# Abstract Interpretation

SAVE 2016, Changsha, 10 December 2016

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# Scientific research

# This is an abstract interpretation









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# Scientific research

• In Mathematics/Physics:

trend towards unification and synthesis through universal principles

• In Computer science:

trend towards dispersion and parcellation through a ever-growing collection of local ad-hoc techniques for specific applications

An exponential process, will stop!

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# Example: reasoning on computational structures

WCET Axiomatic semantics	Security protocole Systems biology semantics verification analysis Abstraction Dataflow Model Database refinement	
Confidentiality analysis	analysis checking query Type	
_ ' Fa	Obfuscation Dependence inference	
synthesis	effect Denotational analysis Separation	
Grammar	stems semantics CEGAR _ logic	
analysis Statistical	Trace combination transformation proof	
model-checking	Shape Code Interpolants Abstract Shape	
	ymbolic contracts Integrity model analysis	
	xecution analysis checking Malware	
Probabilistic verification	Quantum entanglement Bisimulation detection Code	
	detection SMT solvers Code e theory Steganography Tautology testers	g

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# Example: reasoning on computational structures

	WCET Security protocole Systems biology semantics Verification applying
	semantics Abstraction Confidentiality Dataflow Model Database refinement
	Program evaluation Dependence inference
	synthesis Effect Denotational analysis Separation Grammar systems Semantics CEGAR logic
	Statistical Trace combination transformation proof
	Invariance Symbolic contracts Integrity model analysis
	Proof execution analysis checking Malware Probabilistic Quantum entanglement Bisimulation detection Verification detection Code
١	verification detection SMT solvers Code Parsing Type theory Steganography Tautology testers

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# Example: reasoning on computational structures

# Abstract interpretation

1	Security protocole Systems biology Operational
	Axiomatic verification systems bloody semantics
	Semantics Abstraction Abstraction
	Confidentiality analysis checking quary
	analysis Partial Obtacction Development
	Program evaluation Dependence inference
	synthesis <sub>Effect</sub> Denotational analysis Separation
	Grammar systems semantics CEGAR logic
I	analysis Theories Program lettimation
l	Statistical Combination transformation F. Semantics
	Code Interpolants Abstract Shape
	Symbolic contracts integrity
	proof execution analysis checking Malware
١	Probabilistic Quantum entanglement Bisimulation detection verification Code
١	TOT IT CALLOTT
	Parsing Type theory Steganography Tautology testers refactoring

# Intuition I

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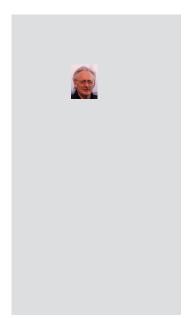
# Concrete



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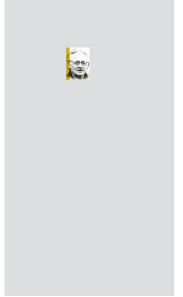
# Abstraction I



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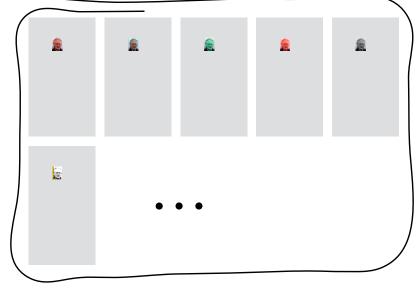
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# Abstraction 2



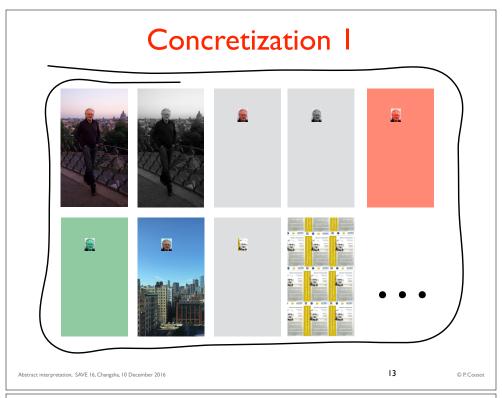
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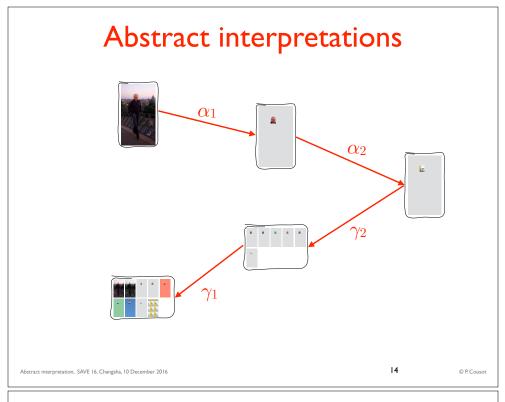
# Concretization 2

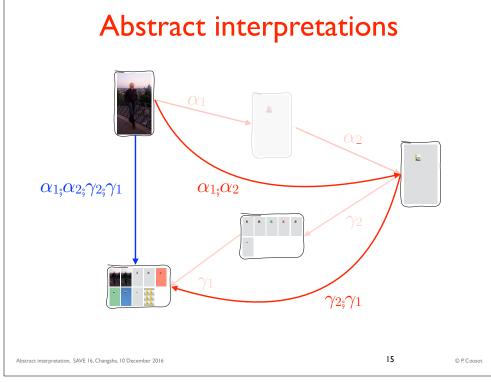


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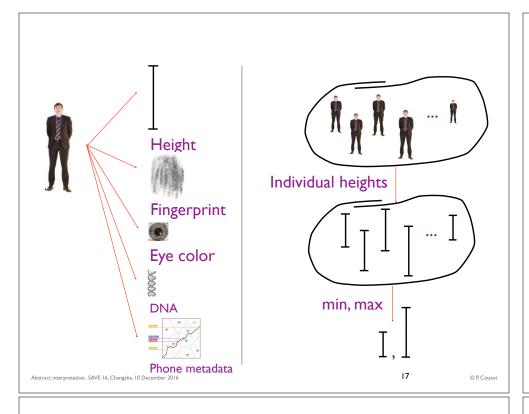
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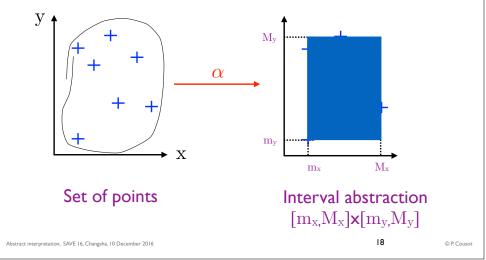




# Intuition 3

# Interval abstraction

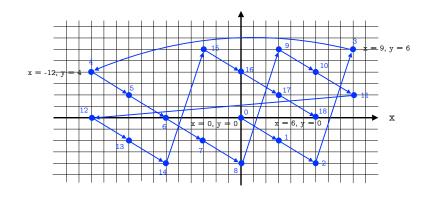
Example: interval abstraction (also called box abstraction)



# A C program and one of its executions

```
Enter two integers: x = 0, y = 0
#include <stdio.h>
int main()
                                                        x = 3, y = -2
                                                         x = 6, y = -4
            int x, y;
                                                         x = 9, y = 6
            printf("Enter two integers: ");
scanf("%d %d",&x, &y);
                                                         x = -12, y = 4
/* 1: */ while ((x != 6) || ( y != 0)) {
                                                         x = -9, y = 2
               printf("x = %d, y = %d\n", x, y);
                                                        x = -6, y = 0
/* 2: */
               x = x + 3;
/* 3: */
               if (x > 10) x = -x;
                                                         x = -3, y = -2
/* 4: */
               y = y - 2;
                                                         x = 0, y = -4
/* 5: */
               if (y < -5) y = -y;
                                                         x = 3, y = 6
/* 6: */ printf("x = %d, y = %d\n",x,y);
                                                         x = 6, y = 4
                                                         x = 9, y = 2
                                                         x = -12, y = 0
                                                         x = -9, y = -2
                                                         x = -6, y = -4
                                                         x = -3, y = 6
                                                         x = 0, y = 4
                                                         x = 3, y = 2
                                                         x = 6, y = 0
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                                                                                      © P. Cousot
```

# Graphical representation of the execution (I)



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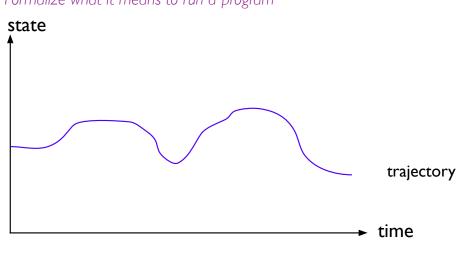
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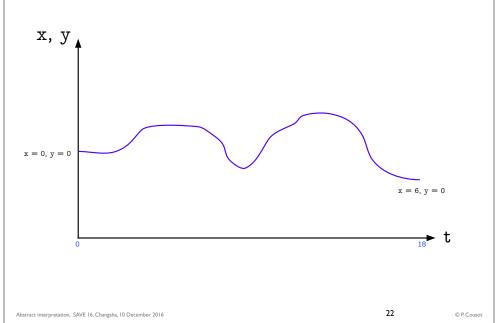
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Formalize what it means to run a program

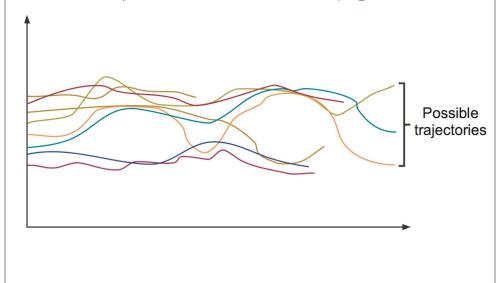


# Graphical representation of the execution (2)



# Properties (Collecting semantics)

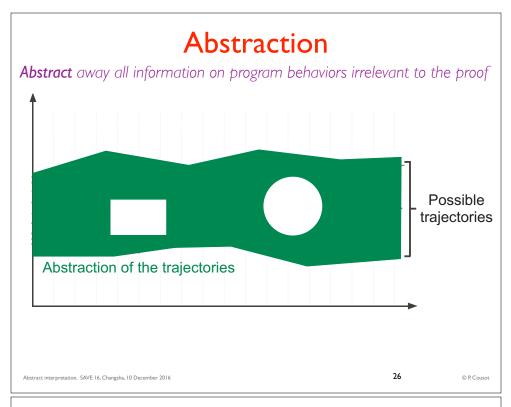
Formalize what you are interested to **know** about program behaviors

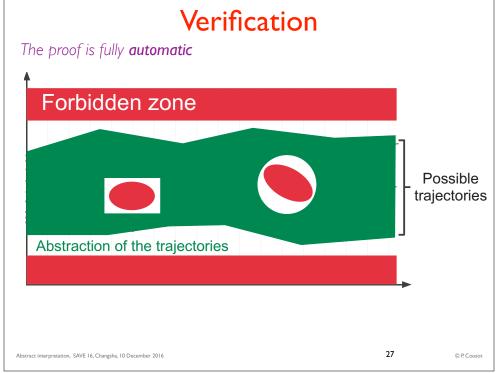


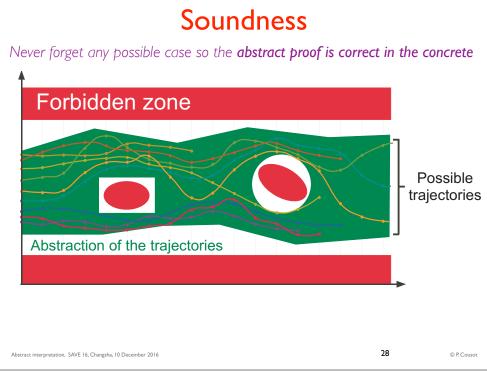
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# Specification Formalize what you are interested to prove about program behaviors Forbiden zone Possible trajectories Abstract interpretation, SAVE 16, Changha, 10 December 2016

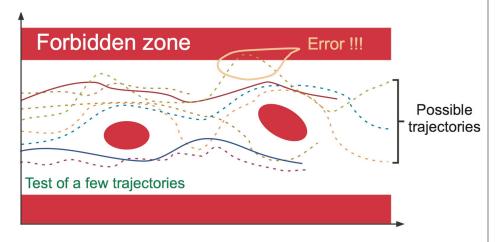






# Unsound methods: testing

Try a few cases



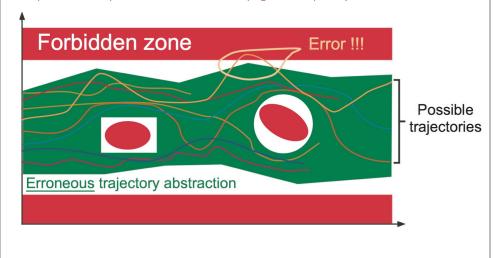
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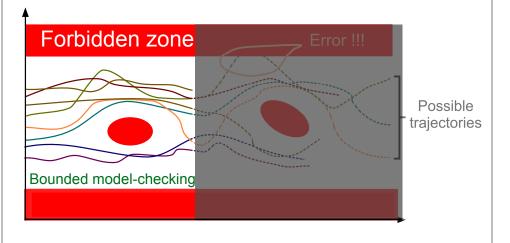
# Unsound methods: soundiness

Many static analysis tools are **unsound** (e.g. Coverity, etc.) so inconclusive



# Unsound methods: bounded model checking

Simulate the beginning of all executions (so called bounded model-checking)



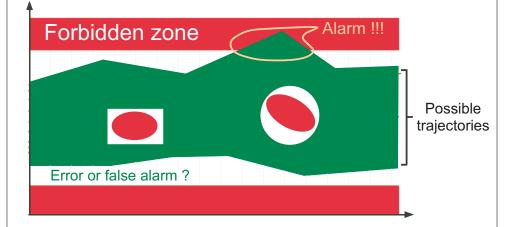
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### **Alarms**

When abstract proofs may fail while concrete proofs would succeed



By soundness an alarm must be raised for this over-approximation!

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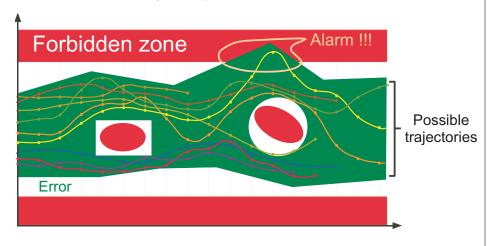
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## True alarm

The abstract alarm may correspond to a concrete error



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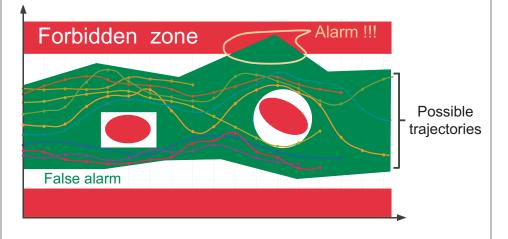
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# What to do in presence of false alarms

- False alarms are ultimately unavoidable (<u>Gödel's</u> incompleteness)
- Consider finite cases or decidable cases only (modelchecking, does not scale)
- Ask for human help by providing information on the program behavior (theorem provers, SMT solvers), program specific and labor costly
- Have specialists refine the abstract interpretation (e.g. Astrée, <a href="http://www.absint.com/astree/index.htm">http://www.absint.com/astree/index.htm</a>),
   shared cost



The abstract alarm may correspond to no concrete error (false negative)

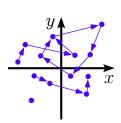


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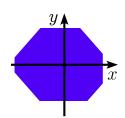
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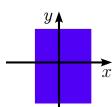
Collecting semantics: partial traces



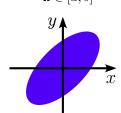
Octagons:

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 $\pm x \pm y \leqslant a$ 

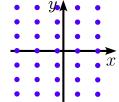


Intervals:  $x \in [a, b]$ 



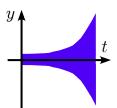
Ellipses:

$$x^2 + by^2 - axy \leqslant d$$



 ${\bf Simple\ congruences:}$ 

$$\mathbf{x} \equiv a[b]$$



Exponentials:

$$-a^{bt} \leqslant \mathtt{y}(t) \leqslant a^{bt}$$

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# The very first static analysis

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# The rule of signs by Brahmagupta (628)

18.30. [The sum] of two positives is positives, of two negatives negative;

# Brahmagupta

Brahmagupta (Sanskrit: ब्रह्मगुप्त;

(598-c.670 CE) was an

Indian mathematician and astronomer who wrote two important works on Mathematics and Astronomy: the Brāhmasphuṭasiddhānta (Extensive Treatise of Brahma) (628), a theoretical treatise, and the Khandakhādyaka, a more practical text.



Died

c.670 CE

Mathematics, Astronomy

Known for Zero, modern Number system

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# The rule of signs by Brahmagupta (628)

18.30. [The sum] of two positives is positives, of two negatives negative;

• The abstraction is that you do not (always) need to known the absolute value of the arguments to know the sign of the result;

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# The rule of signs by Brahmagupta (628)

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- Sometimes imprecise (don't know the sign of the sum of a positive and a negative)

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- Sometimes imprecise (don't know the sign of the sum of a positive and a negative)
- Useful in practice (if you know what to do when you don't know the sign)

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- Sometimes imprecise (don't know the sign of the sum of a positive and a negative)
- Useful in practice (if you know what to do when you don't know the sign)
- e.g. in compilation: do not optimize (a division by 2 into a shift when positive)

# The rule of signs by Brahmagupta (628)

18.30. [The sum] of two positives is positives, of two negatives negative; [...]

18.32. A negative minus zero is negative, a positive [minus zero] positive; zero [minus zero] is zero. When a positive is to be subtracted from a negative or a negative from a positive, then it is to be added.

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18.33. The product of a negative and a positive is negative, of two negatives positive, and of positives positive; the product of zero and a negative, of zero and a positive, or of two zeros is zero.

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18.34. A positive divided by a positive or a negative divided by a negative is positive; a zero divided by a zero is zero; a positive divided by a negative is negative; a negative divided by a positive is [also] negative.

wrong

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# The rule of signs by Michel Sintzoff (1972)

```
For example, a×a+b×b yields the value 25
when a is 3 and b is -4, and when + and \times are
the arithmetic multiplication and addition.
But axa+bxb yields always the object "pos" when
a and b are the objects "pos" or "neg", and when
the valuation is defined as follows:
pos+pos≃pos
                            pos×pos=pos
                            pos×neg=neg
pos+neg=pos,neg
neg+pos=pos,neg
                            neg×pos=neg
                            neg×neg=pos
neg+neg=neg
                            V(p \times q) = V(p) \times V(q)
V(p+q)=V(p)+V(q)
V(0)=V(1)=...=pos
V(-1)=V(-2)=...=neg
The valuation of axa+bxb yields "pos" by the
following computations:
                          V(b)=pos,neg
V(a) =pos,neg
                          V(b×b)=pos×pos,neg×neg
V(axa)=posxpos,negxneg
      ≖pos.pos=pos
                                =pos,pos=pos
V(a\times a+b\times b)=V(a\times a)+V(b\times b)=pos+pos=pos
     This valuation proves that the result of
axa+bxb is always positive and hence allows to
compute its square root without any preliminary
dynamic test on its sign. On the other hand, the
```

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                            V(p \times q) = V(p) \times V(q)
V(p+q)=V(p)+V(q)
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The valuation of axa+bxb yields "pos" by the
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      =pos.pos=pos
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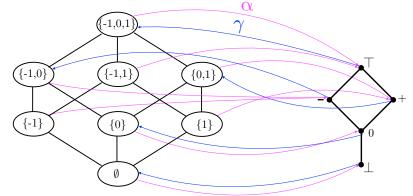
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# The rule of signs by Michel Sintzoff (1972)

For example, a×a+b×b yields the value 25 when a is 3 and b is -4, and when + and  $\times$  are the arithmetic multiplication and addition. But axa+bxb yields always the object "pos" when a and b are the objects "pos" or "neg", and when the valuation is defined as follows: pos×pos=pos pos+pos=pos pos+neg=pos,neg pos×neg=neg neg×pos=neg neg+pos=pos,neg 0∈pos x - l∈neg neg+neg=neg neg×neg=pos  $V(p \times q) = V(p) \times V(q)$ V(p+q)=V(p)+V(q)= 0∉neg V(0)=V(1)=...=posV(-1)=V(-2)=...=negThe valuation of axa+bxb yields "pos" by the following computations: V(b)=pos,neg V(a)=pos,neg V(axa)=posxpos,negxneg V(bxb)=posxpos,negxneg ≖pos,pos≖pos =pos,pos=pos  $V(a \times a + b \times b) = V(a \times a) + V(b \times b) = pos + pos = pos$ This valuation proves that the result of axa+bxb is always positive and hence allows to compute its square root without any preliminary dynamic test on its sign. On the other hand, the

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# The rule of signs Cousot & Cousot (1979)



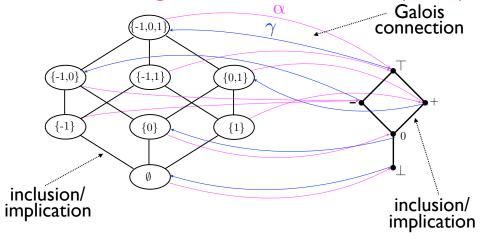
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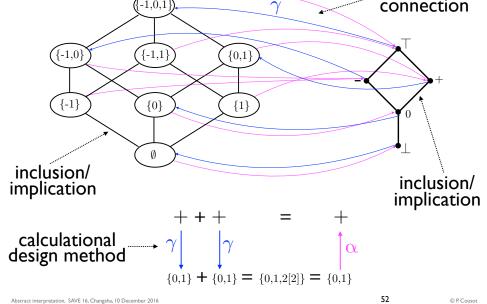
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# The rule of signs Cousot & Cousot (1979)



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# The rule of signs Cousot & Cousot (1979) $\alpha$ Galois connection



# Application of abstract interpretation to static analysis

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# Static analysis

- Check program properties (automatically, using the program text only, without running the program)
- Difficulties:
  - Undecidability / complexity:
    - Precision
    - Scalability
  - Soundness (correctness)
  - Induction: widening/narrowing

# All computer scientists have experienced bugs









Ariane 5.01 failure (overflow)

Patriot failure (float rounding)

Mars orbiter loss (unit error)

Heartbleed (buffer overrun)

- Checking the presence of bugs by debugging is great
- Proving their absence by static analysis is even better!

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Fixpoint equation

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# **Fixpoint**

```
\{y \geqslant 0\} \leftarrow \text{hypothesis}
\{I(x,y)\} \leftarrow \text{loop invariant}
while (x > 0) {
   x = x - 1;
```

Floyd-Naur-Hoare verification conditions:

$$(y\geqslant 0 \land x=y)\Longrightarrow I(x,y)$$
 initialisation  $(I(x,y)\land x>0 \land x'=x-1)\Longrightarrow I(x',y)$  iteration

Equivalent fixpoint equation:

$$I(x,y) = x \geqslant 0 \land (x = y \lor I(x+1,y))$$
 (i.e.  $I = F(I)^{(5)}$ )

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<sup>(5)</sup> We look for the most precise invariant I, implying all others, that is Ifp → F. Abstract interpretation, SAVE 16, Changsha, 10 December 2016

# **Iterates**

$$I$$
terates  $I = \lim_{n o \infty} F^n( ext{false})^{-y}$  $I^0(x,y) = ext{false}$ 

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# **Iterates**

$$I^0(x,y) = ext{false} \ I^0(x,y) = ext{false} \ I^1(x,y) = x \geqslant 0 \wedge (x = y ee I^0(x+1,y)) \ = 0 \leqslant x = y$$

CSE, SNU, Seoul, 09/30/2008

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# **Iterates**

$$I^{0}(x,y) = \text{false} \qquad I^{0}(x,y) = \text{false} \qquad I^{0}(x,y) = x \geqslant 0 \land (x = y \lor I^{0}(x+1,y)) \qquad y \qquad x \geqslant 0 \land (x = y \lor I^{0}(x+1,y)) \qquad y \qquad x \geqslant 0 \land (x = y \lor I^{1}(x+1,y)) \qquad y \qquad x \geqslant 0 \land (x = y \lor I^{1}(x+1,y)) \qquad y \qquad x \geqslant 0 \leqslant x \leqslant y \leqslant x+1$$

# **Iterates**

$$Ierates \ I = \lim_{n \to \infty} F^n(\text{false}) \ y$$

$$I^0(x,y) = \text{false}$$

$$I^1(x,y) = x \geqslant 0 \land (x = y \lor I^0(x+1,y)) \qquad y$$

$$= 0 \leqslant x = y$$

$$I^2(x,y) = x \geqslant 0 \land (x = y \lor I^1(x+1,y)) \qquad y$$

$$= 0 \leqslant x \leqslant y \leqslant x+1$$

$$I^3(x,y) = x \geqslant 0 \land (x = y \lor I^2(x+1,y)) \qquad 1$$

$$= 0 \leqslant x \leqslant y \leqslant x+2$$

# Convergence acceleration: widening

Accelerated Iterates 
$$I = \lim_{n \to \infty} F^n(\text{false})$$
  $y$ 
 $I^0(x,y) = \text{false}$ 
 $I^1(x,y) = x \geqslant 0 \land (x = y \lor I^0(x+1,y))$   $y$ 
 $= 0 \leqslant x = y$ 
 $I^2(x,y) = x \geqslant 0 \land (x = y \lor I^1(x+1,y))$   $0$ 
 $= 0 \leqslant x \leqslant y \leqslant x+1$ 
 $I^3(x,y) = x \geqslant 0 \land (x = y \lor I^2(x+1,y))$   $0$ 
 $= 0 \leqslant x \leqslant y \leqslant x+2$ 
 $I^4(x,y) = I^2(x,y) \lor I^3(x,y) \leftarrow \text{widening}$ 
 $0 \leqslant x \leqslant y$ 

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# **Octagons**

Accelerated Iterates 
$$I = \lim_{n \to \infty} F^n(\text{false})$$
 $I^0(x,y) = \text{false}$ 

$$I^1(x,y) = x \geqslant 0 \land (x = y \lor I^0(x+1,y))$$

$$= 0 \leqslant x = y$$

$$I^2(x,y) = x \geqslant 0 \land (x = y \lor I^1(x+1,y))$$

$$= 0 \leqslant x \leqslant y \leqslant x+1$$

$$I^3(x,y) = x \geqslant 0 \land (x = y \lor I^2(x+1,y))$$

$$= 0 \leqslant x \leqslant y \leqslant x+2$$

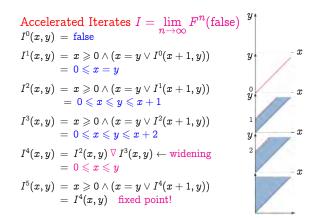
$$I^4(x,y) = I^2(x,y) \lor I^3(x,y) \leftarrow \text{widening}$$

$$= 0 \leqslant x \leqslant y$$

$$I^5(x,y) = x \geqslant 0 \land (x = y \lor I^4(x+1,y))$$

$$= I^4(x,y) \text{ fixed point!}$$

Fixed point



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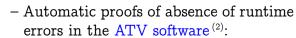
### Industrialisation: Development in cooperation with Airbus France

- Automatic proofs of absence of runtime errors in Electric Flight Control Soft-



- A340/600: 132.000 lines of C, 40mn on a PC 2.8 GHz, 300 Mb (Nov. 2003)
- A380: 1.000.000 lines of C, 34h, 8 Gb (Nov. 2005)

no false alarm, World premières!





- C version of the automatic docking software: 102.000 lines of C, 23s on a Quad-Core AMD Opteron<sup>™</sup> processor, 16 Gb (Apr. 2008)

The invariants are computer representable

with octagons!

<sup>(2)</sup> the Jules Vernes Automated Transfer Vehicle (ATV) enabling ESA to transport payloads to the International Space Station.

# Application of abstract interpretation to program proof methods

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# Maximal execution trace

```
#include <stdio.h>
                                                 Enter an integer: 3 Enter an integer: -1
                                                                        x = -1, y = -1
int main() {
                                                 x = 3, y = 3
                                                 x = 2, y = 5
                                                                        x = -2, y = 1
          printf("Enter an integer: ");
                                                                        x = -3, y = 3
                                                 x = 1, y = 7
          scanf("%d",&x); y = x;
                                                 x = 0, y = 9
                                                                        x = -4, y = 5
/* 1: */ while (x != 0) {
             printf("x = %d, y = %d\n",x,y);
                                                                        x = -738245, y = 1476487
/* 2: */
             x = x - 1:
/* 3: */
             y = y + 2;
/* 4: */ printf("x = %d, y = %d\n",x,y); }
                                               transition ∈ trans ¶P¶
initial state \in init \mathbb{P}
 (1:,3,3,3) \rightarrow (2:,3,3,3) \rightarrow (3:,3,2,3) \rightarrow (1:,3,2,5) \rightarrow (2:,3,2,5)
 \rightarrow (3:,3,1,5) \rightarrow (1:,3,1,7) \rightarrow (2:,3,1,7) \rightarrow (3:,3,0,7) \rightarrow
 (1:,3,0,9) \rightarrow (6:,3,0,9)
```

# Maximal execution trace

```
#include <stdio.h>
                                             Enter an integer: 3 Enter an integer: -1
int main() {
                                             x = 3, y = 3
                                                                  x = -1, y = -1
                                             x = 2, y = 5
                                                                   x = -2, y = 1
          printf("Enter an integer: ");
                                             x = 1, y = 7
                                                                  x = -3, y = 3
         scanf("%d",&x); y = x;
                                             x = 0, y = 9
                                                                   x = -4, y = 5
/* 1: */ while (x != 0) {
            printf("x = %d, y = %d\n",x,y);
                                                                   x = -738245, y = 1476487
/* 3: */
/* 4: */ printf("x = %d, y = %d\n",x,y); }
```

```
(1:,3,3,3) \rightarrow (2:,3,3,3) \rightarrow (3:,3,2,3) \rightarrow (1:,3,2,5) \rightarrow (2:,3,2,5) \rightarrow (3:,3,1,5) \rightarrow (1:,3,1,7) \rightarrow (2:,3,1,7) \rightarrow (3:,3,0,7) \rightarrow (1:,3,0,9) \rightarrow (6:,3,0,9)
```

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# Maximal trace semantics

- The trace semantics of a program is the set of all possible maximal finite or infinite execution traces for that program
- The trace semantics of a programing language maps programs to their trace semantics

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# Inductive definition

- Partial traces:
  - A trace with one initial state is a partial trace
  - A partial trace extended by a transition is a partial trace
- Maximal traces:
  - Finite traces with no extension by a transition
  - Infinite traces which prefixes are all partial traces

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# Invariance abstraction

- Collect at each control point the possible values of variables when execution reaches that control point
- $\alpha(X)c = \{m \mid \exists \sigma, \sigma'. \ \sigma\langle c, m \rangle \sigma' \in X\}$
- Invariance semantics:  $S^i \llbracket P \rrbracket = \alpha(S^t \llbracket P \rrbracket)$

# Fixpoint partial trace semantics

- initial states of program P: init[P]
- transitions of programs P: trans [P]
- $F^t[P]X = \{ s \mid s \in init[P] \} \cup \{ \sigma ss' \mid \sigma s \in X \land ss' \in trans[P] \}$
- $\bullet \ \mathrm{S}^t \llbracket \mathtt{P} \rrbracket = \mathsf{Ifp}^{\scriptscriptstyle \subseteq} \ \mathrm{F}^t \llbracket \mathtt{P} \rrbracket$

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# Invariance abstraction

- Collect at each control point the possible values of variables when execution reaches that control point
- $S^{i}[P] = \alpha(S^{t}[P])c = \{m \mid \exists \sigma, \sigma'. \ \sigma(c,m)\sigma' \in S^{t}[P]\}$

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# Calculations design of the verification conditions

- $\begin{array}{l} \bullet \quad \alpha(\mathrm{F^t}[\![\![\!]\!]X) \\ = \mathbf{\lambda} \, \mathrm{c.} \{\mathrm{m} \mid \exists \sigma,\! \sigma'. \ \sigma \langle \mathrm{c,m} \rangle \sigma' \in X\} \\ = \ldots \\ = \mathrm{F^i}[\![\![\![\!]\!]\!](\alpha(X)) \\ \text{where } \mathrm{F^i}[\![\![\![\!]\!]\!] \text{ are the Turing/Floyd/Naur/Hoare} \end{array}$
- $\bullet$  It follows that  $S^i[\![P]\!] = \mathsf{lfp}^{\dot{\varsigma}} \; F^i[\![P]\!]$

verification conditions

 The proof method is then by fixpoint induction (Tarski 1955)

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# General idea

 All known semantics are abstractions of a most precise semantics

# Application to the semantics of programming languages

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# Abstraction to denotational semantics

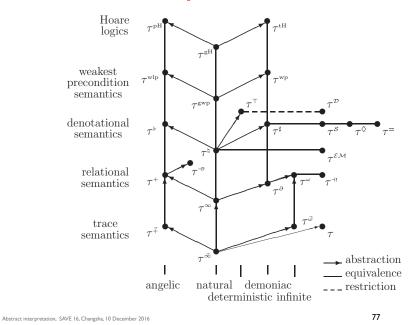
- $\bullet$  The maximal trace semantics  $S^m[\![P]\!]$  (maximal finite and infinite execution traces
- Denotational semantics abstraction:

$$\bullet \ S^d[\![P]\!] = \alpha(S^m[\![P]\!])$$

• 
$$\alpha(X) = \lambda s.\{s' \mid \exists \sigma. \ s\sigma s' \in X\} \cup \{\bot \mid \exists \sigma. \ s\sigma ... \in X\}$$

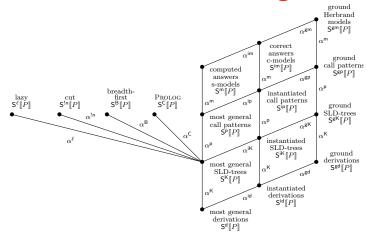
i.e. a map of initial states to the set of final states plus  $\bot$  in case of non-termination

# Hierarchy of abstractions



Conclusion

# idem for Prolog



• all semantics are abstractions of  $S^d[P]$ 

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# Abstract interpretation

- A well-developed theory, still in progress
- Active research e.g.

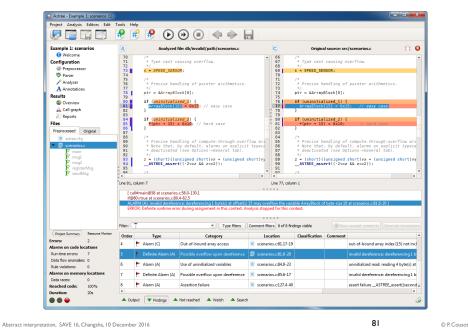
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- abstract domains to handle e.g. complex data structures
- abstraction of parallelism with weak memory models
- applications to biology, ...
- Industrial-quality static analyzers

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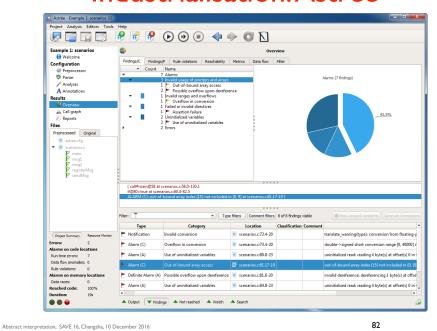
# Industrialisation: Astrée



# Many other static analyzers

- Julia (Java) http://www.juliasoft.com
- Ikos, NASA https://ti.arc.nasa.gov/opensource/ikos/
- Clousot for code contract, Microsoft, https://github.com/Microsoft/CodeContracts
- Infer (Facebook) http://fbinfer.com
- Zoncolan (Facebook)
- Google
- ...

# Industrialisation: Astrée



# Static analysis for software development

Users of Astrée:

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Why not all software developers use static analysis tools?

# Irresponsibility

• Computer engineering is the only technology where developers are not responsible for their errors, even the trivial ones:

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Francesco Logozzo, designer of the Zoncolan static analyzer at Facebook wrote me on 09/12/2016:

"Finding people who really know static analysis is very hard, you should tell your students that if they want a great job in a Silicon Valley company they should study abstract interpretation not JavaScript. Feel free to quote me on that ;-)"

# The future

- Safety and security does matter to the general public
- Computer scientists will ultimately be held responsible for there errors
- At least the automatically discoverable ones
- Since this is now part of the state of the art
- Automatic static analysis, verification, etc has a brilliant future.

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# The End, Thank You

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