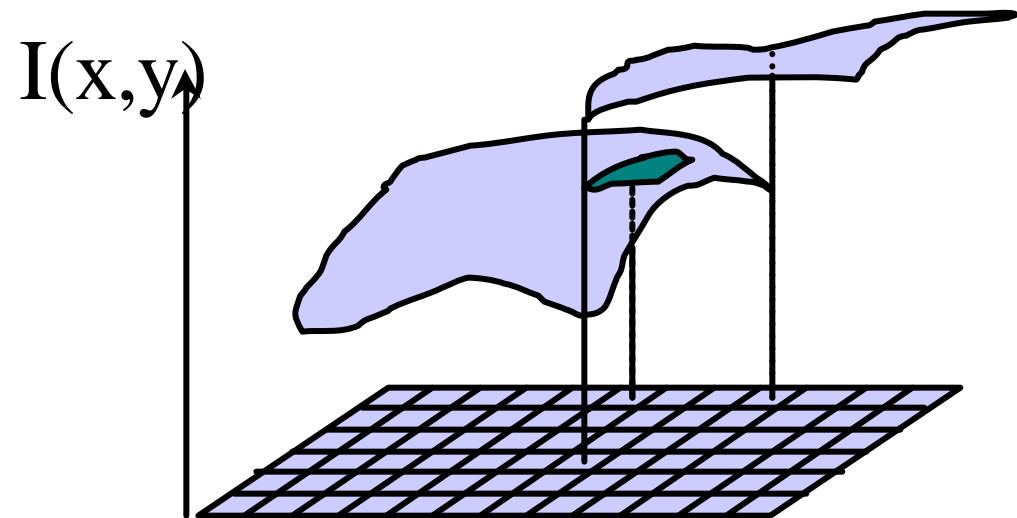
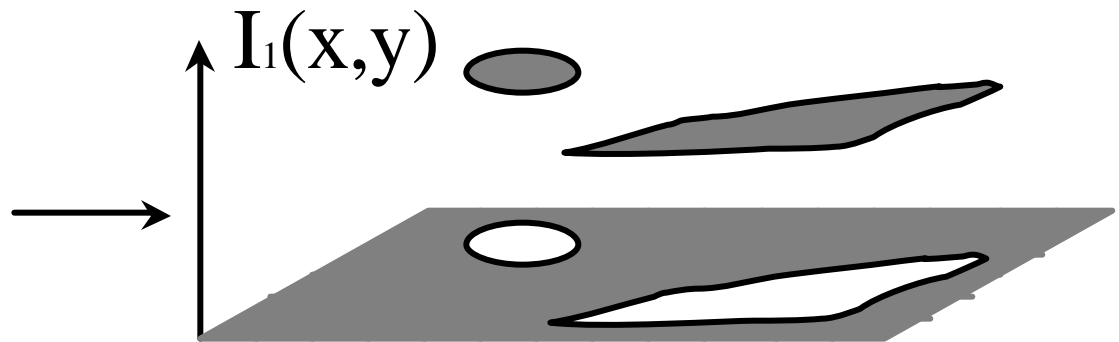
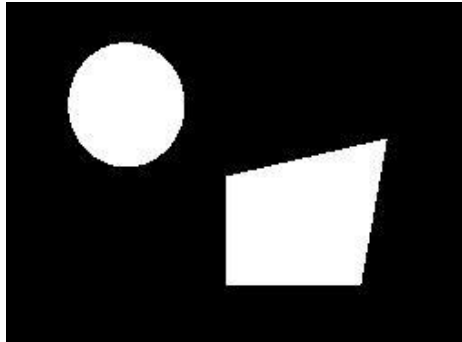


Image Measurements

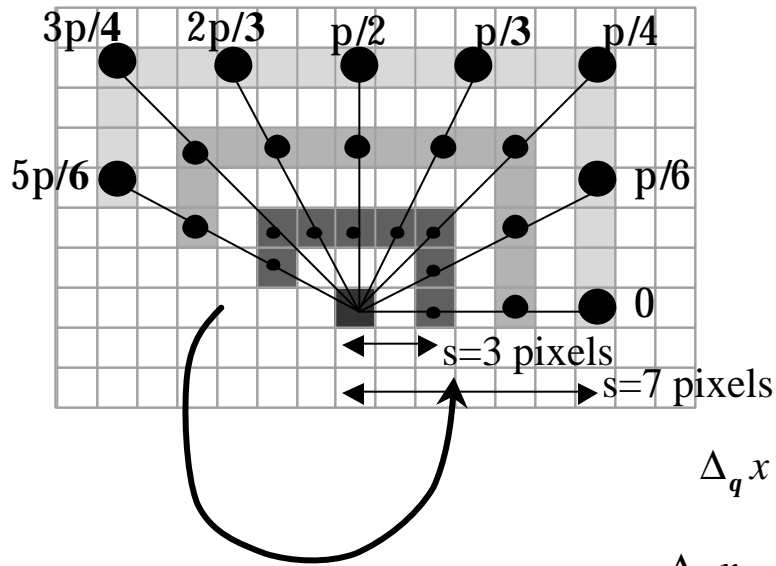
Image Measurements

Images are Intensity Surfaces and Edges are Surface Discontinuities



Measurements: Intensity Accumulation, $\tilde{I}(x, y, \mathbf{q}, s)$

For each pixel (x, y) we evaluate the accumulation of the intensity along sixteen (16) directions, $\theta=0, \pi/6, \pi/4, \pi/3, \pi/2, 2\pi/3, 3\pi/4, 5\pi/6, \pi, 7\pi/6, 5\pi/4, 4\pi/3, 3\pi/2, 5\pi/3, 7\pi/4, 13\pi/6$, and four (4) different scales, $s=3, 5, 7, 9$.



Locations of $\tilde{I}(x, y, \mathbf{q}, s)$

$$\tilde{x}_{\tilde{I}}(x, \mathbf{q}) = \frac{1}{s} \sum_{i=0}^{s-1} (x + i \Delta_q x \cos \mathbf{q}),$$

$$\tilde{y}_{\tilde{I}}(y, \mathbf{q}) = \frac{1}{s} \sum_{i=0}^{s-1} (y + i \Delta_q y \sin \mathbf{q})$$

$$\tilde{I}(x, y, \mathbf{q}, s) = \frac{1}{s} \int_0^s I(\mathbf{a} \cos \mathbf{q}, \mathbf{a} \sin \mathbf{q}) d\mathbf{a}$$

Discrete approximation

$$\tilde{I}(x, y, \mathbf{q}, s) \approx \frac{1}{s} \sum_{i=0}^{s-1} I(x + i \Delta_q x \cos \mathbf{q}, y + i \Delta_q y \sin \mathbf{q})$$

where,

$$\Delta_q x = 1 \text{ and } \Delta_q y = 1 \text{ for } \theta = 0, \pi/2, \pi, 3\pi/2$$

$$\Delta_q x = \sqrt{2} \text{ and } \Delta_q y = \sqrt{2} \text{ for } \theta = \pi/4, 3\pi/4, 5\pi/4, 7\pi/4$$

$$\Delta_q x = \frac{2}{\sqrt{3}} \text{ and } \Delta_q y = 1 \text{ for } \theta = \pi/6, 5\pi/6, 7\pi/6, 13\pi/6$$

$$\Delta_q x = 1 \text{ and } \Delta_q y = \frac{2}{\sqrt{3}} \text{ for } \theta = \pi/3, 2\pi/3, 4\pi/3, 5\pi/3.$$

Measurements: Intensity Accumulation II, $\hat{I}(x, y, \mathbf{q}, s)$

In order to obtain more robust measures, for an angle θ , $\tilde{I}(x, y, \mathbf{q}, s)$
we can average the value of along $\pi/2 + \theta$ to obtain $\hat{I}(x, y, \mathbf{q}, s)$

$$\hat{I}(x, y, \mathbf{q}, s) = \frac{1}{4}(\tilde{I}(x, y, \mathbf{q}, s) + \tilde{I}(x, y+1, \mathbf{q}, s) + \tilde{I}(x, y-1, \mathbf{q}, s) + \tilde{I}(x+1, y, \mathbf{q}, s))$$

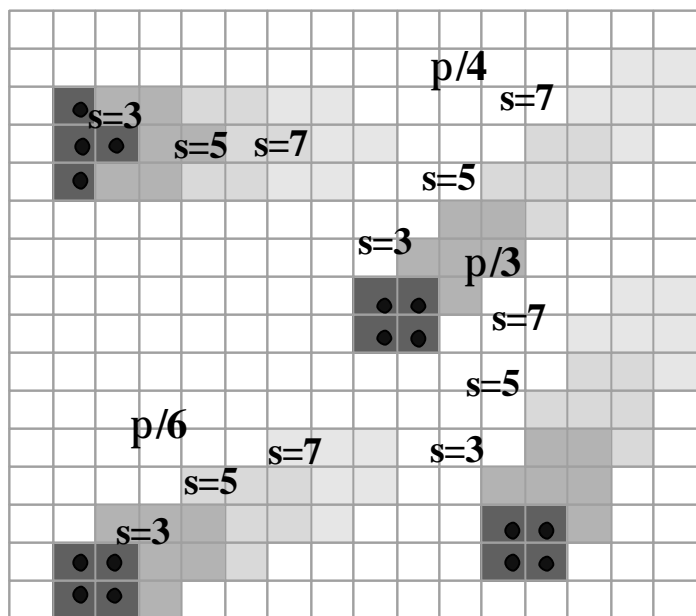
for $\theta = 0, \pi$,

$$\frac{1}{4}(\tilde{I}(x, y, \mathbf{q}, s) + \tilde{I}(x+1, y, \mathbf{q}, s) + \tilde{I}(x-1, y, \mathbf{q}, s) + \tilde{I}(x, y+1, \mathbf{q}, s))$$

for $\theta = \pi/2, 3\pi/2$,

$$\frac{1}{4}(\tilde{I}(x, y, \mathbf{q}, s) + \tilde{I}(x-1, y, \mathbf{q}, s) + \tilde{I}(x, y+1, \mathbf{q}, s) + \tilde{I}(x-1, y+1, \mathbf{q}, s))$$

for $\theta = \pi/6, \pi/4, \pi/3$.



Measurements: Homogeneity

The average intensity should not vary across scales if there no discontinuities along θ .

$$\tilde{R}(x, y, \mathbf{q}, s) = |\tilde{I}_c(x, y, \mathbf{q}, s) - \tilde{I}_c(x, y, \mathbf{q}, s - \Delta s)| / |\tilde{I}_c(x, y, \mathbf{q}, s)|$$

where $\tilde{I}_c(x, y, \mathbf{q}, s) = \frac{s}{s-1} \left(\tilde{I}(x, y, \mathbf{q}, s) - \frac{1}{s} I(x, y) \right)$ does not include the center pixel.

Finally

$$\tilde{H}(x, y, s) = \sum_{q=0}^{11p/6} \tilde{R}(x, y, \mathbf{q}, s) ,$$

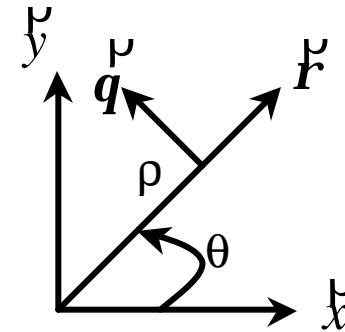
is a measure of homogeneity, the lower it is the more homogeneous is the region centered on (x, y) . Analogously one can compute $\hat{H}(x, y, s)$.

Edges and Junctions are expected to be localized at homogeneous pixels.

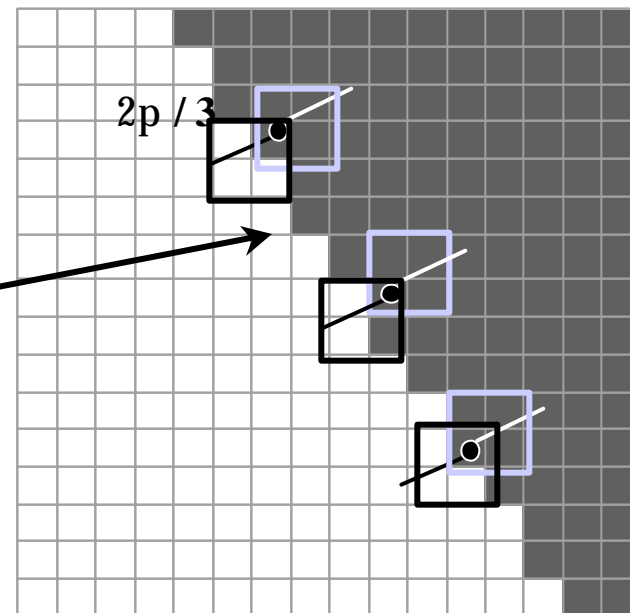
Measurements: Derivatives $D_r \hat{I}(x, y, \mathbf{q}, s)$

Taking the derivative along the angle θ , i.e., in a direction $\hat{\mathbf{r}} = (\cos \mathbf{q}, \sin \mathbf{q})$

$$\begin{aligned} D_r \hat{I}(x, y, \mathbf{q}, s) &= \nabla \hat{I}(x, y, \mathbf{q}, s) \cdot (\cos \mathbf{q}, \sin \mathbf{q}) \\ &= \frac{\partial \hat{I}(x, y, \mathbf{q}, s)}{\partial x} \cos \mathbf{q} + \frac{\partial \hat{I}(x, y, \mathbf{q}, s)}{\partial y} \sin \mathbf{q} \\ &\approx \hat{I}(x, y, \mathbf{q}, s) - \hat{I}(x, y, \mathbf{p} + \mathbf{q}, s) . \end{aligned}$$



Analogously we obtain $D_r \tilde{I}(x, y, \mathbf{q}, s)$. We have now a bank of eight (8) distinct oriented filters at different scales, namely $\{D_r \hat{I}(x, y, \mathbf{q}, s); \theta = 0, \pi/6, \dots, 5\pi/6\}$, and $s = 1, 3, 5, 7, \dots\}$, with the property that $D_r \hat{I}(x, y, \mathbf{q}, s) = -D_r \hat{I}(x, y, \mathbf{q} + \mathbf{p}, s)$

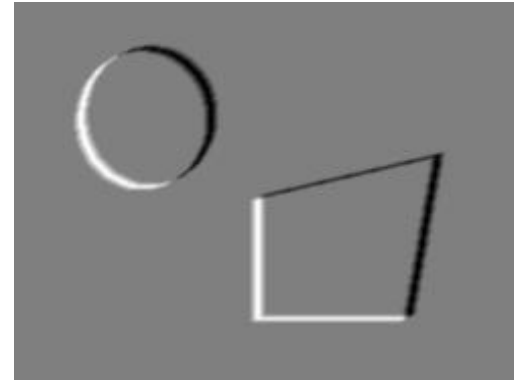


$|D_r \hat{I}(x, y, \mathbf{q} = \mathbf{p} / 6, s)|$ will have maximum response (highest value) among the possible orientations, while $|D_r \hat{I}(x, y, \mathbf{q} = \frac{2\mathbf{p}}{3}, s)|$, will have the minimum response.

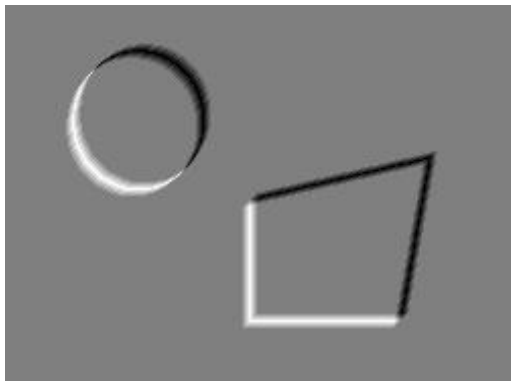
Experiments: $D_r \hat{I}(x, y, \mathbf{q}, s)$



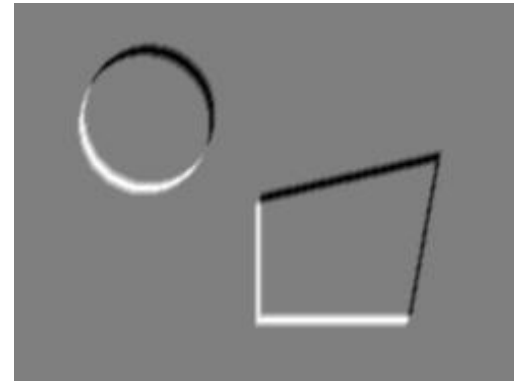
$$D_r \hat{I}(x, y, 0, 3)$$



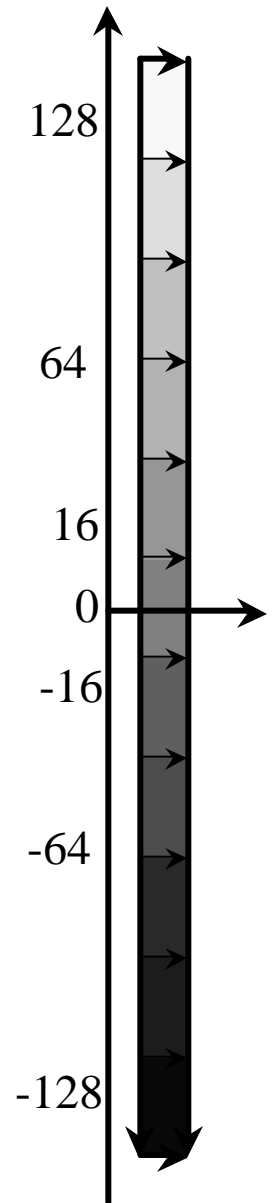
$$D_r \hat{I}(x, y, \frac{\mathbf{p}}{6}, 3)$$



$$D_r \hat{I}(x, y, \frac{\mathbf{p}}{4}, 3)$$



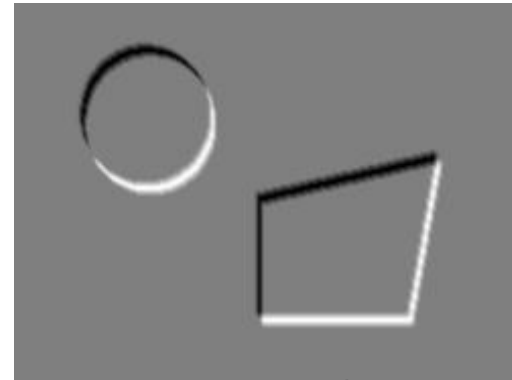
$$D_r \hat{I}(x, y, \frac{\mathbf{p}}{3}, 3)$$



Experiments (cont.): $D\hat{I}(x, y, \mathbf{q}, s)$



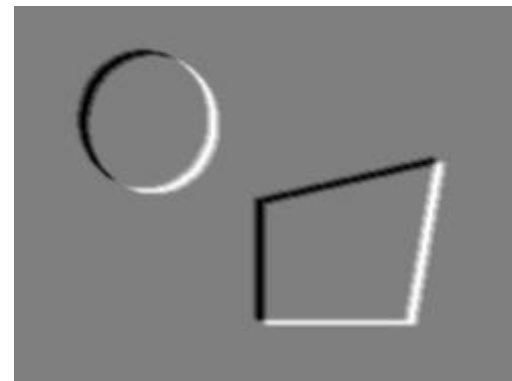
$$D_r \hat{I}(x, y, \frac{\mathbf{p}}{2}, 3)$$



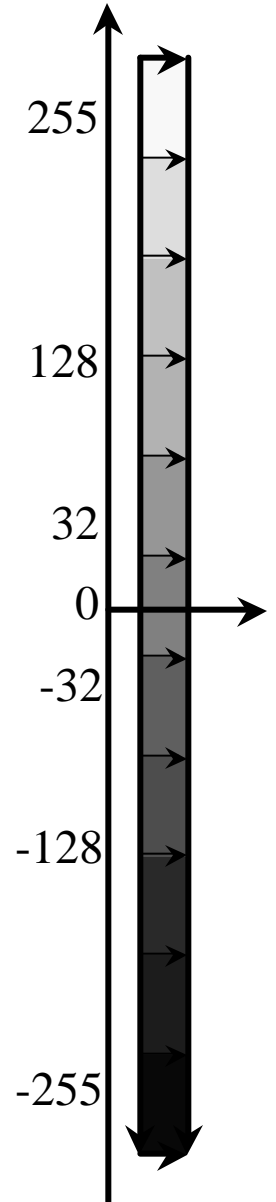
$$D_r \hat{I}(x, y, \frac{2\mathbf{p}}{3}, 3)$$



$$D_r \hat{I}(x, y, \frac{3\mathbf{p}}{4}, 3)$$

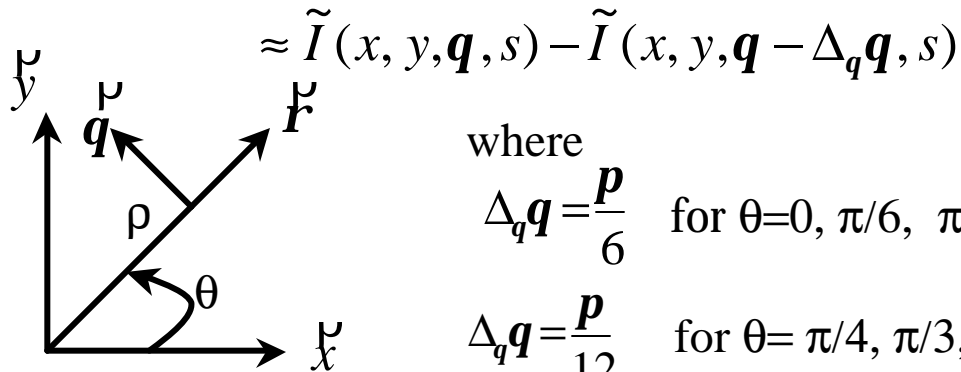


$$D_r \hat{I}(x, y, \frac{5\mathbf{p}}{6}, 3)$$



Measurements: Derivatives $D_q \tilde{I}(x, y, \mathbf{q}, s)$

$$D_q \tilde{I}(x, y, \mathbf{q}, s) = \nabla \tilde{I}(x, y, \mathbf{q}, s) \cdot (-\sin \mathbf{q}, \cos \mathbf{q}) = -\frac{\partial \tilde{I}(x, y, \mathbf{q}, s)}{\partial x} \sin \mathbf{q} + \frac{\partial \tilde{I}(x, y, \mathbf{q}, s)}{\partial y} \cos \mathbf{q}$$



$$\approx \tilde{I}(x, y, \mathbf{q}, s) - \tilde{I}(x, y, \mathbf{q} - \Delta_q \mathbf{q}, s)$$

where

$$\Delta_q \mathbf{q} = \frac{\mathbf{p}}{6} \quad \text{for } \theta = 0, \pi/6, \pi/2, 2\pi/3, \pi, 7\pi/6, 3\pi/2, 5\pi/3,$$

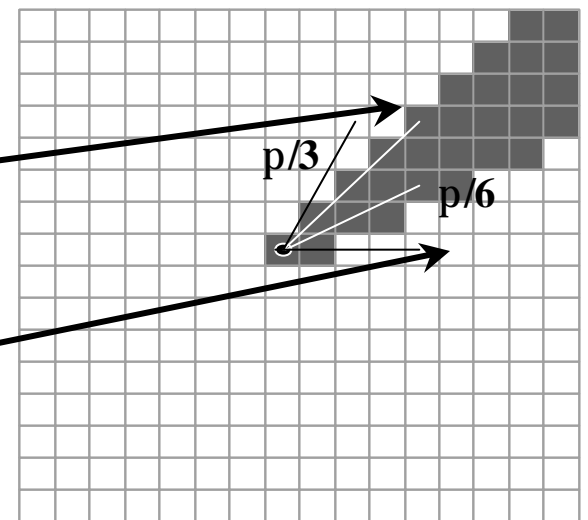
$$\Delta_q \mathbf{q} = \frac{\mathbf{p}}{12} \quad \text{for } \theta = \pi/4, \pi/3, 3\pi/4, 5\pi/6, 5\pi/4, 4\pi/3, 7\pi/4, 11\pi/6.$$

Corners and Junctions will respond to high values of $D_q \hat{I}(x, y, \mathbf{q}, s)$

The maximum responses here, among different θ are for

$$D_q \hat{I}(x, y, \frac{\mathbf{p}}{3}, s) \quad \text{and}$$

$$D_q \hat{I}(x, y, \frac{\mathbf{p}}{6}, s)$$



Measurements: 2nd Derivatives

$$H(x, y) = \begin{pmatrix} \frac{\partial^2 \hat{I}}{\partial_x^2} & \frac{\partial^2 \hat{I}}{\partial_x \partial y} \\ \frac{\partial^2 \hat{I}}{\partial y \partial x} & \frac{\partial^2 \hat{I}}{\partial_y^2} \end{pmatrix}$$

Hessian allows for computing the second derivative

in order to compute the (second) derivative along a direction \hat{v} of a (first) derivative along a direction \hat{u} , we compute the projections

$$D_{vu} \hat{I}(x, y, \mathbf{q}, \mathbf{f}, s) = \hat{v} H(x, y) \hat{u}^T$$

For example for $\hat{u} = (1, 0) = \hat{x}$; $\hat{v} = (1, 0) = \hat{x}$ we obtain $D_{vu} \hat{I}(x, y, \mathbf{q}, \mathbf{f}, s) = \frac{\partial^2 \hat{I}}{\partial x^2}$

and for $\hat{u} = (1, 0) = \hat{x}$; $\hat{v} = (0, 1) = \hat{y}$ we obtain $D_{vu} \hat{I}(x, y, \mathbf{q}, \mathbf{f}, s) = \frac{\partial^2 \hat{I}}{\partial y \partial x}$

Measurements: 2nd Derivatives (cont.)

in order to compute the (second) derivative along a direction ϕ of a (first) derivative along a direction θ , we obtain a continuous and a lattice approximation as

$$D_{\mathbf{f}\mathbf{q}} \hat{I}(x, y, \mathbf{q}, \mathbf{f}, s) = (\cos \mathbf{f}, \sin \mathbf{f}) H(x, y) (\cos \mathbf{q}, \sin \mathbf{q})^T \\ \approx D\hat{I}(x, y, \mathbf{q}, s) - D\hat{I}(x - \Delta_f x \cos \mathbf{f}, y - \Delta_f y \sin \mathbf{f}, \mathbf{q}, s) / s \Delta$$

