

# No Need for Liveness Model Checking Algorithms?

April, 2004

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(joint work with Viktor Schuppan and Cyrille Artho)

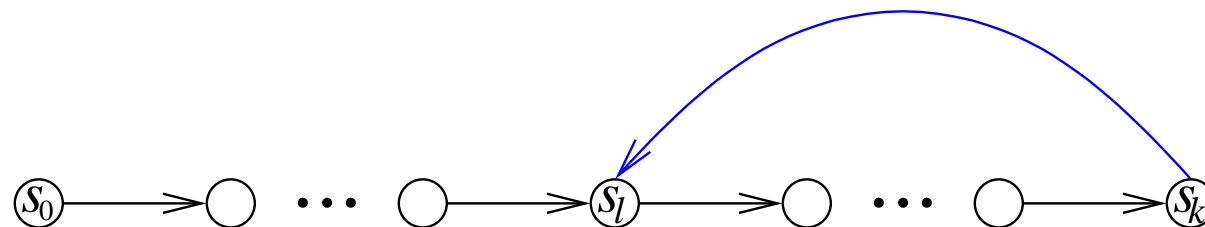
Computer Systems Institute  
ETH Zürich

Beyond Safety  
International Workshop

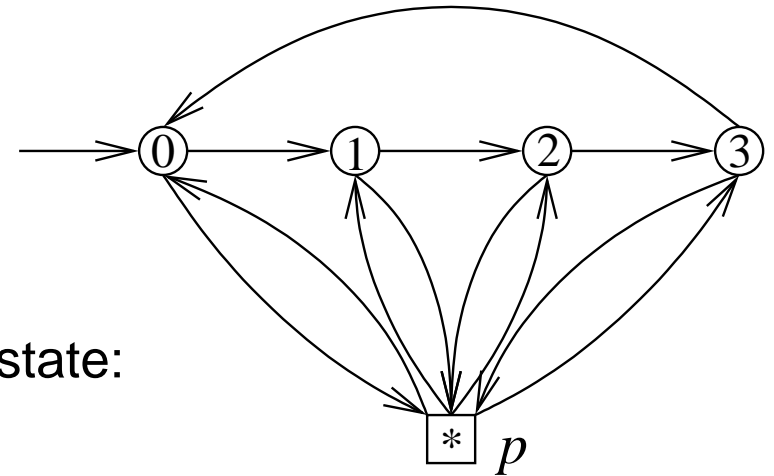
April 25–28, 2004, Ringberg Castle, Germany

- simple **safety** properties:
  - LTL:  $\mathbf{G}p$
  - CTL:  $\mathbf{AG}p$
  
- simple **liveness** properties:
  - LTL:  $\mathbf{F}p$
  - CTL:  $\mathbf{AF}p$
  - plus fairness constraints (generalized Büchi Automata)
  
- full LTL can be translated to **simple liveness + fairness**

- counter examples to a **safety** property are finite traces
  - **radius** is the length of shortest initialized path to an arbitrary state
  - radius is a **completeness threshold** for (simple) safety properties
  - no longer potential counter example traces have to be checked
- every counter example trace to a liveness property is *lasso* shaped:



- **diameter** is the length of the longest shortest path between two states
- **wrong:** completeness threshold for liveness properties is radius + diameter

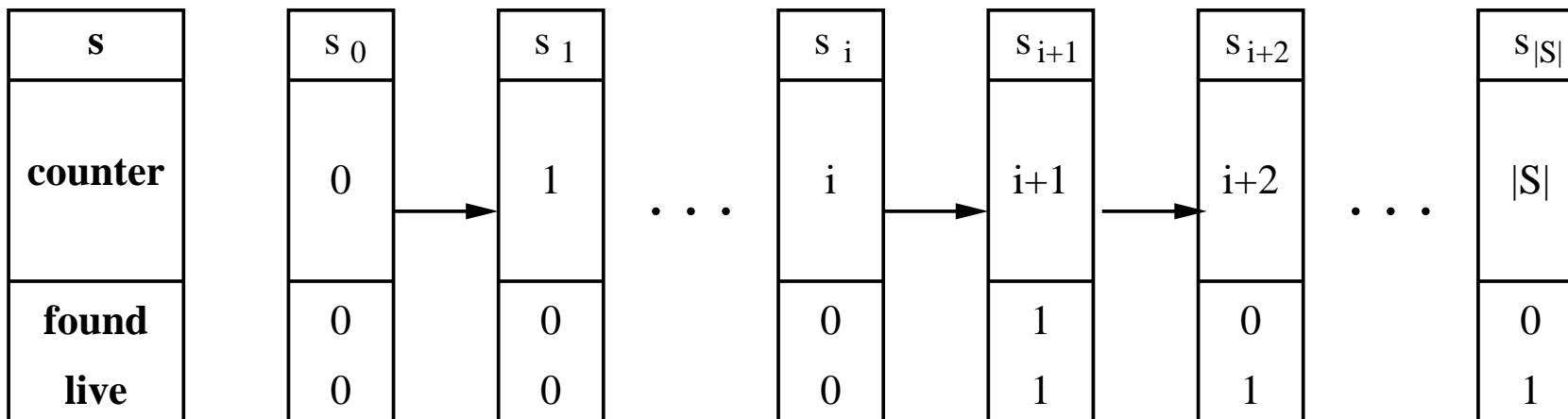


- modulo  $n$  (here  $n = 4$ ) counter with an explicit set state:
- radius and diameter both constant, but shortest counter example is of length  $n$
- **solution:** use  $\neg p$  predicated radius + diameter:
  - restrict Kripke structure to states in which  $\neg p$  holds
  - calculate radius and diameter in restricted Kripke structure

- liveness is actually bounded liveness:  $\mathbf{F}p \equiv \mathbf{F}_{\leq |S|} p$

$$\mathbf{F}_{\leq |S|} p \equiv p \vee \mathbf{X}p \vee \dots \vee \underbrace{\mathbf{X} \dots \mathbf{X}}_{|S|} p$$

- brute force expansion needs exponential space for symbolic model checking (via the standard Büchi-Automata translation)
- **counting translation** requires twice the number of state bits



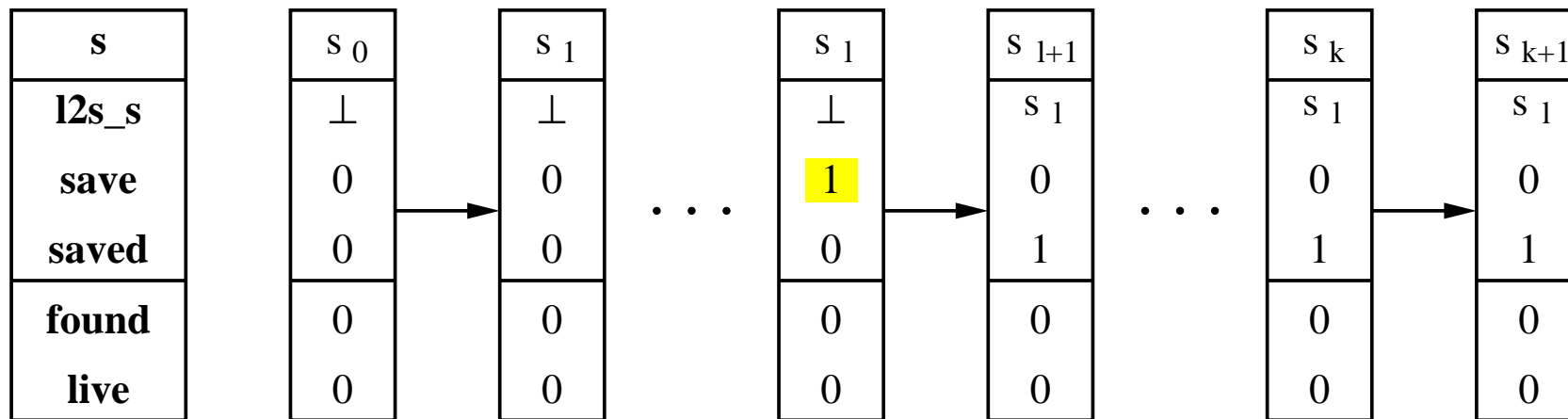
**s** = original state component

**counter** =  $\lceil \log_2 |S| \rceil$ -bit counter ( $|S|$  = number of original states)

**found** = boolean flag: body of liveness property is satisfied

**live** = boolean state bit: **found** is or was true

$$\mathbf{G} (\mathbf{counter} = |S| \rightarrow \mathbf{live})$$



**s** = original state component

**l2s\_s** = copy of original state component to save a state

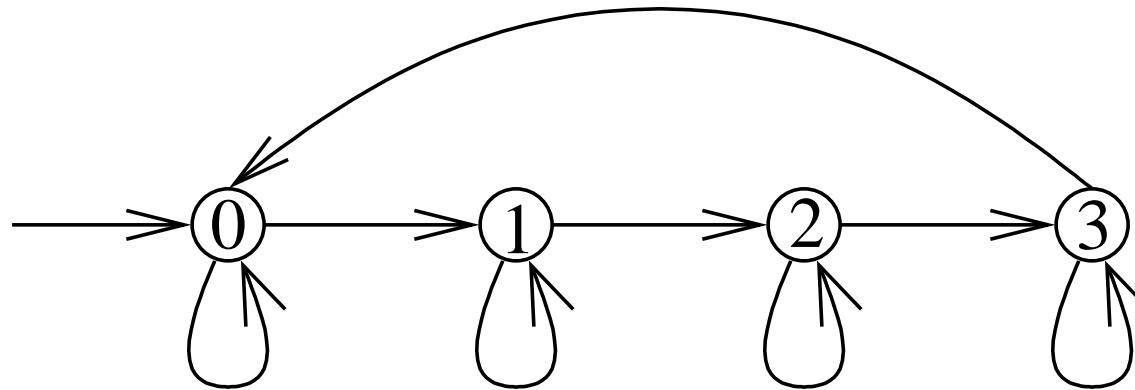
**save** = oracle (new primary input) to control when a state is saved

**saved** = boolean flag set to true when state has been saved

**found** = boolean flag: body of liveness property is satisfied

**live** = boolean state bit: **found** is or was true

$$G (s = l2s\_s \rightarrow live)$$



$\neq \mathbf{F}(s = 3)$



```

MODULE main
VAR
s: {0, 1, 2, 3};
ASSIGN
init(s) := 0;
next(s) := case
  s = 0: {1, s};
  s = 1: {2, s};
  s = 2: {3, s};
  s = 3: {0, s};
esac;

```

```

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s: {0, 1, 2, 3};
ASSIGN
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  s = 1: {2, s};
  s = 2: {3, s};
  s = 3: {0, s};
esac;

```

```

-- loop detection part
VAR
counter: 0..4;
ASSIGN
init(counter) := 0;
next(counter) := case
  counter < 4: counter + 1;
  1: counter;
esac;

```

```

DEFINE
looped := counter = 4;

```

```

-- property observing part
VAR live: boolean;
DEFINE found := s = 3;
ASSIGN
init(live) := 0;
next(live) := live | found;
SPEC AG (looped -> live)

```

```

EC AF s = 3

```

```

-- loop detection part
VAR
save: boolean;
saved: boolean;
l2s_s: {0, 1, 2, 3};
ASSIGN
init(saved) := 0;
next(saved) := on_loop;
init(l2s_s) := s;
next(l2s_s) := case
  save & !saved: s;
  1: l2s_s;
esac;
DEFINE
looped := saved & (s = l2s_s);
on_loop := save | saved;

```

```

-- property observing part
VAR live: boolean;
DEFINE found := s = 3;
ASSIGN
init(live) := 0;
next(live) := live | found;
SPEC AG (looped -> live)

```

- both translations are *complete*
- both translations double the number of state bits (in symbolic model checking)
- both translations may double the number of reachable states (really bad for explicit model checking)
- radius in counting translation may increase exponentially: (in symbolic model checking)

$$r^{\text{counting}} \geq |S|$$

- radius in state recording translation (optimizations possible):

$$r^{\text{recording}} \leq \max\{r + 2d + 2, r_{\neg p} + d_{\neg p} + 1\} = O(\max\{d, d_{\neg p}\})$$

- counter examples found are indeed counter examples (correctness)
- conditions for completeness (modulo reachability):
  - if there is a counter example, then there is also a lasso shaped one
  - each trace visits only finite many states
- examples where it works (state variables  $\in \mathbb{N}$ ):

$$\begin{array}{l|l}
 I(s) \equiv s \in \mathbb{N} & I(s, b) \equiv s = 0 \wedge b \in \mathbb{N} \\
 T(s, s') \equiv s \geq s' \wedge \text{details}(s, s') & T((s, b), (s', b')) \equiv I(s', b') \vee \\
 & s \leq s' \wedge b = b' \wedge \text{details}(s, s')
 \end{array}$$

- completeness threshold is different for liveness and safety
  - predicated diameter instead of ordinary diameter as bound
- finite states: efficient translation of liveness to safety
  - through state-recording translation
  - works in practice for symbolic model checking (e.g. with interpolation)
- infinite states: state recording works for some examples
  - combination of state recording with fairness?
  - can we always (efficiently) translate liveness to safety?