

## Notes on Kruskal's Algorithm for Minimal Spanning Tree

In Kruskal's algorithm (§23.2) the edges are ordered  $e_1, \dots, e_E$  by of weight and  $e_i$  is added to the tree if and only if its addition does not cause a cycle. The data structure that does this efficiently is covered in detail in Chapter 21, which we are not covering. Instead, these notes give a specific implementation of the algorithm. Assume the edges have already been ordered by weight and  $x_i, y_i$  are the vertices of  $e_i$ . To each vertex  $x$  we have functions  $\pi(x)$  and  $SIZE(x)$ , initially all  $\pi(x) \leftarrow x$  and all  $SIZE(x) \leftarrow 1$ .

FOR  $i = 1$  to  $E$  we set (for notational convenience)  $x \leftarrow x_i, y \leftarrow y_i$  and do the following:

WHILE  $\pi(x) \neq x$

$x \leftarrow \pi(x)$  (\*sliding down the bannister\*)

(\*  $x$  now at root for the component of the original  $x$  \*)

WHILE  $\pi(y) \neq y$

$y \leftarrow \pi(y)$  (\*sliding down the bannister\*)

(\* ditto  $y$  \*)

IF  $x \neq y$  (\* else reject \*) then DO

IF  $SIZE(x) \leq SIZE(y)$  then DO

$\pi(x) \leftarrow y$

$SIZE(y) \leftarrow SIZE(y) + SIZE(x)$

OTHERWISE (\*  $x$  component bigger \*) DO

$\pi(y) \leftarrow x$

$SIZE(x) \leftarrow SIZE(x) + SIZE(y)$

Add  $e_i$  to Minimal Spanning Tree

At any time the  $\pi(x)$  will give a rooted forest with  $\pi(x) = x$  exactly when  $x$  is a root. In that case  $SIZE(x)$  will be the size of the forest. Certain edges will have already been put in the Minimal Spanning Tree so that the structure will be a forest. That forest and the forest given by  $\pi(x)$  will have the same components (though they may have different edges).

Example.  $e_1 = (a, c), e_2 = (c, b), e_3 = (d, e), e_4 = (a, d), e_5 = (b, d)$ . With  $i = 1$  we add  $e_1$  to tree,  $\pi(a) \leftarrow c$  and  $SIZE(c) \leftarrow 2$ . With  $i = 2$  we add  $e_2$  to tree, as  $SIZE(c) > SIZE(b)$  we set  $\pi(b) \leftarrow c$  and  $SIZE(c) \leftarrow 3$ . With  $i = 3$  we add  $e_3$  to tree,  $\pi(d) \leftarrow e$  and  $SIZE(e) \leftarrow 2$ . Now  $i = 4$  so  $x \leftarrow a; y \leftarrow d$ . The WHILE parts trace  $x$  down to its root  $c$  and  $y$  down to its root  $e$ . As  $SIZE(c) > SIZE(e)$  we set  $\pi(e) \leftarrow c, SIZE(c) \leftarrow 5$  and add  $e_4$  to the tree. Note that the current state of the Minimal Spanning Tree and the forest given by  $\pi$  have different edges but the same components.

Now with  $i = 5$ ,  $x \leftarrow b$ ;  $y \leftarrow e$ . Both  $x, y$  trace down with the WHILE loops to the same  $c$  so we do nothing and  $e_5$  is not added to the tree.

To analyze the time we note that the process is done  $E$  times, so we analyze the process with a particular  $x = x_i, y = y_i$ . The key aspect to the time is we must iterate  $\pi(x) \leftarrow x$  until reaching a root. (Similarly for  $y$ .) At first blush, this seems like it might take time  $V$ . ( $V$  is number of vertices.) *However*, here we use the fact that when we earlier considered an edge  $x, y$  and we moved them down to their roots we then reset  $\pi(x) \leftarrow y$  where  $SIZE[y]$  had been bigger than  $SIZE[x]$ . Now the new  $SIZE[y]$  became the old  $SIZE[x] + SIZE[y]$ . That is, the new  $SIZE[y]$  is at least double the old  $SIZE[x]$ . As  $x$  is no longer a root its value of  $SIZE[x]$  will never change. The value of  $SIZE[y]$  may change later, but it can only get larger. Hence we will have  $2 \cdot SIZE[x] \leq SIZE[y]$  forevermore. Therefore, as we look at a path  $x, \pi(x), \pi(\pi(x)), \dots$  the value  $SIZE(\cdot)$  at least doubles each iteration. Therefore the path can only be of length  $\log V$ . This is a big savings over the length  $V$  without this aspect. Now the process with a particular  $x, y$  takes time  $O(\log V)$  and therefore the total time is  $O(E \log V)$ .

**Path Compression:** (This is extra material and **not** on the final!) Before we move “down the bannister” we save, temporarily, the original value of  $x$ . (same for  $y$ ) with

*originalx*  $\leftarrow x$

Then we go “down the bannister” to the new value of  $x$ . Now we go back up to *originalx* and reset the entire path to arrow the new  $x$ :

$z \leftarrow \textit{originalx}$

$\pi[z] \leftarrow x$

WHILE  $\pi[z] \neq z$

$\pi[z] \leftarrow x$

$z \leftarrow \pi[z]$

That is, the entire path from *originalx* to  $x$  is now pointing directly to  $x$ . This has effectively doubled the time, as we go down the WHILE loop twice. However, when later in the program we have a WHILE loop that hits *originalx* it will jump directly to  $x$ . That is, the path has been *compressed*. Analysis of path compression is remarkably subtle (mathematicians love it!) but lets just say that it gives an improved running time for MST when  $n$  is *really really really* large.