# Lecture 2: Absorbing states in Markov chains. Mean time to absorption. Wright-Fisher Model. Moran Model. 

Antonina Mitrofanova, NYU, department of Computer Science

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## 1 Higher Order Transition Probabilities

Very often we are interested in a probability of going from state $i$ to state $j$ in $n$ steps, which we denote as $p_{i j}^{(n)}$. For example, the probability of going from the state $i$ to state $j$ in two steps is:

$$
p_{i j}^{(2)}=\sum_{k} p_{i k} p_{k j}
$$

where $k$ is the set of all possible states. In other words it consists of probabilities of going from state $i$ to any other possible state (in one step) and then going from that step to $j$. Interestingly, the probability $p_{i j}^{(2)}$ corresponds to $(i, j)$ 'th entry in the matrix

$$
P^{2}=P \times P
$$

Similarly, going from $i$ to $j$ in $n$ steps is defined as

$$
p_{i j}^{(n)}=\sum_{k} p_{i k} p_{k j}^{(n-1)}=\sum_{k} p_{i k}^{(n-1)} p_{k j}
$$

and correspond to the $(i, j)^{\prime}$ th entry in $P^{n}$ matrix (therefore we can compute transition probabilities by taking matrix powers).

We define the $n$-step transition probabilities for the Markov Chain by

$$
P\left[X_{n}=j \mid X_{0}=i\right]
$$

Since we know that

$$
P\left[X_{n+1}=k_{1}, \ldots X_{n+m}=k_{m} \mid X_{n}=i\right]=P\left[X_{1}=k_{1}, \ldots, X_{m}=k_{m} \mid X_{0}=i\right]
$$

then

$$
P\left[X_{n}=j \mid X_{0}=i\right]=p\left[X_{n+m}=j \mid X_{m}=i\right]
$$

In other words, the probability that a path started at $i$ and ended at $j$ does not depend on the time at which it is initiated. Therefore

$$
p_{i j}^{(n)}=P\left[X_{n}=j \mid X_{0}=i\right]
$$

We can also write

$$
p_{i j}^{(n+m)}=\sum_{k} p_{i k}^{(n)} p_{k j}^{(m)}
$$

which is also called Chapman-Kolmogorov equation.
It follows that we can compute a uniconditional probability (of $X_{n}$ taking a value of $j$ )as

$$
P\left[X_{n}=j\right]=p_{j}^{(n)}=\sum_{i} p_{i} p_{i j}^{(n)}
$$

Frequently we are interested in the time the system goes from some initial state to some terminal critical state, called absorbing state.

## 2 Absorption Probabilities

The state $i$ is called absorbing if $p_{i i}=1$. In other words, once the system hits state $i$, it stays there forever not being able to escape.

The most interesting absorbing states which arise in population genetics are at $i=0$ and at $i=M$. Let us assume the population of 2 N haploids, each having either allele $A_{1}$ or allele $A_{2}$. In this case $M=2 N$. And let $X$ be a random variable which describes the frequency of allele $A_{1}$ in a given population. In population genetics, it is of interest to find out how fast the allele will go to either absorption state $(i=0$ or $i=2 N)$ given that the population started with $i$ alleles $A_{1}$.

Many functionals (including absorption probabilities) on Markov Chain are evaluated by a technique called first step analysis. This method proceeds by the analyzing the possibilities that can arise at the end of the first transition.

Let us now fix $k$ as absorbing state. The probability of absorption in this state depends on the initial state $X_{0}=i$. Let us define $U_{i k}$ as the probability of eventually reaching state $k$ given that we started in state $i$. First possibility would be to go from state $X_{0}=i$ to $X_{1}=k$ immediately, which is described by $p_{i k}$. However, if the state $k$ is not entered at $X_{1}$, then we must go to some other state $j \neq k$. Once we enter state $j$, the probability of ultimate absorption in $k$ is $U_{j k}$ by definition. Weighting all the possibilities gives

$$
\begin{equation*}
U_{i k}=p_{i k}+\sum_{j=0 \& j \neq k}^{M} p_{i j} U_{j k}=\sum_{j=0}^{M} p_{i j} U_{j k} \tag{1.1}
\end{equation*}
$$

since $U_{k k}=1$.
If we write $u_{i}$ as the probability of absorption (say, in 2 N ), then we write

$$
\begin{equation*}
u_{i}=\sum_{j=0}^{M} p_{i j} u_{j} \tag{1.2}
\end{equation*}
$$

## 3 Mean time until absorption

It is more difficult to assess the properties of the (random) time until absorption. However, it is common to evaluate the mean time until X reaches 0 or $2 N$ starting from $i$ (it is called mean absorption time).

We wish to make a calculation of a mean time until absorption for a general starting point $i$. We now introduce a concept, which is central in calculating the mean absorption time: Let us observe that starting from $i$ the system will visit state $j$ some number of times before absorption. This fact it true for all $j$ (except 0 and 2 N ). Therefore, if we know the number of times the system visits state $j$ (for all $j$ ) before absorption, then we can obtain an average time until absorption by summing up over average times the system is in a specific state, for each state.

Let us now formally define mean number of times that $X$ takes the value $j$ before absorbtion in 0 or $2 N$ (given that it started in $i$ ) as $\left\{\bar{t}_{i j}\right\}$. Then the mean time to absorption given that we started at state $i$ is the sum:

$$
\bar{t}_{i}=\sum_{j=1}^{M-1} \bar{t}_{i j}
$$

We will proceed by a first step analysis: if the system starts at $i$ and then proceeds to $k$ at its next step, then the mean number of visits to state $j$ prior to absorption starting from state $k$ now is $\left\{\bar{t}_{k j}\right\}$ by definition. However, observe that in this case, we miss the case when $i=j$. Therefore, there is a need to define an additional variable $\delta_{i j}=1$ if $i=j$, and 0 otherwise. As a result, weighting by the probability of going to a state $k$ at the first step, we obtain

$$
\bar{t}_{i j}=\sum_{k=0}^{M} p_{i k} \bar{t}_{k j}+\delta_{i j}, \quad \bar{t}_{0 j}=\bar{t}_{M j}=0
$$

By summing up the meant times the system is in state $j$ for all $j$, we obtain

$$
\sum_{j=1}^{M-1} \bar{t}_{i j}=\sum_{j=1}^{M-1} \sum_{k=0}^{M} p_{i k} \bar{t}_{k j}+\sum_{j=1}^{M-1} \delta_{i j}
$$

By definition $\sum_{j=1}^{M-1} \bar{t}_{i j}=\bar{t}_{i}$ so that

$$
\bar{t}_{i}=\sum_{k=0}^{M} p_{i k} \bar{t}_{k}+1, \quad \bar{t}_{0}=\bar{t}_{M}=0
$$

Observe that since $\sum_{j=1}^{M-1} \delta_{i j}$ will equal to 1 only once (when $i=j$ ), then $\sum_{j=1}^{M-1} \delta_{i j}=1$ in the above equation.

Now, we will discuss two most important models in population genetics, which describe the evolution of allele frequencies: Wright-Fisher model and Moran model.

## 4 Wright-Fisher Model

Let us assume a simple haploid model of the population of 2 N genes (or alternatively -N diploid organisms) of random reproduction, with each haploid possessing either allele $A_{1}$ or allele $A_{2}$. Let us, for start, disregard mutation pressures and selective forces. At every time-step, each gene (allele) gives birth to some number of offsprings (which are the exact copies of himself) and dies immediately after that, thus living only one generation. This process describes how the genes get transmitted from one generation to the next. However, the processed of birth and death will have to remain unseen behind the curtain for a moment. Instead, we will only observe how the frequency of alleles will change from generation to generation. ${ }^{1}$

We will fix our attention at frequency of allele $A_{1}$ in the population of $2 N$ haploids. Let us think of this process of going from one generation to the other as a Markov Chain, where the state $X$ of the chain corresponds to the number of haploids (genes) of type $A_{1}$. Clearly, in any generation $X$ takes one of the values $0,1, \ldots, 2 N$, which constitutes a state space. We will denote the value taken by $X$ in generation $t$ as $X_{t}$.

The model assumes that genes for the generation $t+1$ are derived by sampling with replacement from the genes of generation $t$. Thus, the make up of the next generation is determined by $2 N$ independent Bernoulli trials so that $X_{t}$ is a binomial random variable. Let the initial generation consist of $i$ genes of type $A_{1}$ and $2 N-i$ genes of type $A_{2}$. Then we define a probability of success (resulting in allele $A_{1}$ ) $p_{i}$ and a probability of failure $q_{i}$ (resulting in allele $A_{2}$ ) for each Bernoulli trial as

$$
p_{i}=\frac{i}{2 N} \quad q_{i}=1-\frac{i}{2 N}
$$

We generate a Markov Chain $\left\{X_{n}\right\}$, where $X_{n}$ is the number of $A_{1}$ genes in the n'th generation, among a constant population size of 2 N individuals. Basically, $X_{t+1}$ is a binomial random variable with index 2 N and parameter (probability of success) $X_{t} / 2 N$. Observe that the transition probabilities from $X_{t}=i$ to $X_{t+1}=j$ for this Markov Chain are computed according to the binomial distribution as

$$
P\left(X_{t+1}=j \mid X_{t}=i\right)=p_{i j}=\binom{2 N}{j} p_{i}^{j} q_{i}^{2 N-j}=\binom{2 N}{j}(i / 2 N)^{j}\{1-(i / 2 N)\}^{2 N-j}
$$

Observe now that states 0 and 2 N are completely absorbing. In other words, no matter what the value of $X_{0}$ is, eventually $X_{t}$ will take the value 0 or $2 N$. And once this happens, $X$ will stay in that state forever. In the case of $X_{t}=0$, the population will consist only of $A_{2}$ genes, while in the case of $X_{t}=2 N$ the population will be purely $A_{1}$-gene population.

[^0]
### 4.1 Absorption probability in Wright-Fisher model

Let us discuss absorption probabilities in Wright-Fisher model. In fact, the population can attain fixation and be composed of only $A_{1}$-genes ( $X_{t}=2 N$ ) or $A_{2}$-genes ( $X_{t}=0$ ). It can be shown that with probability one, either of the absorbing states (either 0 or 2 N ) is eventually entered (and this is true for both Wright-Fisher and Moran models). And therefore $\lim _{t \rightarrow \infty} P\left(X_{t}=j\right)=0$.

We will discuss two cases of absorption: at 0 and at 2 N .

### 4.1.1 Absorption at zero:

We write the probability of extinction (absorption at 0 ) of a gene given that it started with $i$ copies as $\lim _{n \rightarrow \infty} P\left(X_{n}=\right.$ $0 \mid X_{0}=i$ )

Let us find the probability of absorbing in state 0 by using $E\left(X_{n}\right)$. We express $E\left(X_{n}\right)$ by using the expectation of a conditional expectation

$$
E\left(X_{n}\right)=E\left[E\left(X_{n} \mid X_{n-1}\right)\right]=E\left(X_{n-1}\right)=E\left(X_{n-2}\right)=\cdots=E\left(X_{0}\right)=i
$$

This property is called the constancy of expectation (and is also true for Moran model). Further we can write $E\left(X_{n}\right)$ as

$$
E\left(X_{n}\right)=0 \times u_{i, 0}+2 N \times\left(1-u_{i, 0}\right)
$$

Now, since $\lim _{n \rightarrow \infty} E\left(X_{n}\right)=i$,

$$
i=0 \times u_{i, 0}+2 N \times\left(1-u_{i, 0}\right)
$$

and therefore

$$
u_{i, 0}=\frac{2 N-i}{2 N}
$$

Observe that we ignore $P\left(X_{t}=j\right)$ since they are equal to zero as n goes to infinity.

### 4.1.2 Absorption at 2N:

We want to calculate probability that $A_{1}$ eventually becomes fixed in the population (absorption at 2 N ) and follow a similar argument:

$$
i=0 \times\left(1-u_{i, 2 N}\right)+2 N \times u_{i, 2 N}
$$

so that

$$
u_{i, 2 N}=\frac{i}{2 N}
$$

A different argument (which is more relevant to a genetical point of view) is that eventually every gene in the population is descended from the unique gene in generation zero. The probability that such a gene (allele) is $A_{1}$ is simply the initial fraction of $A_{1}$ alleles, namely $i / 2 N$, and this also must be a fixation probability of allele $A_{1}$.

### 4.1.3 Absorption starting with one $A_{1}$ allele

Suppose that in a population of pure $A_{2}$ alleles a single new mutant $A_{1}$ allele (gene) arises. There are no more new mutations and therefore we can assume that we start with a population with one $A_{1}$ allele and $2 N-1 A_{2}$ alleles. According to the previous result, the probability of fixation for this allele is

$$
u_{1,2 N}=\frac{i}{2 N}=\frac{1}{2 N}
$$

. On the other hand, the probability that the allele is lost is $1-1 / 2 N$.

### 4.2 Mean time until absorption in Wright-Fisher model

The calculation of the mean time until absorption for the Wright-Fisher model is very computationally expensive. Therefore, it is useful to approximate this quantity, which will be described in the next section. However, it is relatively simple to derive the mean time until absorption starting with one allele of type $A_{1}$ (before the mutant is lost or before the mutant is fixed).

For this calculation we use the same analysis as before. We will use the expected number of visits to a state $j$ along the path to absorption, starting from state $X_{0}=1$. We denote the mean number of generations to absorption in 0 or 2 N , given that we started with one allele $A_{1}$, as $\bar{t}_{1}$. We need to sum up the expected number of such visits for all $j$, avoiding states 0 and $2 N$ :

$$
\bar{t}_{1}=\sum_{j=1}^{2 N-1} \bar{t}_{1, j}
$$

where $\bar{t}_{1, j}$ is the mean number of times when the number of $A_{1}$ alleles takes the value of $j$ (system is in state $j$ ) before reaching either 0 or $2 N$. Both Fisher and Wright found that

$$
\bar{t}_{1, j} \approx \frac{2}{j}
$$

starting at $i=1$. Since $\sum_{i=1}^{N} \frac{1}{i}=\log (N)+\gamma$ where $\gamma$ is a Euler's constant ( $0.5772 \ldots$ ), we derive

$$
\begin{gathered}
\bar{t}_{1}=\sum_{j=1}^{2 N-1} \bar{t}_{1, j}=\sum_{j=1}^{2 N-1} \frac{2}{j}=2 \sum_{j=1}^{2 N-1} \frac{1}{j} \\
=2(\log (2 N-1)+\gamma)
\end{gathered}
$$

### 4.3 Approximating Mean Time until Absorption

Even though in principle we can find solutions of the mean time to absorption for a general $i$, in practice these solutions seem extremely difficult, and simple expressions for these mean times have not yet been found. Let us now present a simple approximation for $\bar{t}_{i}$. We again apply the first step analysis, where we start from state $i$ and in the first step attend some intermediate step $k$. We define $M=2 N, i / M=x, k / M=x+\delta x$, and $\bar{t}_{i}=\bar{t}(x)$.

Then we can rewrite the equation

$$
\bar{t}_{i}=\sum_{k=0}^{M} p_{i k} \bar{t}_{k}+1
$$

as

$$
\begin{align*}
\bar{t}(x) & =\sum P\{x \rightarrow x+\delta x\} \bar{t}(x+\delta x)+1  \tag{1}\\
& =E\{\bar{t}(x+\delta x)\}+1 \tag{2}
\end{align*}
$$

Now assuming that $\bar{t}(x)$ is a twice differentiable function of a continuous variable $x$, we can use Taylor series to approximate the above quantity. The Taylor series states that

$$
\begin{align*}
f(y) & =\sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!}(y-a)^{n}  \tag{4}\\
& =\frac{f(a)}{0!}(y-a)^{0}+\frac{\{f(a)\}^{\prime}}{1!}(y-a)^{1}+\frac{\{f(a)\}^{\prime \prime}}{2!}(y-a)^{2}+\ldots  \tag{5}\\
& =f(a)+\{f(a)\}^{\prime}(y-a)+\frac{1}{2}\{f(a)\}^{\prime \prime}(y-a)^{2}+\ldots, \tag{6}
\end{align*}
$$

We re-write $\bar{t}(x)$ by applying Taylor's series (showing three leading terms):

$$
\begin{align*}
\bar{t}(x) & =E\{\bar{t}(x+\delta x)\}+1  \tag{7}\\
& \approx \bar{t}(x)+E(\delta x)\{\bar{t}(x)\}^{\prime}+\frac{1}{2} E(\delta x)^{2}\{\bar{t}(x)\}^{\prime \prime}+1 \tag{8}
\end{align*}
$$

All expectations are conditional on $x$. Using the fact that the expectation of the binomial random variable is $E(Y)=n p$, we can rewrite then

$$
E(x+\delta x)=E(j / M)=\frac{E(j)}{M}=\frac{M \times \frac{i}{M}}{M}=\frac{i}{M}
$$

, where $p=\frac{i}{M}$. We can as well use the fact established before that $E\left(X_{n} \mid X_{n-1}=i\right)=i$. At the same time $x=\frac{i}{M}$ and $E(x)=x$; therefore $E(\delta x)=0$. As a result the term $E(\delta x)\{\bar{t}(x)\}^{\prime}=0$.

Let us calculate $E(\delta x)^{2}$. In our case, the $E(\delta x)^{2}=\operatorname{Var}(\delta x)$ since $\operatorname{Var}(\delta x)=E(\delta x)^{2}-[E(\delta x)]^{2}$ and $[E(\delta x)]^{2}=0$, as shown from the previous result.

The variance of the binomial random variable

$$
\operatorname{Var}(x+\delta x)=\operatorname{Var}(j / 2 N)=\frac{\operatorname{Var}(j)}{4 N^{2}}=\frac{2 N \frac{i}{2 N}\left(1-\frac{i}{2 N}\right)}{4 N^{2}}=\frac{x(1-x)}{2 N}
$$

The above gives

$$
\begin{aligned}
\bar{t}(x) \approx & \bar{t}(x)+\frac{1}{2} \frac{x(1-x)}{2 N}\{\bar{t}(x)\}^{\prime \prime}+1 \\
& -1 \approx \frac{1}{2} \frac{x(1-x)}{2 N}\{\bar{t}(x)\}^{\prime \prime} \\
& -4 N \approx x(1-x)\{\bar{t}(x)\}^{\prime \prime}
\end{aligned}
$$

The solution to this equation, subject to the boundary conditions $\bar{t}(0)=\bar{t}(1)=0$ is

$$
\begin{align*}
\bar{t}(x) & =\iint-4 N \frac{1}{x(1-x)}  \tag{10}\\
& =-4 N \iint \frac{1}{x(1-x)}  \tag{11}\\
& =-4 N \iint\left(\frac{1}{x}+\frac{1}{1-x}\right)  \tag{12}\\
& =-4 N \int\left(\int \frac{1}{x}+\int \frac{1}{1-x}\right)  \tag{13}\\
& =-4 N \int(\ln (x)+\ln (1-x))  \tag{14}\\
& =-4 N\left\{\int \ln (x)+\int \ln (1-x)\right\}  \tag{15}\\
& =-4 N\{(x \ln (x)-x)+((1-x) \ln (1-x)-(1-x))\}  \tag{16}\\
& \approx-4 N\{x \log x+(1-x) \log (1-x)\} \tag{17}
\end{align*}
$$

where $x=\frac{i}{2 N}$, the initial frequency of allele $A_{1}$. This is also is called diffusion approximation to the mean absorption time.

When we initially start with one $A_{1}$ allele $x=\frac{1}{2 N}$, then the mean time to absorption is

$$
\begin{align*}
\bar{t}\left(\frac{1}{2 N}\right) & =-4 N\left\{\frac{1}{2 N} \log \left(\frac{1}{2 N}\right)+\left(1-\frac{1}{2 N}\right) \log \left(1-\frac{1}{2 N}\right)\right\}  \tag{18}\\
& \approx 2+2 \log 2 N \tag{19}
\end{align*}
$$

At the same time, when $x=\frac{1}{2}$, then

$$
\bar{t}\left(\frac{1}{2}\right) \approx 2.8 N
$$

Observe that for equal initial frequencies $\left(x=\frac{1}{2}\right)$, the mean time is relatively long.

## 5 Moran model

In each generation of the Moran model, one gene is chosen at random to give 2 offsprings and one gene is chosen to die (all other genes survive to the next generation). As opposed to Wright-Fisher model, Moran model has overlapping generations. This model is also known as a birth-and-death model. We still consider a constant population size of $2 N$ haploids, each of which has either allele $A_{1}$ or allele $A_{2}$. Let us (for now) ignore mutation or selection pressures.

Again, we define $X$ to be a random variable, which represents the number of alleles of type $A_{1}$ in the population. It is of interest to calculate transition probabilities for the implied Markov chain. Suppose that in population $t$ (which corresponds to state $X_{t}$ in underlying Markov chain) the number of alleles $A_{1}$ is $i$. Then in population $t+1$, the number of alleles $A_{1}$ can be either $(j=i-1),(j=i+1)$, or $j=i$.

The system can go from $i$ to $i-1$ if $A_{2}$ individual is chosen to give 2 offsprings and $A_{1}$ individual is chosen to die:

$$
p_{i, i-1}=\left(\frac{2 N-i}{2 N}\right)\left(\frac{i}{2 N}\right)
$$

To go from $i$ to $i+1$, the opposite should be true: $A_{2}$ is chosen to die and $A_{1}$ is chosen to reproduce:

$$
p_{i, i+1}=\left(\frac{2 N-i}{2 N}\right)\left(\frac{i}{2 N}\right)
$$

and for going from $i$ to $i$, it takes either $A_{1}$ to reproduce and die or $A_{2}$ to reproduce and die:

$$
p_{i, i}=\left(\frac{2 N-i}{2 N} \times \frac{2 N-i}{2 N}\right)+\left(\frac{i}{2 N} \times \frac{i}{2 N}\right)=\frac{i^{2}+(2 N-i)^{2}}{(2 N)^{2}}
$$

Observe that $p_{i j}=0$ for all other values of $j$ since it is impossible to make other transitions.

### 5.1 Properties of a Continuant matrix in Moran model.

In the case of Moran model, the transition probability matrix is Continuant, which means that $p_{i j}=0$ iff $|i-j|>1$. Now we can apply the standard Continuant matrix theory to our model so that the probability of fixation and mean time to absorption can be found explicitly.

In particular, we can use a "birth-and-death" process concepts to calculate the desired quantities. The birthdeath process is a special case of Continuous-time Markov process where the states represent the current size of a population and where the transitions are limited to births and deaths. When a birth occurs, the state $i$ goes to state $i+1$, defined by the birth rate $p_{i, i+1}=\lambda_{i}$. When the death occurs, the process goes from state $i$ to state $i-1$, defined by the death rate $p_{i, i-1}=\mu_{i}$.

For now, we will just use facts from the theory of birth-death processes, without proving them; however, we would like to return to formal definitions and proofs in one of the future lectures.

We define

$$
\rho_{i}=\frac{\mu_{1} \mu_{2} \ldots \mu_{i}}{\lambda_{1} \lambda_{2} \ldots \lambda_{i}}
$$

and $\rho_{0}=1$. If 0 and $M=2 N$ are both absorbing states, then the probability of absorption in either of them becomes

$$
u_{i}=\sum_{k=0}^{i-1} \rho_{k} / \sum_{k=0}^{M-1} \rho_{k}
$$

Proceeding further with the above argument, we can calculate the mean number of times the system is in state $j$ given that it started in state $i$ as

$$
\begin{gathered}
\bar{t}_{i j}=\frac{\left(1-u_{i}\right) \sum_{k=0}^{j-1} \rho_{k}}{\rho_{j-1} \mu_{j}},(j=1, \ldots, i) \\
\bar{t}_{i j}=\frac{u_{i} \sum_{k=j}^{M-1} \rho_{k}}{\rho_{j} \lambda_{j}},(j=i+1, \ldots, M-1)
\end{gathered}
$$

from this we can derive $\bar{t}_{i}$

$$
\bar{t}_{i}=\sum_{j=1}^{M-1} \bar{t}_{i j}=\sum_{j=1}^{i} \frac{\left(1-u_{i}\right) \sum_{k=0}^{j-1} \rho_{k}}{\rho_{j-1} \mu_{j}}+\sum_{j=i+1}^{M-1} \frac{u_{i} \sum_{k=j}^{M-1} \rho_{k}}{\rho_{j} \lambda_{j}}
$$

### 5.2 Probability of fixation in Moran model

Let us now observe that in the Moran model

$$
\lambda_{i}=\mu_{i}=i(2 N-i) /(2 N)^{2}
$$

so that

$$
\rho_{i}=\frac{\mu_{1}}{\lambda_{1}} \frac{\mu_{2}}{\lambda_{2}} \ldots \frac{\mu_{i}}{\lambda_{i}}=1
$$

for $i=0,1, \ldots, 2 N$. It can be shown that, similarly to Wright-Fisher model, $E\left(X_{t}\right)=i$.
Following all of the above, the probability of fixation (given that we started with $i$ copied of $A_{1}$ ) is

$$
u_{i}=\frac{i}{2 N}
$$

given that $M=2 N$.

### 5.3 Expected absorption time

Using the fact that $\rho_{i}=1$, we can derive the following
for $j=1, \ldots, i$

$$
\begin{align*}
\bar{t}_{i j} & =\frac{\left(1-u_{i}\right) \sum_{k=0}^{j-1} \rho_{k}}{\rho_{j-1} \mu_{j}}  \tag{21}\\
& =\frac{\left(1-\frac{i}{2 N}\right) \sum_{k=0}^{j-1} 1}{1 \frac{2 N-j}{2 N} \frac{j}{2 N}}  \tag{22}\\
& =\frac{\left(\frac{2 N-i}{2 N}\right) j \times 2 N \times 2 N}{(2 N-j) j}  \tag{23}\\
& =\frac{(2 N-i) \times 2 N}{2 N-j} \tag{24}
\end{align*}
$$

and for $j=i+1, \ldots, M-1$

$$
\begin{align*}
\bar{t}_{i j} & =\frac{u_{i} \sum_{k=j}^{M-1} \rho_{k}}{\rho_{j} \lambda_{j}}  \tag{25}\\
& =\frac{\frac{i}{2 N} \sum_{k=j}^{M-1} 1}{1 \frac{2 N-j}{2 N} \frac{j}{2 N}}  \tag{26}\\
& =\frac{\frac{i}{2 N}(2 N-j) \times 2 N \times 2 N}{(2 N-j) j}  \tag{27}\\
& =\frac{i \times 2 N}{j} \tag{28}
\end{align*}
$$

Now we can calculate the expected time to absorption as

$$
\begin{align*}
\bar{t}_{i} & =\sum_{j=1}^{M-1} \bar{t}_{i j}  \tag{30}\\
& =\sum_{j=1}^{i} \frac{\left(1-u_{i}\right) \sum_{k=0}^{j-1} \rho_{k}}{\rho_{j-1} \mu_{j}}+\sum_{j=i+1}^{M-1} \frac{u_{i} \sum_{k=j}^{M-1} \rho_{k}}{\rho_{j} \lambda_{j}}  \tag{31}\\
& =\sum_{j=1}^{i} \frac{(2 N-i) \times 2 N}{2 N-j}+\sum_{j=i+1}^{M-1} \frac{i \times 2 N}{j}  \tag{32}\\
& =(2 N-i) 2 N \sum_{j=1}^{i} \frac{1}{2 N-j}+2 N i \sum_{j=i+1}^{M-1} \frac{1}{j} \tag{33}
\end{align*}
$$

It is possible to condition on the fact that, say $A_{1}$ eventually fixes. In this case, it is not difficult to derive simpler expressions for mean absorption times. Such derivations will be discussed in the future lectures.

## References

[1] Warren Ewens, "mathematical Population Genetics", Second edition, 2004, pp 20-23, 86-91, 92-99, 104109.
[2] Howard Taylor and Samuel Karlin, "An Introduction to Stochastic Modeling", Third edition, 1998, pp 95138.
[3] Sidney Resnick, "Adventures in Stochastic Processes", 1992, pp72-116.


[^0]:    ${ }^{1}$ In this model, the allele frequency of the next generation is manipulated mainly by a genetic drift (a Genetic drift can be defined as a force that reduces heterozygosity by the random loss of alleles).

