

# V22.0453-001: Honors Theory of Computation

## Problem Set 5 Solutions

### Problem 1

**Solution:** Let  $M_L$  be the Turing machine that recognizes  $L$ . This means that on every  $w \in L$ ,  $M_L$  accepts, and on every  $x \notin L$ ,  $M_L$  either rejects or never halts.

Note that  $\Sigma^*$  is a countable set. Let  $x_1, x_2, x_3, \dots$  denote an ordering of all strings in  $\Sigma^*$ . For example, one can order strings in increasing order of length, and strings with the same length can be ordered lexicographically.

Note also that the set  $\mathbf{N} \times \mathbf{N}$  is countable (where  $\mathbf{N}$  is the set of natural numbers). Let  $(i_1, j_1), (i_2, j_2), (i_3, j_3), \dots$  denote an ordering of  $\mathbf{N} \times \mathbf{N}$ . For example, one can order the pairs in increasing order of the sum of two co-ordinates, and pairs with the same sum can be ordered in increasing order of the first co-ordinate.

Define the required machine  $M$  as follows:

For  $k = 1, 2, 3, \dots$  do:

- Let  $(i_k, j_k)$  be the  $k^{\text{th}}$  pair in the ordering of  $\mathbf{N} \times \mathbf{N}$ .
- Simulate the machine  $M_L$  on string  $x_{i_k}$  for  $j_k$  steps.
- If  $M_L$  accepts, then print the string  $x_{i_k}$  on the output tape, and print the symbol  $\#$ .

Clearly,  $M$  prints only those strings that are accepted by  $M_L$ , i.e. the strings in  $L$ . On the other hand, for any  $w \in L$ ,  $w$  is accepted by  $M_L$  in (say)  $t$  steps. Suppose  $w = x_i$  in the ordering of  $\Sigma^*$ . When the machine  $M$  works on the pair  $(i, t)$  (it will, eventually), it prints  $x_i$  on the output tape.

### Problem 2

**Solution:** It is clear that Set-Cover  $\in \mathbf{NP}$ , as an NTM can decide whether  $\langle \mathcal{S} = \{S_1, \dots, S_m\}, k \rangle \in \text{Set-Cover}$  by nondeterministically guessing a subcollection  $\{S_{i_1}, \dots, S_{i_k}\}$  of size  $k$ , and verifying whether  $\cup_{j=1}^k S_{i_j} = \cup_{j=1}^m S_j$ .

To show that Set-Cover is **NP-Complete**, we give a polynomial-time reduction from Vertex-Cover to Set-Cover, as follows:

On input a Vertex-Cover instance  $\langle G = (V, E), k \rangle$ :

1. Let  $U = E$ , that is, the universe  $U$  is the set of edges in  $G$ .
2. For each vertex  $v \in V$  in  $G$ , define  $S_v = \{(u, v) : (u, v) \in E\}$ . That is,  $S_v$  is the set of all edges incident with  $v$ .
3. Let  $\mathcal{S} = \{S_v : v \in V\}$ . That is, the collection  $\mathcal{S}$  consists of  $S_v$  for every vertex  $v \in V$ .
4. Output  $\langle \mathcal{S}, k \rangle$ .

Clearly the reduction takes polynomial time. We now show that the reduction is correct, that is,  $\langle G, k \rangle \in \text{Vertex-Cover}$  if and only if  $\langle \mathcal{S}, k \rangle \in \text{Set-Cover}$ .

If  $\{v_1, \dots, v_k\}$  is a vertex cover in  $G$ , then  $\cup_{i=1}^k S_{v_i} = E = U$ , and thus  $\{S_{v_1}, \dots, S_{v_k}\}$  is a set cover in  $\mathcal{S} = \{S_v : v \in V\}$ . Conversely, if  $\{S_{v_1}, \dots, S_{v_k}\}$  is a set cover in  $\mathcal{S}$ , then  $\cup_{i=1}^k S_{v_i} = E = U$ , and thus  $\{v_1, \dots, v_k\}$  is a vertex cover in  $G$ .

We therefore conclude that Set-Cover is **NP-Complete**.

### Problem 3

**Solution to Part 1:** Suppose that  $\mathbf{P} = \mathbf{NP}$ . Then there is a polynomial-time algorithm  $A$  that decides 3-SAT. We now describe an algorithm  $B$  that actually finds a satisfying solution to any given 3-SAT instance  $\varphi$  that is satisfiable by invoking algorithm  $A$   $n$  times, where  $n$  is the number of variables in  $\varphi$ . Therefore, if  $A$  runs in polynomial-time, then  $B$  runs in polynomial-time.

**Algorithm B:**

On input  $\varphi(x_1, \dots, x_n)$ :

1. Run algorithm  $A$  on  $\varphi$  to decide whether  $\varphi$  is satisfiable. If not, then output NO and halt. If  $\varphi$  is satisfiable, then the rest of the algorithm finds a satisfying assignment in  $n$  iterations, as follows.
2. Define formulas  $\varphi_0(x_2, \dots, x_n) = \varphi(0, x_2, \dots, x_n)$  and  $\varphi_1(x_2, \dots, x_n) = \varphi(1, x_2, \dots, x_n)$ . That is,  $\varphi_0$  and  $\varphi_1$  are the resulting formulas after  $x_1$  is substituted by constants 0 and 1 respectively. If  $\varphi$  is satisfiable, then clearly *at least one* of  $\varphi_0$  and  $\varphi_1$  must be satisfiable, as in any satisfying assignment  $x_1$  is assigned either 0 or 1. Thus, in the first iteration, first run algorithm  $A$  on  $\varphi_0$  to decide whether  $\varphi_0$  is satisfiable, and if so, set  $a_1 = 0$ ; else  $\varphi_1$  must be satisfiable, and set  $a_1 = 1$ . Assign  $x_1 = a_1$ , and repeat the above for  $\varphi_{a_1}$  until all variables have been assigned. That is:
3. In general, in the  $i$ -th iteration, with  $a_1, \dots, a_{i-1}$  already assigned to  $x_1, \dots, x_{i-1}$  in the first  $i - 1$  iterations so that  $\varphi_{a_1, \dots, a_{i-1}}(x_i, \dots, x_n) = \varphi(a_1, \dots, a_{i-1}, x_i, \dots, x_n)$  is satisfiable, set

$$\varphi_{a_1, \dots, a_{i-1}, 0}(x_{i+1}, \dots, x_n) = \varphi(a_1, \dots, a_{i-1}, 0, x_{i+1}, \dots, x_n),$$

and

$$\varphi_{a_1, \dots, a_{i-1}, 1}(x_{i+1}, \dots, x_n) = \varphi(a_1, \dots, a_{i-1}, 1, x_{i+1}, \dots, x_n).$$

Then as above, *at least one* of  $\varphi_{a_1, \dots, a_{i-1}, 0}$  and  $\varphi_{a_1, \dots, a_{i-1}, 1}$  must be satisfiable. Thus, first run algorithm  $A$  on  $\varphi_{a_1, \dots, a_{i-1}, 0}$  to decide whether it is decidable, and if so, set  $a_i = 0$ ; else  $\varphi_{a_1, \dots, a_{i-1}, 1}$  must be satisfiable, and set  $a_i = 1$ .

4. Repeat the above process until all variables  $x_1, \dots, x_n$  have been assigned, and output the assignment  $x_1 = a_1, \dots, x_n = a_n$ .

If  $\varphi$  is not satisfiable, then algorithm  $B$  outputs NO at the beginning. If  $\varphi$  is satisfiable, then the assignment  $x_1 = a_1, \dots, x_n = a_n$  found by  $B$  satisfies  $\varphi$  as explained in the description of algorithm  $B$ . The claimed polynomial running time of  $B$  can be easily verified.

**Solution to Part 2:** Define the language

$$\text{MAX-3-SAT} = \{ \langle \varphi, k \rangle : \varphi \text{ is in 3-CNF and } \exists \text{ an assignment that satisfies } k \text{ clauses of } \varphi \}.$$

Clearly  $\text{MAX-3-SAT} \in \mathbf{NP}$ , as an NTM can decide whether  $\langle \varphi, k \rangle \in \text{MAX-3-SAT}$  by nondeterministically guessing an assignment and verifying whether it satisfies  $k$  clauses of  $\varphi$ . Therefore if  $\mathbf{P} = \mathbf{NP}$ , then there is a polynomial-time algorithm  $C$  that decides MAX-3-SAT. We now construct the following algorithm  $D$  that finds an assignment that satisfies the maximum number of clauses in a given  $\varphi$  using this algorithm  $C$ . Algorithm  $D$  uses essentially the same technique as algorithm  $B$  does.

**Algorithm D:**

On input  $\varphi(x_1, \dots, x_n) = C_1 \wedge \dots \wedge C_m$ , where  $m$  is the number of clauses in  $\varphi$ :

For  $k = m$  downto 0:

1. If  $k = 0$ , then output any assignment and halt. Else,
2. Run algorithm  $C$  on  $\langle \varphi, k \rangle$  to decide whether there is an assignment that satisfies  $k$  clauses of  $\varphi$ . If  $C$  outputs NO, then go to the next iteration. Else (if  $C$  outputs YES), we find such an assignment as follows:
3. Set  $\varphi_0(x_2, \dots, x_n) = \varphi(0, x_2, \dots, x_n)$  and  $\varphi_1(x_2, \dots, x_n) = \varphi(1, x_2, \dots, x_n)$  as in algorithm  $B$ . Then *at least one* of  $\varphi_0$  and  $\varphi_1$  has an assignment that satisfies at least  $k$  clauses. Thus first run algorithm  $C$  on  $\langle \varphi_0, k \rangle$ , and if  $C$  accepts, set  $a_1 = 0$ ; else set  $a_1 = 1$ . Repeat this for  $\varphi_{a_1}$  in a way similar to algorithm  $B$ , until all variables have been assigned.
4. Output  $x_1 = a_1, \dots, x_n = a_n$  and halt.

It is not hard to see that algorithm  $D$  finds an assignment that satisfies the maximum number of clauses of a given formula  $\varphi$ , and it takes polynomial time provided that  $C$  runs in polynomial time.

**Problem 4**

**Solution:** We show that **Subset-Sum** is a special case of **Knapsack**. Consider special instances of **Knapsack** where the volumes and costs are the same, i.e.  $v_i = c_i \forall i$ , and the volume bound equals the target cost, i.e.  $B = t$ . The **Knapsack** problem asks whether there exists a set  $S \subseteq \{1, 2, \dots, n\}$  such that

$$\sum_{i \in S} c_i \geq t \quad \text{and} \quad \sum_{i \in S} v_i \leq B \tag{1}$$

which is same as asking whether there exists  $S$  such that

$$\sum_{i \in S} v_i \geq t \quad \text{and} \quad \sum_{i \in S} v_i \leq t$$

which is same as asking whether there exists  $S$  such that

$$\sum_{i \in S} v_i = t$$

which is an instance of **Subset-Sum**.

Therefore, since **Subset-Sum** is a **NP-hard** problem, so is **Knapsack**. On the other hand, **Knapsack** is in **NP** (guess the set  $S$  and verify whether Condition (??) is satisfied). Hence **Knapsack** is **NP-complete**.

**Problem 5**