



# Information-Theoretic approaches to Information Flow

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# The problem

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#### Control the information leakage

i.e.

# the amount of **secret information** that an adversary can **infer** from what he can **observe**

#### An example to illustrate the problem: The Dining Cryptographers (Chaum, 1988)

- Three cryptographers have a dinner
- Their master informs each of them separately whether he should pay for the (whole) bill or not. If none of them pays, the master will pay
- The cryptographers are allowed to try to find out whether the master has asked one of them to pay, **but they should not know whom**







#### Dining Cryptographers: The solution proposed by Chaum

- Place a binary coin between each two cryptographers and toss them
- Each cryptographer makes the binary sum of the adjacent coins. The payer (if any) adds 1. The results are announced
- The binary sum of the results is 1 iff one of them is a payer
- If the coins are fair, we have perfect anonymity



# Example: Crowds (Rubin and Reiter'98)

- Problem: A user (initiator) wants to send a message anonymously to another user (dest.)
- Crowds: A group of n users who agree to participate in the protocol.
- The initiator selects randomly another user (forwarder) and forwards the request to him
- A forwarder randomly decides whether to send the message to another forwarder or to dest.
- ... and so on



**Probable innocence:** under certain conditions, an attacker who intercepts the message from x cannot attribute more than 0.5 probability to x to be the initiator



# Our problem: Formalize the notion of information leakage

- No agreement on the subject. (Here we present our proposal.)
- There is not even agreement on the true-false notions:
  - **Perfect anonymity:** my favorite notion is the one by Chaum: for each observation, the *a posteriori probability* that c<sub>i</sub> is the payer is the same as the *a priori probability*
  - **Probable innocence:** Reiter and Rubin defined it only informally and other researchers got it wrong
- We are interested in a **quantitative** notion, i.e. how much information does the system leak

# Common features in Information Flow

- There is information that we want to keep secret
  - the payer in DC
  - the initiator in Crowds
- There is information that is revealed (observables)
  - the declarations in DC
  - the users who forward messages to a corrupted user in Crowds
- The value of the secret information may be chosen probabilistically, and the system may use randomization (maybe even in purpose, to hide the link between secrets and observables)
  - coin tossing in DC
  - random forwarding to another user in Crowds





#### Example: Dining Cryptographers







#### An intriguing analogy:

#### Systems as Information-Theoretic channels





- an input can generate different outputs (according to a prob. distr.)
- an output can be generated by different inputs (even in **det. syst.**)



given that the secret is s<sub>i</sub>





# Towards a quantitative def. of leakage

• A general principle (on which most people agree):

Leakage = a priori uncertainty – a posteriori uncertainty

- But what is ``uncertainty''? (and here people disagree)
- Our answer is that there is no unique answer: it depends on
  - the model of attack, and
  - how we measure it success





## Uncertainty, this unknown

- Kopf and Basin model of attack: assume an oracle who answers yes/no to questions of a certain form. The attack is then defined by the form of the questions
- Example I: The questions are of the form "is S ∈ P ?", and the measure of success is: the expected number of questions of this kind needed to determine the value of S

#### then

#### uncertainty corresponds to Shannon entropy

• For instance, guessing the last bit of a password





## Uncertainty, this unknown

• **Example 2:** The questions are of the form "is S = v ?", and the measure of success is: the probability of determining the value of S with just one try

#### then

#### uncertainty corresponds to Renyi's min entropy

- For instance, guessing a password by trying it
- In any case, leakage can be modeled as mutual information:

I(S;O) = H(S) - H(S | O)

### Computing the leakage by model checking e.g. reachability analysis

#### Example

 $\begin{array}{ll} x^{aA}_{inii} = \frac{1}{3} \cdot x^A_{q_a}, & x^A_{q_a} = \frac{p}{3} \cdot x^A_{q_a} + \frac{p}{3} \cdot x^A_{q_b} + \frac{p}{3} \cdot x^\epsilon_{corr}, & x^A_{corr} = x^A_S, \\ x^{bA}_{inii} = \frac{2}{3} \cdot x^A_{q_b}, & x^A_{q_b} = \frac{p}{3} \cdot x^A_{q_a} + \frac{p}{3} \cdot x^A_{q_b} + \frac{p}{3} \cdot x^C_{corr}, & x^A_S = 0, \\ x^{aB}_{inii} = \frac{1}{3} \cdot x^B_{q_a}, & x^B_{q_a} = \frac{p}{3} \cdot x^B_{q_a} + \frac{p}{3} \cdot x^B_{q_b} + \frac{p}{3} \cdot x^B_{corr}, & x^B_S = 0, \\ x^{bB}_{inii} = \frac{2}{3} \cdot x^B_{q_b}, & x^B_{q_a} = \frac{p}{3} \cdot x^B_{q_a} + \frac{p}{3} \cdot x^B_{q_b} + \frac{p}{3} \cdot x^C_{corr}, & x^B_S = 0, \\ x^{aU}_{inii} = \frac{1}{3} \cdot x^U_{q_a}, & x^U_{q_a} = \frac{p}{3} \cdot x^U_{q_a} + \frac{p}{3} \cdot x^U_{q_b} + (1-p) \cdot x^\epsilon_S, & x^\epsilon_{corr} = x^\epsilon_S, \\ \end{array}$  $x_{\textit{init}}^{bU} = \tfrac{2}{3} \cdot x_{q_b}^U, \qquad x_{q_b}^U = \tfrac{p}{3} \cdot x_{q_a}^U + \tfrac{p}{3} \cdot x_{q_b}^U + (1-p) \cdot x_S^\epsilon, \qquad x_S^\epsilon = 1.$ 

> $x_{init}^{aA} = \frac{7}{40}, \qquad x_{init}^{aB} = \frac{3}{40}, \qquad x_{init}^{aU} = \frac{1}{12},$  $x_{init}^{bA} = \frac{3}{20}, \qquad x_{init}^{bB} = \frac{7}{20}, \qquad x_{init}^{bU} = \frac{1}{6}.$

#### Solution



as a

Matrix of joint probabilities

#### Complexity

 $\Box O((|obs| \times |Q|)^3)$ In general

□ O ( |obs| × |Q|³ ) Some Scenarios (e.g observables at the end)



#### A digression on something that I find rather puzzling





## Possibilistic approach

- Very popular, 'cause it is simpler than the quantitative approaches
- Key principle: A system P has no leakage iff: For every pair of secret values a, b, P[a] "is equivalent" to P[b]
  - Uhu ???
    - It assumes that the scheduler "helps"
    - Problem with refinement





#### Example: Consider the following system

 $S \stackrel{\text{def}}{=} (c, out)(A \parallel H_1 \parallel H_2 \parallel Corr),$ 

 $A \stackrel{\mathrm{def}}{=} \overline{c} \langle sec \rangle, \quad H_1 \stackrel{\mathrm{def}}{=} c(s). \overline{out} \langle a \rangle, \quad H_2 \stackrel{\mathrm{def}}{=} c(s). \overline{out} \langle b \rangle, \quad Corr \stackrel{\mathrm{def}}{=} c(s). \overline{out} \langle s \rangle$ 

- S[a/sec] and S[b/sec] are bisimilar, so the system should have no leakage
- But: nondeterminism in concurrency is meant as underspecification
  - Some schedulers may always select *Corr* first
  - Standard implementation refinement (simulation) preserves properties of individual runs, but no-leakage is expressed as a global property.
- This problem is actually well known. (My understanding of) the main proposals to solve it are based on changing the notion of refinement: bisimulation instead than simulation. The actual implementation would be probabilistic, but it would be viewed as nondeterministic in order to prove bisimulation





$$S \stackrel{\text{def}}{=} (c, out)(A \parallel H_1 \parallel H_2 \parallel Corr ),$$
$$A \stackrel{\text{def}}{=} \overline{c} \langle sec \rangle, \quad H_1 \stackrel{\text{def}}{=} c(s).\overline{out} \langle a \rangle, \quad H_2 \stackrel{\text{def}}{=} c(s).\overline{out} \langle b \rangle, \quad Corr \stackrel{\text{def}}{=} c(s).\overline{out} \langle s \rangle$$

S[a/sec]







# Thank you !