$

② $x = x * 3;$
thread-exit();

}

a

6

i

12

b

19

ii

57

i

9

a

18

b

25

ii

75

i

9

a

18

ii

54

b

61

Observe: ① x can take many different final values
→ Contrast with

```
int main(...) {
```

t1();

t2();

}

② Accesses from different threads
can interleave.

head = NULL

t1

insert(1);

t2

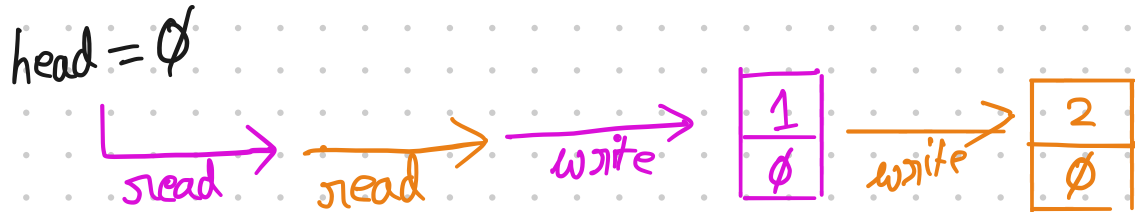
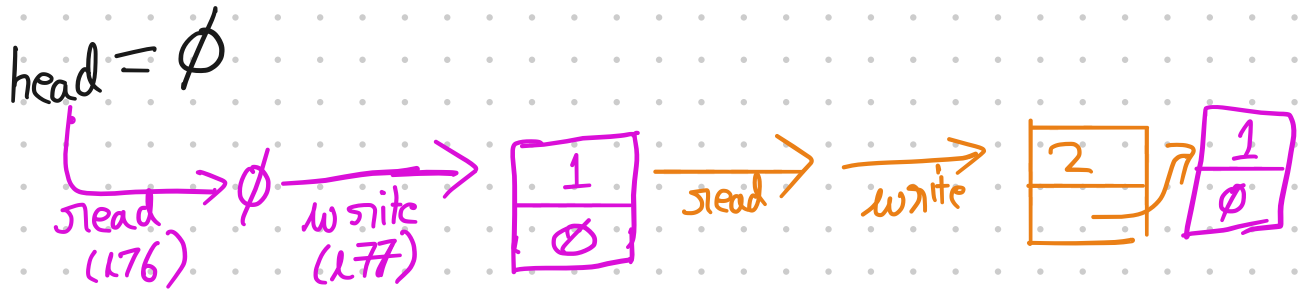
insert(2);

```
66 struct List_elem {
67     int data;
68     struct List_elem* next;
69 };
70
71 List_elem* head = 0;
72
73 insert(int data) {
74     List_elem* l = new List_elem;
```

```

75     l->data = data;
76     l->next = head;
77     head = l;
78 }

```



...

© Not all interleavings are safe/correct.

```

66 struct List_elem {
67     int data;
68     struct List_elem* next;
69 };
70
71 List_elem* head = 0;
72
73 insert(int data) {
74     List_elem* l = new List_elem;
75     l->data = data;
76     l->next = head;
77     head = l;
78 }

```

Don't want another thread to read or write to head b/w line 76 & 77

Should be Atomic

- Synchronization primitives

↳ Tools to control interleaving

↳ Limit concurrent Actions.

CRITICAL SECTION

- A way to implement/get atomicity

Three properties

- MUTUAL EXCLUSION: AT MOST ONE THREAD IS EXECUTING LOGIC IN CRIT. SECTION AT A TIME.

f() {
 print(beep)

- }
- PROGRESS
 - BOUNDED WAITING
- } see notes.

How to implement critical sections?

- Mutex

- mutex-init
- mutex-lock
- mutex-unlock

Book

pthread_mutex_init
pthread_mutex_lock
pthread_mutex_unlock

```
66 struct List_elem {  
67     int data;  
68     struct List_elem* next;  
69 };  
70  
71 List_elem* head = 0;  
72  
73 insert(int data) {  
74     List_elem* l = new List_elem;  
75     l->data = data;  
76     l->next = head;  
77     head = l;  
78 }
```

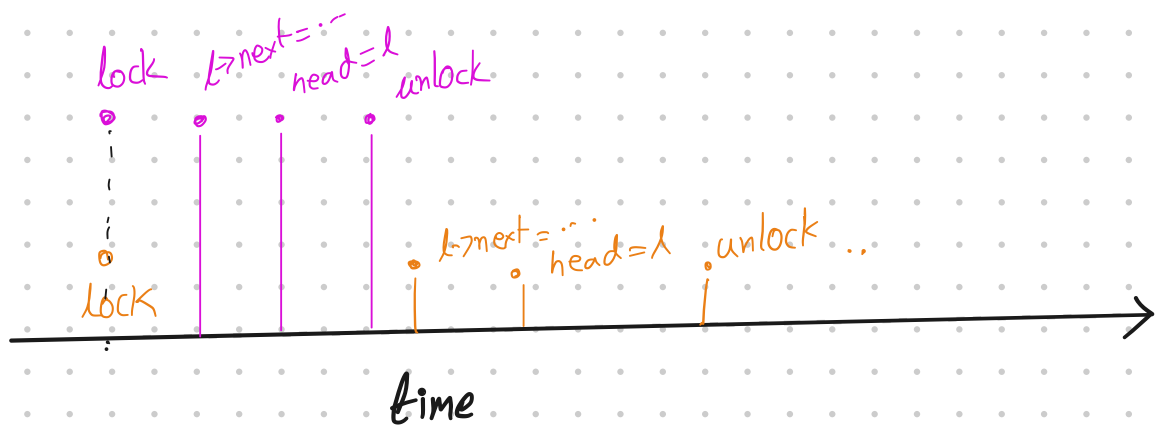
mutex-t m;

mutex-lock(&m);

mutex-unlock(&m);

WARNING: ILLUSTRATIVE, LATER LECTURE WILL SUGGEST
A DIFFERENT STYLE THAT YOU MUST FOLLOW!

t1 | t2
 insert(1); | insert(2);



Semantics

- When mutex-lock returns caller holds the lock
- Locks can be granted to waiting threads in ANY order

TIME
 ↓

t1: lock(L)
 t1: CRIT SEC
 t2: lock(L)
 t3: lock(L)
 t1: unlock(L)
 t3: CRIT SEC

t1: lock(L)
 t1: CRIT SEC
 t2: lock(L)
 t3: lock(L)
 t1: unlock(L)
 t2: CRIT SEC

NEED TO BE CAREFUL ABOUT WHAT LOCK YOU USE FOR A CRIT SECTION

```

68 int data;
69 struct List_elem* next;
70 };
71 List_elem* head = 0;
72
73 insert(int data) {
74     List_elem* l = new List_elem;
75     l->data = data;
76     l->next = head;
77     head = l;
78 }

```

mutex-t m;

mutex-lock(&m);

mutex-unlock(&m);

mutex_t m2;

int remove() {

int ret = 0;

mutex_lock(&m2);

if (head != NULL) {

ret = head->data;

head = head->next;

}

mutex_unlock(&m2);

return ret;

}

Is the list
still correct?

insert(List_elem* hd, data)
remove(hd, data)

int main(...)

List_elem* hd;
thread_create(&t1, &hd)

Will reinforce this over the next several lectures, but



WHEN USING SYNCH. PRIMITIVES (locks, cond vars, ...) KEEP
TRACK OF WHAT DATA THEY ARE ASSOCIATED WITH

↳ Variables/structs/...

CONDITION VARIABLES

m,

x = []

t1

t2

- wait until
 $x \geq 15$
- PRINT PROGRESS
- $x = 0$

```
while (true) {
    Do Work.
    x++;
}
```

(a) Need to protect x with a lock. Why?

(b) Ideally, want a way to notify t_1 only
when $x \geq 15$.

↳ CONDITION VARIABLES!

- `cond-init (cond*, ...)`
- `cond-wait (mutex *m, cond *c)`
- `cond-signal (mutex *m, cond *c)`
- `cond-broadcast (mutex *m, cond *c)`

t_1

`mutex_lock(&m)`

- Check x

`getm → cond-wait(&m, &c)`

`lock(m)`

t_2

`mutex_lock(&m)`
`cond-bcast(&m, &c)`

`mutex_unlock(&m)`

→ xcm.

