

Runtime Environments

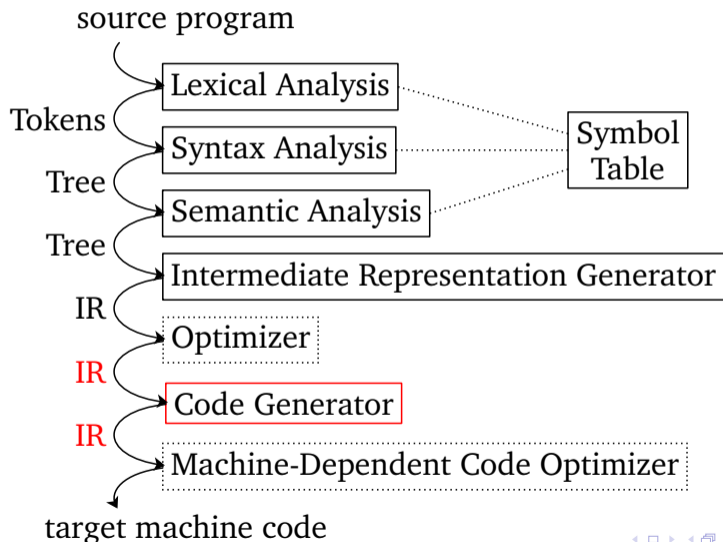
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Sixth compilation phase



Outline

- 1 Storage organization
- 2 Activation Trees
- 3 The Runtime Stack
- 4 The Runtime Heap



1 Storage organization

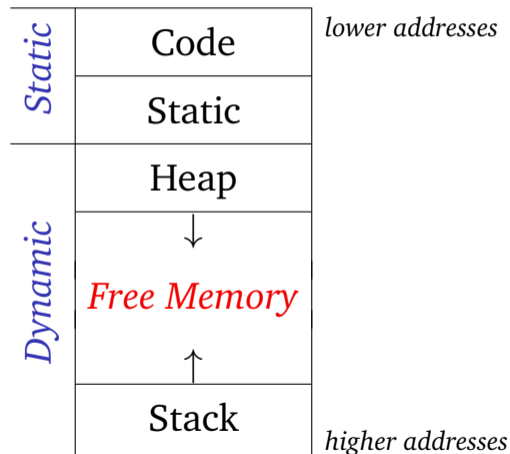
2 Activation Trees

3 The Runtime Stack

4 The Runtime Heap



Storage Organization



Storage Organization

Code area instructions, address ptrs.

Static area global constants, internalized strings.

Heap objects, records, arrays, variable strings.

Runtime stack activation records/stack frames.



1 Storage organization

2 Activation Trees

3 The Runtime Stack

4 The Runtime Heap



Activation trees

```
...
void quicksort(int m, int n){
    int i;
    if (n > m){
        i = partition(m,n); /* picks "quicksort separator value" */
        quicksort(m, i-1);
        quicksort(i+1, n);
    }

main() {
    readArray(); /* reads 9 integers into a[1],...,a[9] */
    ... /* sets sentenials a[0], a[10] */
    quicksort(1,9);
}
```



Activation trees

Figure 7.4 (p.433):

*Show activation tree, and
show live activations when control is with quicksort(2,3)*



- 1 Storage organization
- 2 Activation Trees
- 3 The Runtime Stack**
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The stack

Consider the (pseudo) program:

```
main = f(); g()    /* where f and g are procedures
```

```
f= if ... then f() else g()
```

```
g= (...)
```

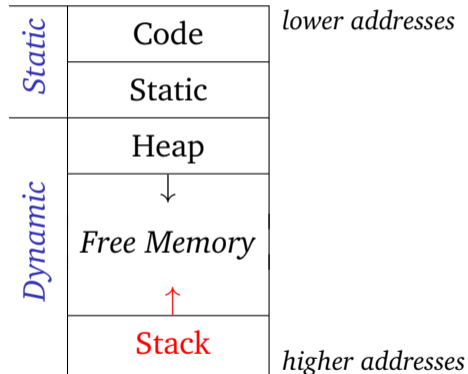


The stack

*Show all states of runtime stack activations during execution.
Compare with live activations in associated activation tree.*

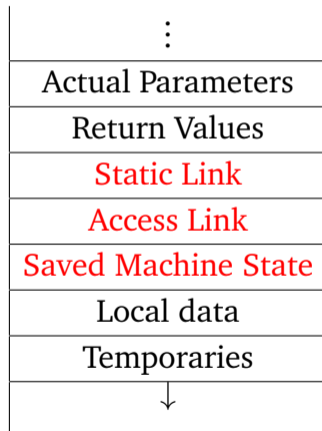


The stack



The stack

Activation record or “frame”:



The stack

Typical “frame core” scenario:

Static link (saved frame pointer, or control link)
points to saved “frame core” (of caller).

Access link for nested procedures, typically absent.

Saved machine status saved PC and registers (of caller).



The stack

Typical runtime stack organization:

Show the runtime relationship that two consecutive, active records are in, given a general target architecture...



Target Architectures

High-end (expensive) architectures:

- ▶ ARM: Tablets, mobile phones, ultrabooks, Raspberry Pi.
- ▶ amd64: Intel (and AMD) PCs and servers.
- ▶ SPARC: Oracle servers.
- ▶ Power PC: IBM servers.

Low-end (cheap) architectures:

- ▶ 6505: 8-bit architecture...



The stack

Calling Conventions generally speaking:

A “static storage allocation contract” between caller and callee, which is guaranteed to hold at runtime.

- ▶ size of allocated entities (actual parameters and return values, e.g. based on static type info),
- ▶ where address information is kept (registers or stack).



ARM Calling Conventions

| <i>Register</i> | <i>On Entry</i> | <i>On Return</i> |
|-----------------|---------------------|------------------------|
| r0–3 | parameter or unused | return value or unused |
| r4–11 | preserved | same as on entry |
| r12 | undefined | undefined |
| r13 'sp' | stack pointer | same as on entry |
| r14 'lr' | return address | (unconstrained) |
| r15 'pc' | program counter | return address |

For full details see

http://infocenter.arm.com/help/topic/com.arm.doc.ih0042e/IH0042E_aapcs.pdf



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ARM Instructions

- ▶ `MOV B, A` – “Move”
copy what is in *A* to *B*.
- ▶ `BL label` – “Branch with Link”
set *lr* to next instruction address then jump to *label*.
- ▶ `STMFd sp!, {regs}` – “Store Multiple/Fully Descending”
push all the listed *regs* on stack (that grows downwards).
- ▶ `LDMFD sp!, {regs}` – “Load Multiple/Fully Descending”
pop all the listed *regs* from stack (downwards).



ARM Call and Return Code

Caller:

```
MOV r0, <param1>  
MOV r1, <param2>  
MOV r2, <param3>  
MOV r3, <param4>  
BL Callee
```

Callee:

```
STMFD sp!,{r4-r11,lr}
```

Body with parameters in r0-r3...

```
MOV r0, <return value>  
LDMFD sp!,{r4-r11,pc}
```

Use return value in r0



AMD64 Call and Return Code

Caller:

```
put actuals on stack/registers  
call Callee
```

Callee:

```
push %rbp  
move %rbp, %rsp  
sub %rsp, <frame size>
```

Body with parameters in [%rbp-...]...

```
move %rax, <return value>  
move %rsp, %rbp  
pop %rbp  
ret
```

remove actuals from stack

Use return value in %rax

Other stack topics

- ▶ saving registers across calls,
- ▶ variable-sized data on stack,
- ▶ accessing non-local stack variables.



ARM Call and Return Code Example

Caller:

```
MOV r0, #1
MOV r1, #1
BL Callee
```

Callee:

```
STMFD sp!, {r4-r11, lr}
ADD r0, r0, r1
LDMFD sp!, {r4-r11, pc}
```

Continue...



ARM Call and Return Code Example

Caller:

```
MOV r0, #1
MOV r1, #1
BL Callee
```

Callee:

```
STMFD sp!,{r4-r11,lr}
ADD r0, r0, r1
LDMFD sp!,{r4-r11,pc}
```

Continue...



ARM Call and Return Code Example

Caller:

```
MOV r0, #1
MOV r1, #1
BL Callee
```

Callee:

```
STMFD sp!, {lr}
ADD r0, r0, r1
LDMFD sp!, {pc}
```

Continue...



ARM Call and Return Code Example

Caller:

```
MOV r0, #1
```

```
MOV r1, #1
```

```
BL Callee
```

Callee:

```
ADD r0, r0, r1
```

```
MOV pc, lr
```

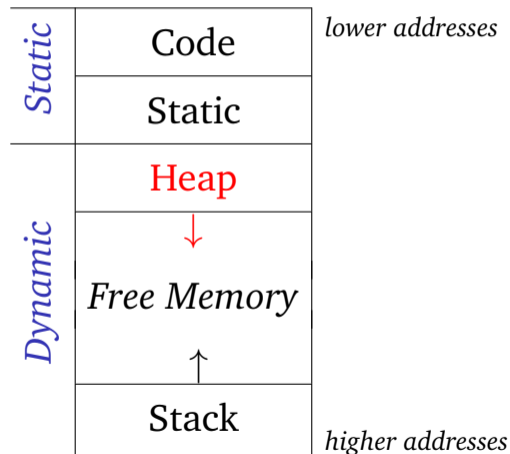
Continue...



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The heap



The heap

*Heap "objects" may live indefinitely.
"Life span" is managed automatically or from program
(memory manager).*

| | Java | C | C++ |
|---------------------|-------------------|---------------------|---------------------|
| Allocation | <code>new</code> | <code>malloc</code> | <code>new</code> |
| Deallocation | <i>garbage c.</i> | <code>free</code> | <code>delete</code> |



Questions?

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