

Computational Illumination

Ramesh Raskar, Computational Illumination

Computational Illumination

SIGGRAPH 2006 Course

Course WebPage :
<http://www.merl.com/people/raskar/photo/>

Ramesh Raskar
Mitsubishi Electric Research Labs

Computational Illumination

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Edgerton 1930's

Not Special Cameras but Special Lighting

Edgerton 1930's

Stroboscope
(Electronic Flash)

Multi-flash
Sequential Photography

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Computational Illumination:

- Presence or Absence, Duration, Brightness
 - Flash/No-flash
- Light color/wavelength
- Light position
 - Multi-flash for depth edges
 - Programmable dome (image re-lighting and matting)
- Spatial Modulation
 - Dual Photography

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Denoising Challenging Images

Available light:

- + nice lighting
- noise/blurriness
- color



No-flash


Flash:

- + details
- + color
- flat/artificial



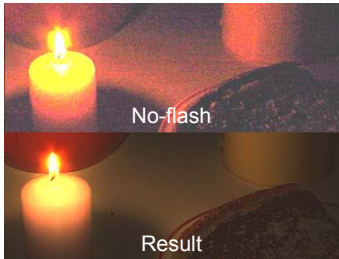
Elmar Eisemann and Frédo Durand, Flash Photography Enhancement via Intrinsic Relighting
Georg Petschnigg, Maneesh Agrawala, Hugues Hoppe, Richard Szeliski, Michael Cohen, Kentaro Toyama, Digital Photography with Flash and No-Flash Image Pairs.

Denoise no-flash image using flash image



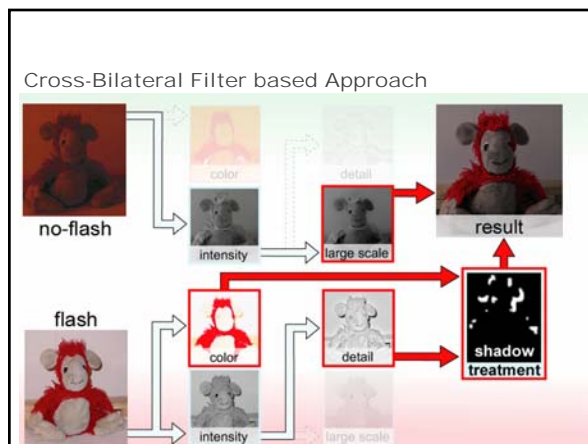
No-flash Flash Result

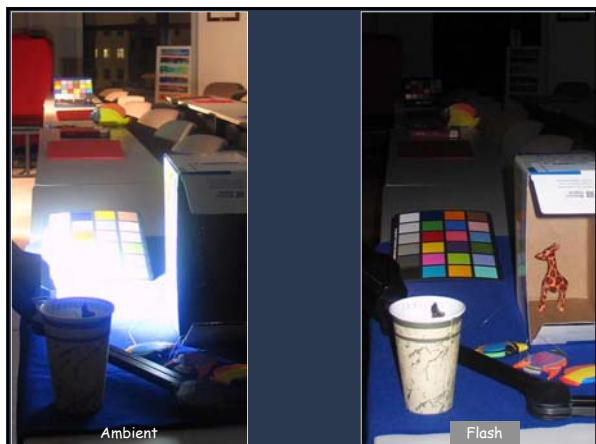
Transfer detail from flash image to no-flash image



No-flash Result Flash

- + original lighting
- + details/sharpness
- + color





Build Exposure HDR image

- Multiple images with different exposure
 - Debevec & Malik, Siggraph 97
 - Nayar & Mitsunaga, CVPR 00

Increasing Exposure →

Build Flash HDR image

Flash Intensity ↑

Build Flash-Exposure HDR image

Flash Intensity ↑

Exposure →

Agrawal, Raskar, Nayar, Li
Siggraph05

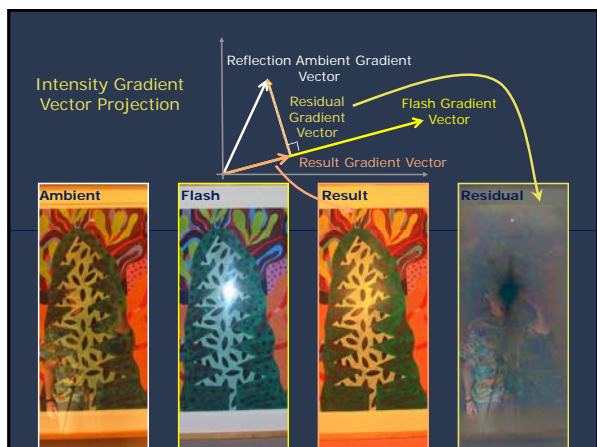
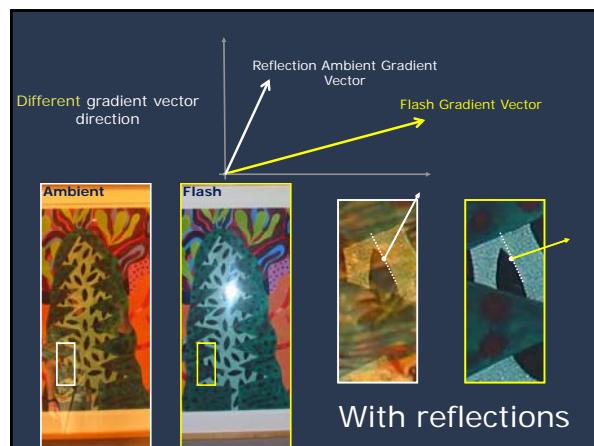
Capturing HDR Image

Varying Exposure time Varying Flash brightness Varying both

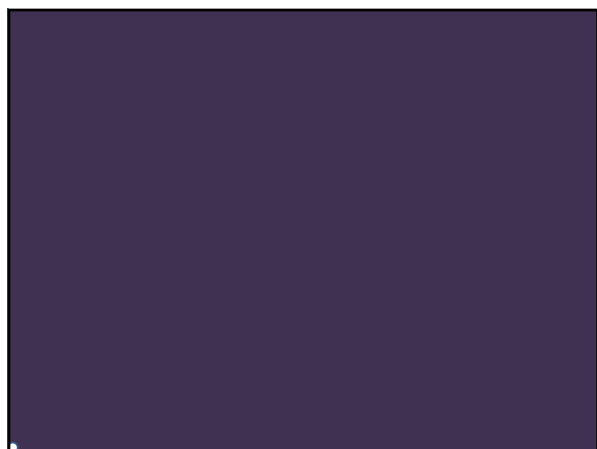
Flash and Ambient Images

[Agrawal, Raskar, Nayar, Li Siggraph05]

Ambient Flash Result Reflection Layer



- Computational Illumination:**
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Dark Flash Photography

Dilip Krishnan and Rob Fergus

Dept. of Computer Science,
Courant Institute,
New York University

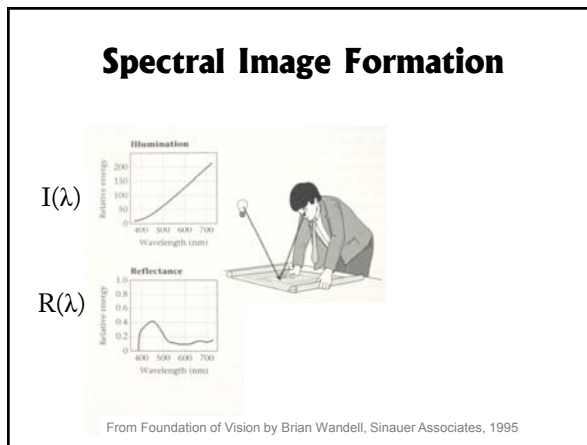
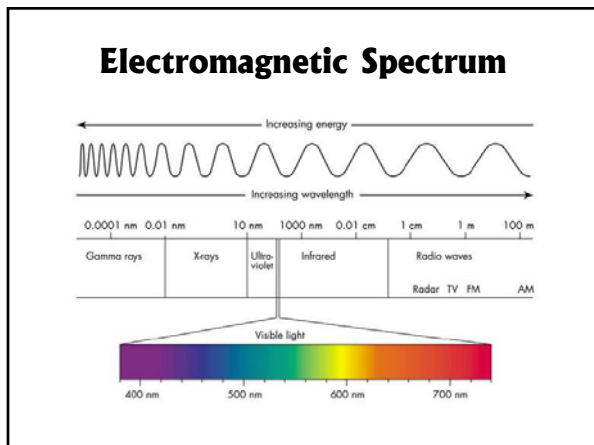


Dark Flash Photography

- Dark flash is ~200 times dimmer than conventional

Dark flash image Ambient image Reconstruction Ground truth

F



Spectral Image Formation

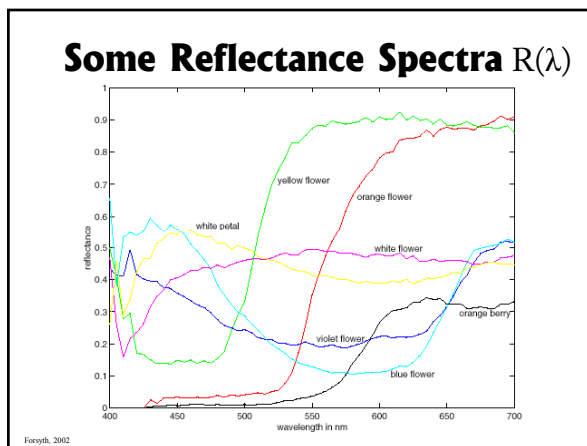
$$p_c = \int I(\lambda) S_c(\lambda) R(\lambda) d\lambda$$

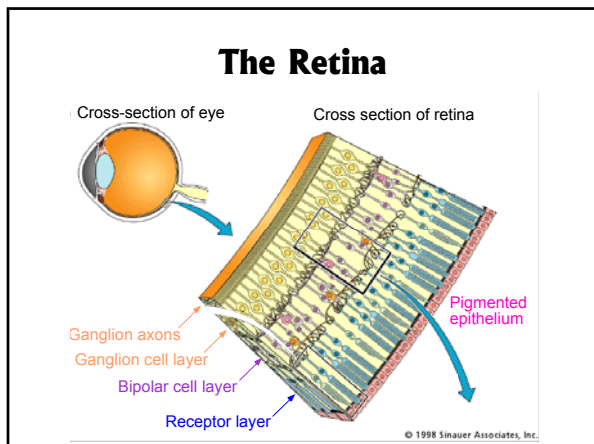
$I(\lambda)$ - Illumination Spectrum

$S_c(\lambda)$ - Spectral sensitivity of channel c
Properties of illumination/sensor

$R(\lambda)$ - Surface reflectance/transmission
Property of the scene

Pixel value / Perceived color depends on all 3 terms





Two Types of Light Sensitive Receptors

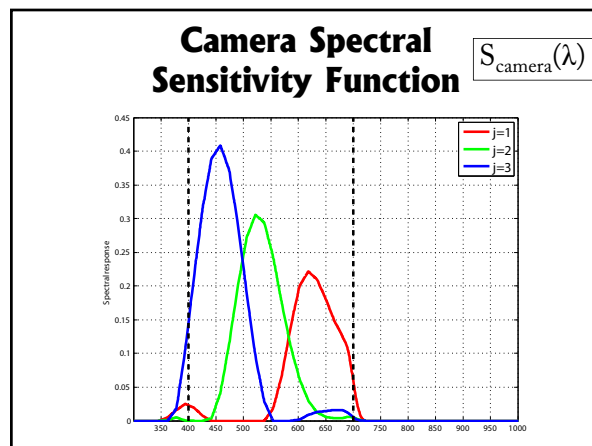
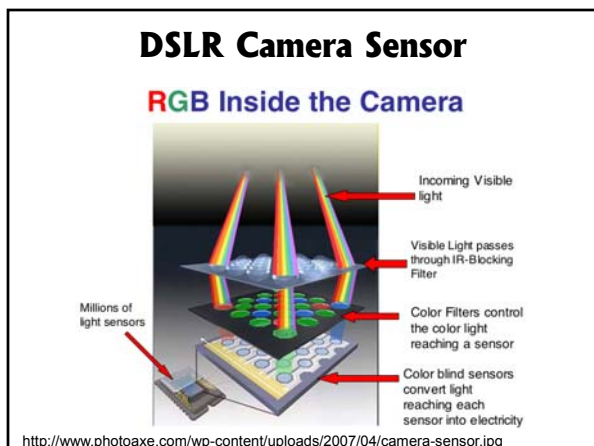
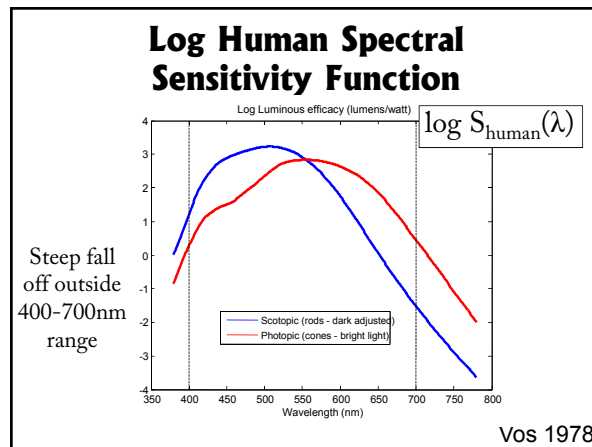
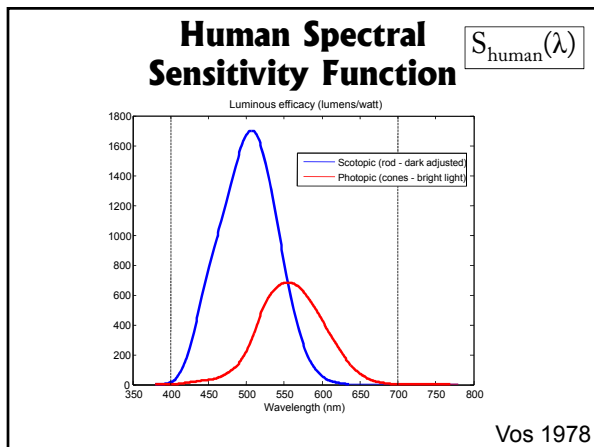
Cones

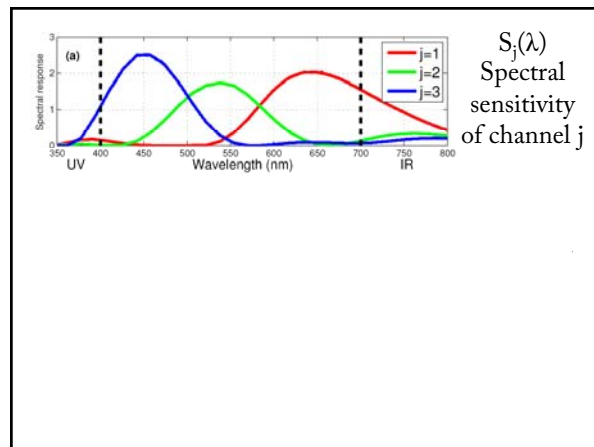
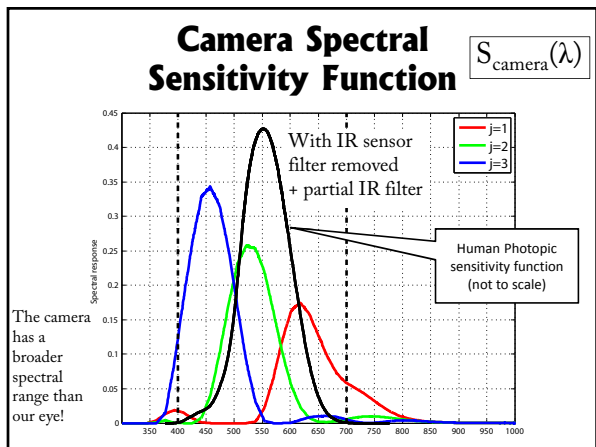
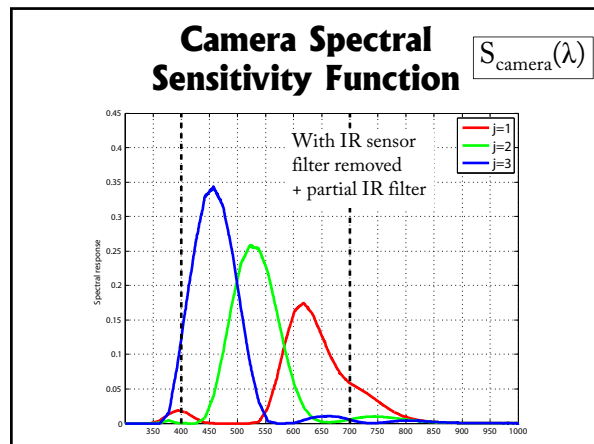
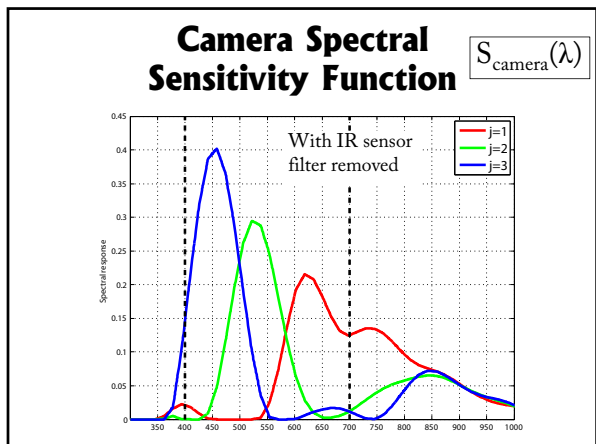
- cone-shaped
- color vision
- less sensitive
- Photopic -- operate in high light

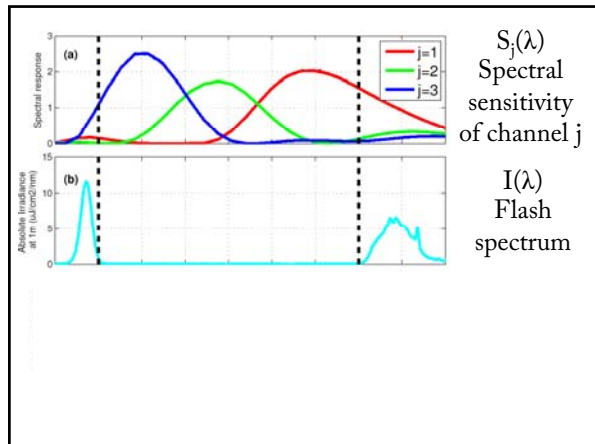
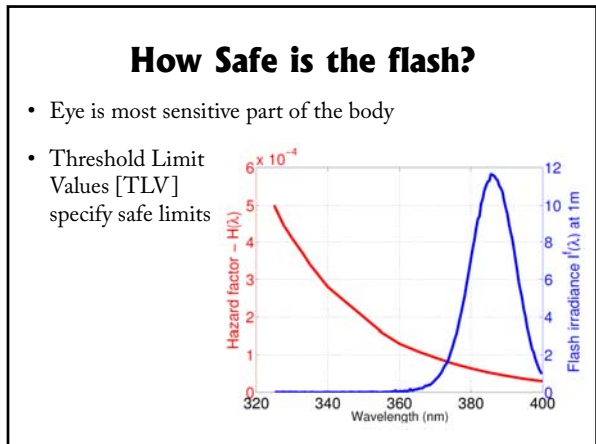
Rods

- rod-shaped
- gray-scale vision
- highly sensitive
- Scotopic -- operate in low light

cone
rod







Recording Five Different Spectral Bands

- Need two images
 - Temporal multiplexing
- With UV/IR flash image:
 - “Blue” channel records UV
 - “Red” channel records IR

Assumptions

1. Little ambient UV and IR light
2. UV/IR flash dominates ambient visible light

Flash/No-flash photography

- Visible flash & ambient (no flash) image
- Petsnigg et al. SIGGRAPH 2004
- Eisemann & Durand SIGGRAPH 2004
- Cross/Joint-bilateral filter combines images

Related Work

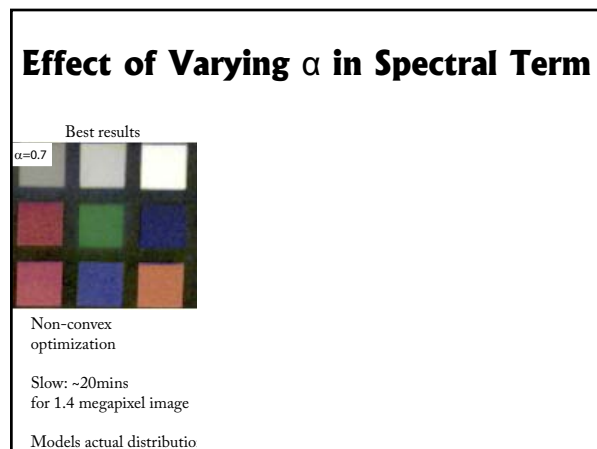
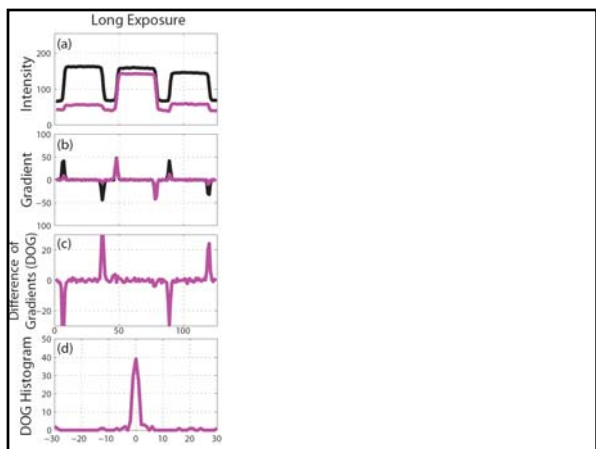
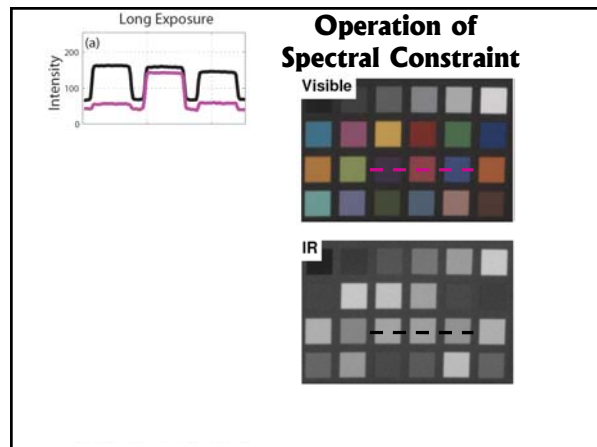
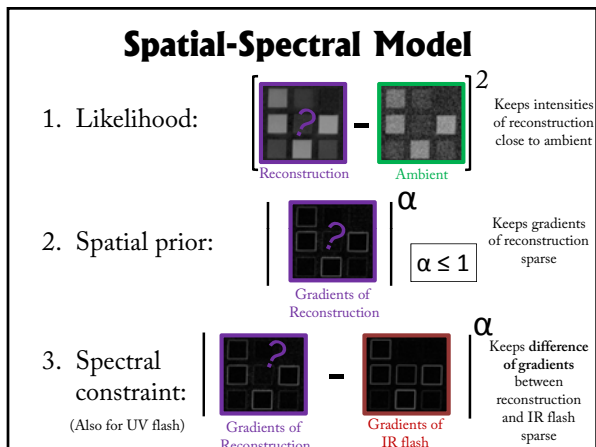
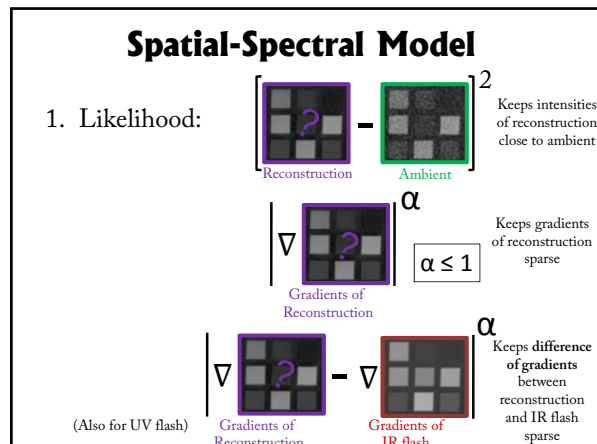
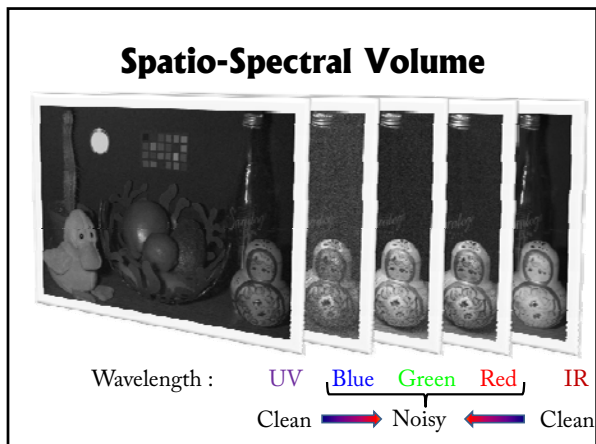
- Relighting faces with IR (Wang et al. Eurographics '08)
- Multispectral Video Fusion
 - Bennett, Mason and McMillan IEEE TIP '07
 - Twin cameras: IR/Visible
 - Temporal smoothing
 - Cross-bilateral filter

Our Approach

Typical scene

1. Dark Flash image

2. Ambient image

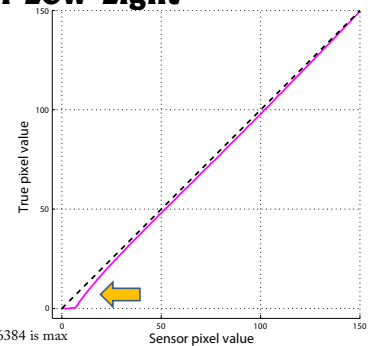


Overall Scheme

- Pre-processing
 - White balance
 - Masking of shadows in dark flash image
- Optimization of spatial-spectral model
 - Each channel in reconstruction estimated separately
- Post-processing
 - Removal of color cast
 - Gamma correction

Sensor Non-Linearity in Low Light

- Due to noise processes in sensor
- Introduces color cast if channels have different levels



Color Cast Correction

- Use noise curve

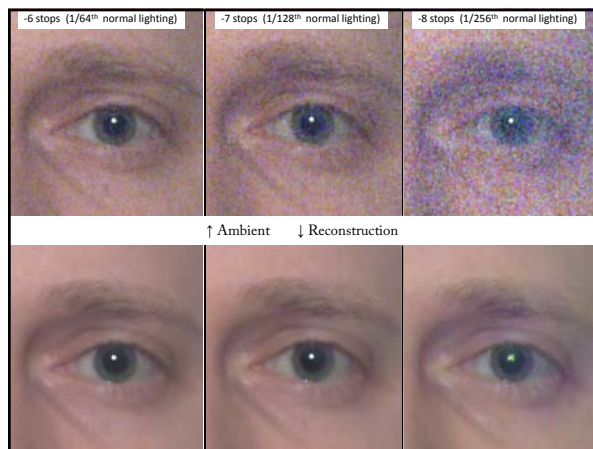
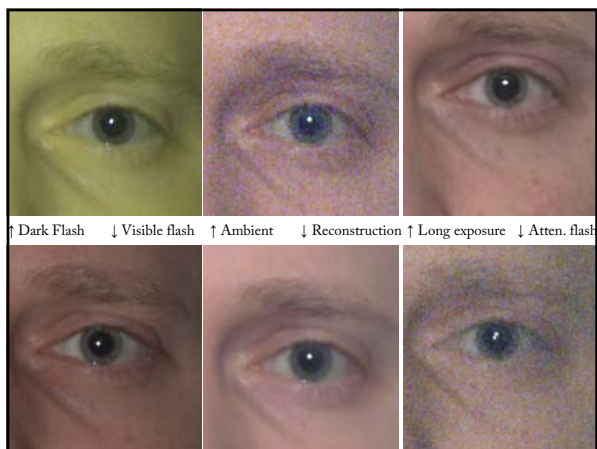


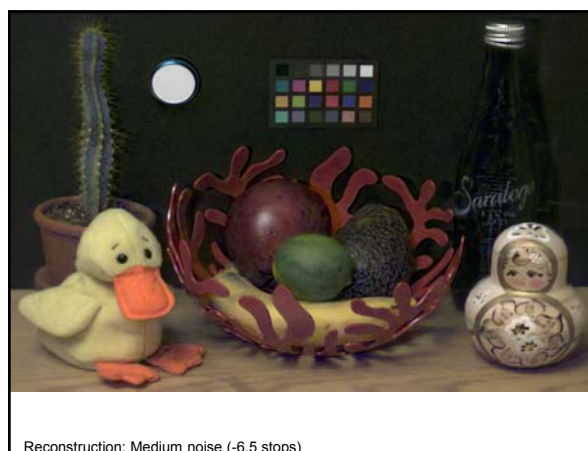
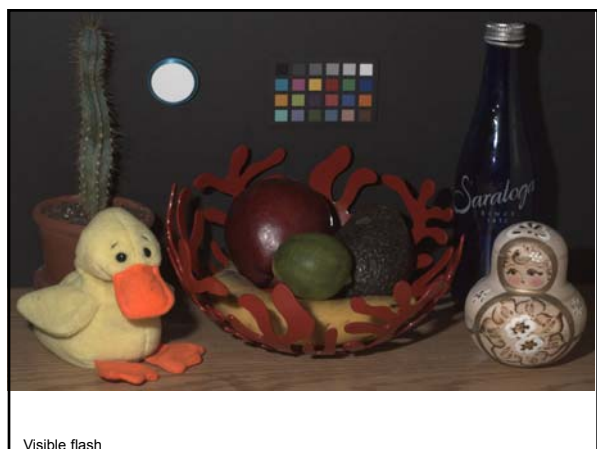
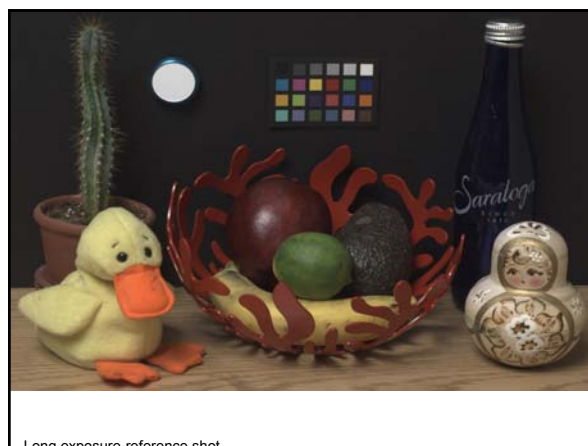
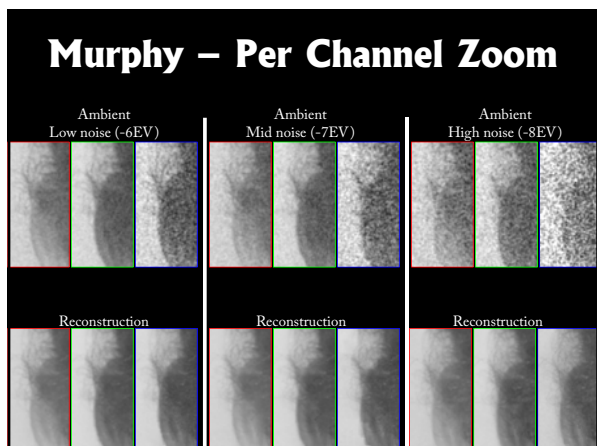
- Only form of color correction used
- Further correction color possible
e.g. leveraging face detector

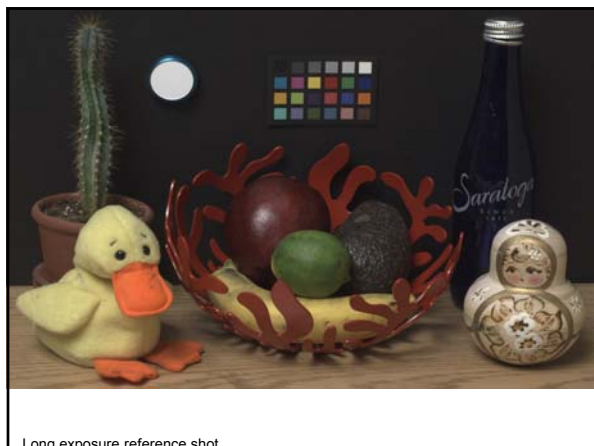
Experiments

- People & General scenes
 - Wide range of materials
- Explore different levels of ambient lighting
- Comparison to other approaches
- All scenes captured with a tripod, $\alpha = 0.7$









Doll image, Per Channel Close-up

Ambient Red Green Blue
Reconstruction Reconstruction Reconstruction Reconstruction

Low noise (-5 stops 1/32nd)

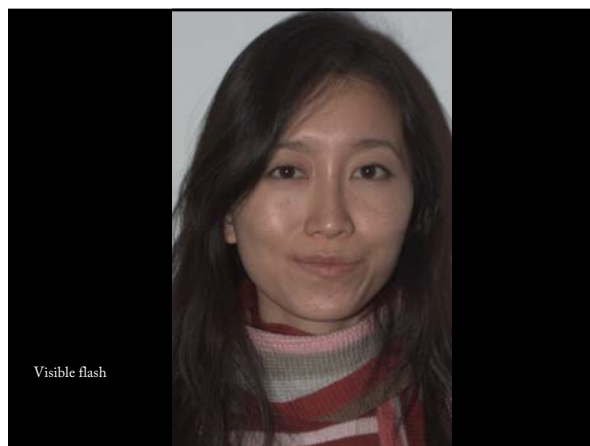
Mid noise (-6 stops 1/64th)

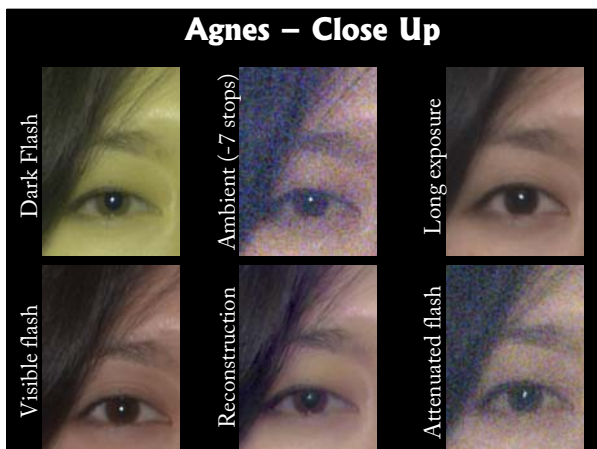
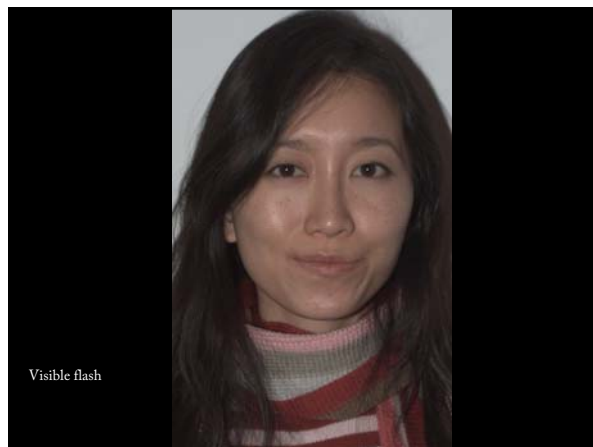
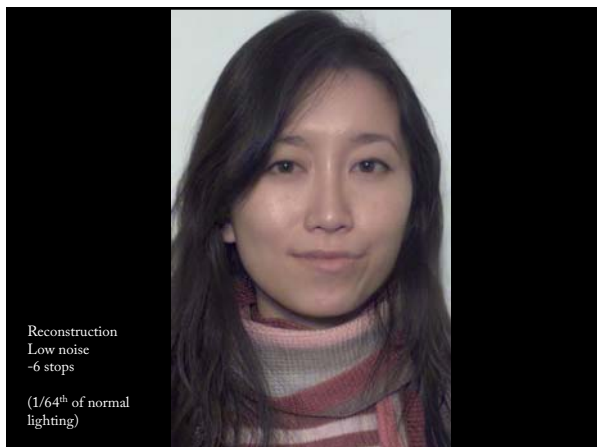
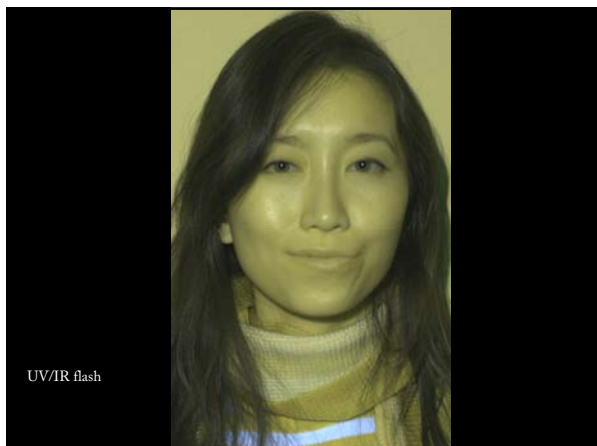
High noise (-7 stops 1/128th)

Doll image - Close-up

Dark flash Low noise (-5 stops, 1/32nd) Mid noise (-6 stops, 1/64th) High noise (-7 stops, 1/128th)

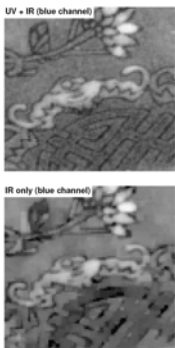
Long Exposure (Ground truth) ↑ Ambient ↓ Reconstruction





Are both IR and UV Flash Channels Needed?


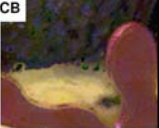

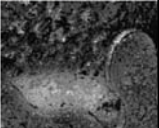

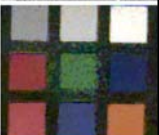
UV + IR (blue channel)



Effect of removing UV flash component

Comparison to Cross-Bilateral Filtering

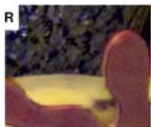


- Cross bilateral filtering is method used in flash/no-flash papers (Petsnigg et al., Eiseman & Durand Siggraph 2004)
- Also known as joint bilateral filtering
- Has L2-like constraint between color channels
 - Similar to $\alpha=2$

	Our model	Cross-bilateral
R		
CB		
		

Comparison to Denoising Methods


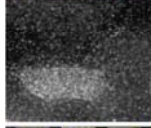

Our model

R




Bilateral filter on ambient

B

Noise Ninja on ambient

NN

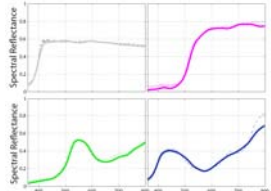
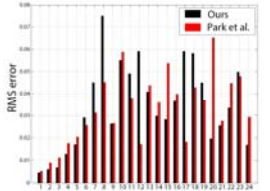




Other Applications

1. Spectroscopy (Hardware)
2. Color channel denoising (Software)

1. Spectroscopy


- Reconstruct $R(\lambda)$ using two images:
 1. With dark flash
 2. With visible-only flash
 Model $R(\lambda)$ using 6-dim PCA projections
- Comparison to Park et al. ICCV '07 on Macbeth color chart squares

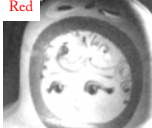
2. Color Channel Denoising

Candle-lit scene, after white balancing

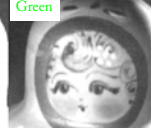
Captured by unmodified camera




Red



Green



Blue



2. Color Channel Denoising

- Denoise blue channel
- Spectral terms use red and green channels as constraint on blue



- Technique can be applied to images captured with a standard camera

Off-the-shelf Hardware

Standard
Nikon
50mm
f/1.8 lens
(~\$80)
+
MaxMax
CC3 filter
(~\$50)



Hoya U360
filter glass
(~\$200)

Fuji IS Pro (~\$3000)
Comes without IR filter sensor

Nikon SB-14 flash (~\$200)

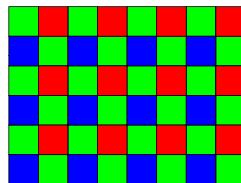
Improving the Hardware

- Can use LEDs for flash
 - Narrow spectral width
 - Good for cell phones (low power, compact)
- Need to two separate images is awkward
 - Some cameras have sensors with double image buffer, e.g. Fuji finePix Z10d



Single Shot Dark Flash Photography

Standard Bayer
3 channels



Summary

- Dark flash system that can capture images in low light conditions without dazzling subjects
- Spatial-spectral model with novel spectral constraints
- Future work:
 - Better color correction
 - Improve hardware to require only a single shot

Acknowledgements


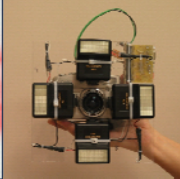
- Fredo Durand, Yann LeCun, Anat Levin, Olga Sorkine, Dennis Zorin
- Subjects: Agnes Chen, Murphy Stein
- MaxMax.com for camera hardware


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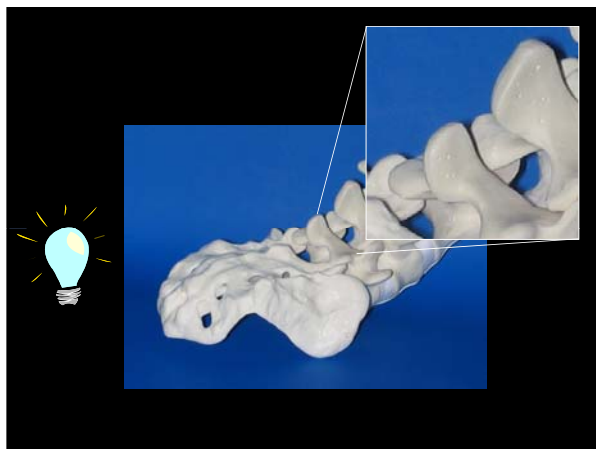
Computational Illumination:

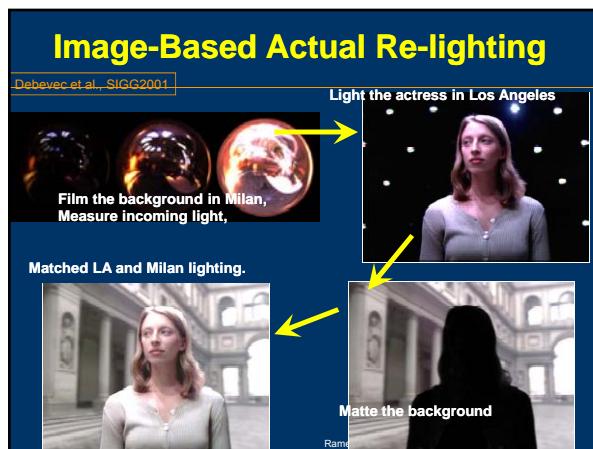
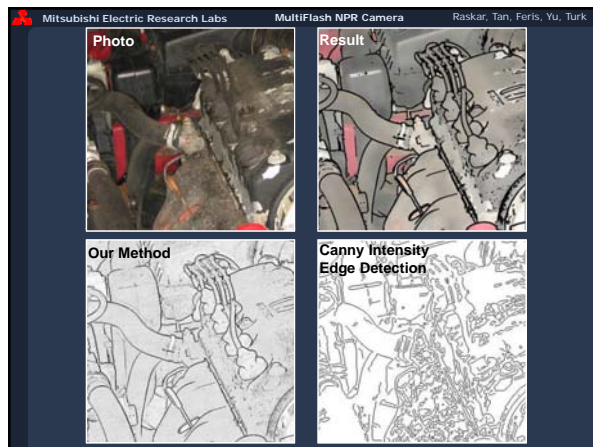
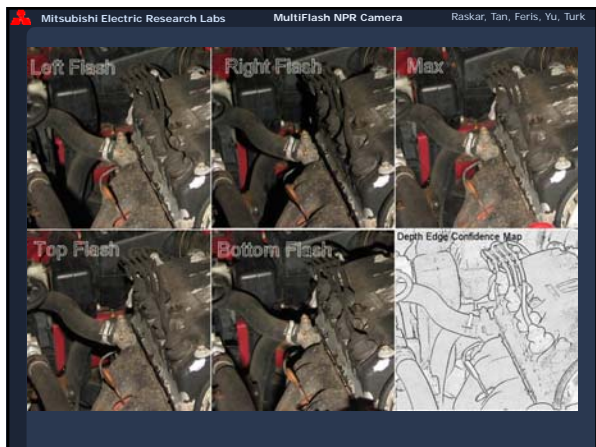
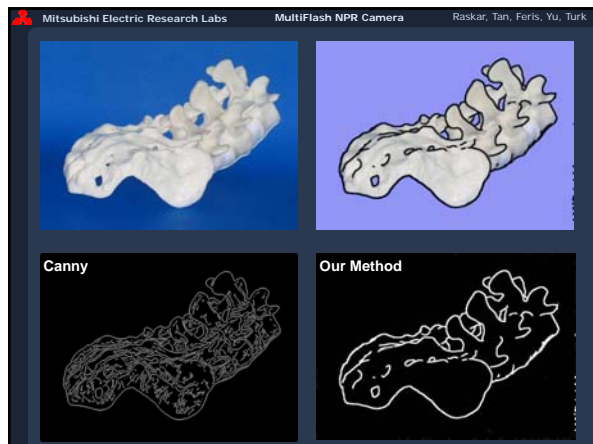
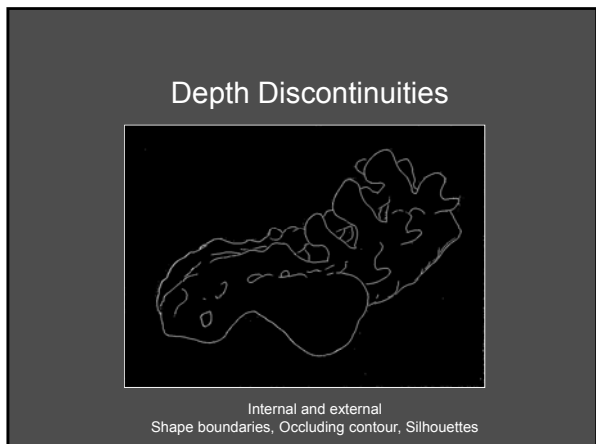
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- Spatial Modulation
 - Dual Photography

Non-photorealistic Camera: Depth Edge Detection and Stylized Rendering using Multi-Flash Imaging


 Ramesh Raskar, Karhan Tan, Rogerio Feris,
 Jingyi Yu, Matthew Turk
 Mitsubishi Electric Research Labs (MERL), Cambridge, MA
 U of California at Santa Barbara
 U of North Carolina at Chapel Hill





A 4-D Light Source

[Debevec et al. 2000] [Masselus et al. 2002] [Matusik et al. 2002]

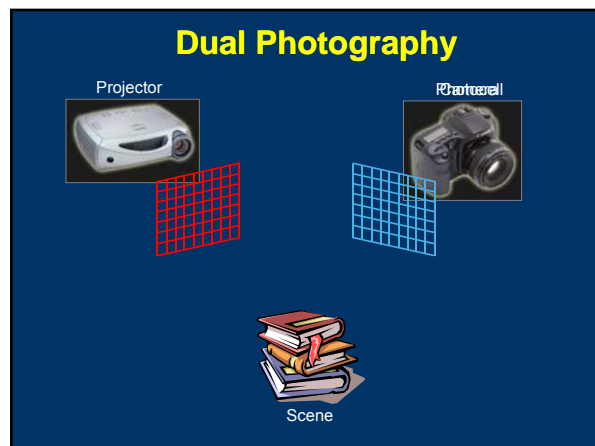
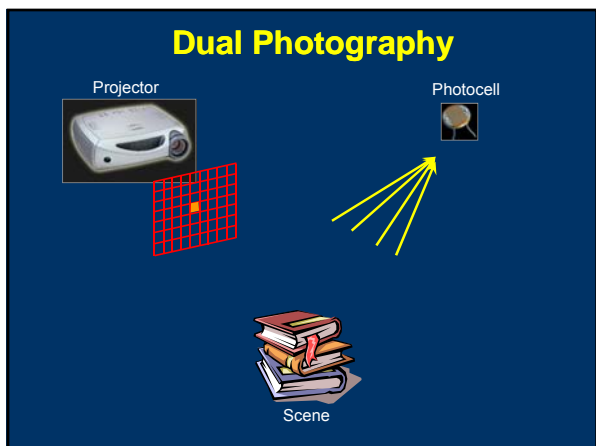
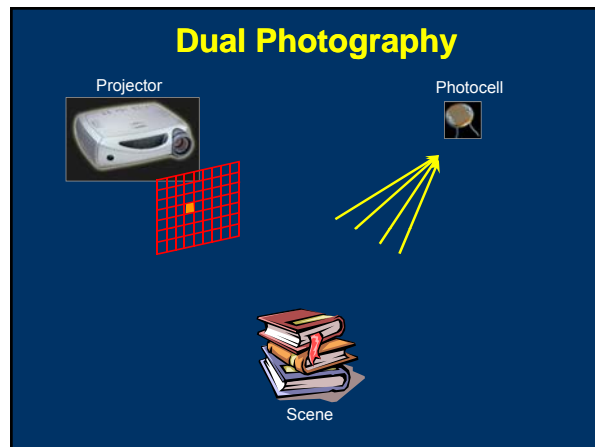
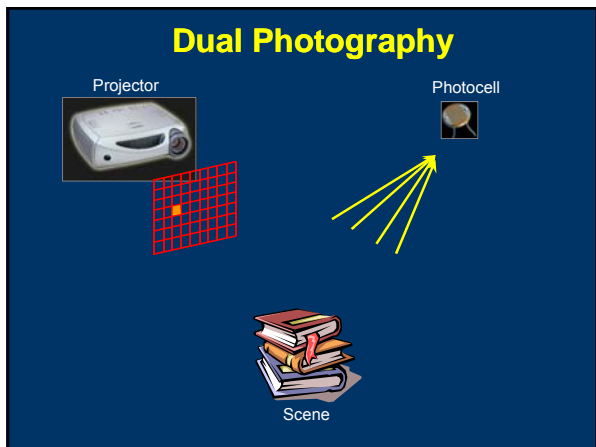
[Debevec et al. 2002] [Masselus et al. 2003] [Malzbender et al. 2002]

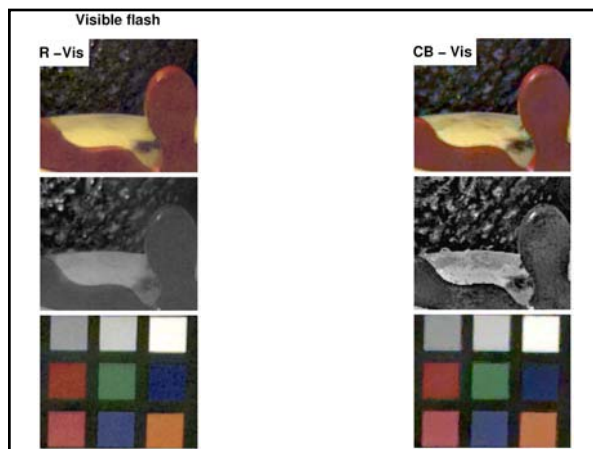
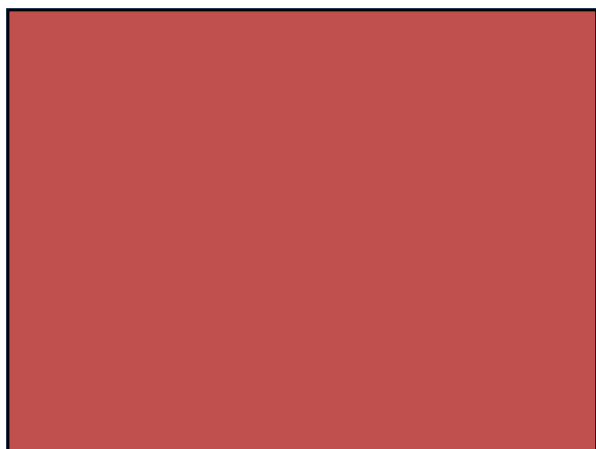
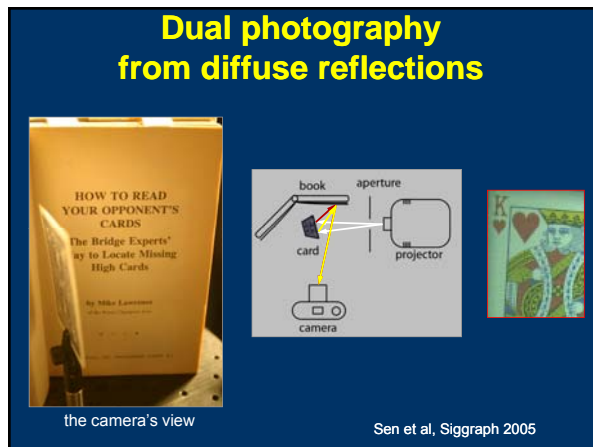
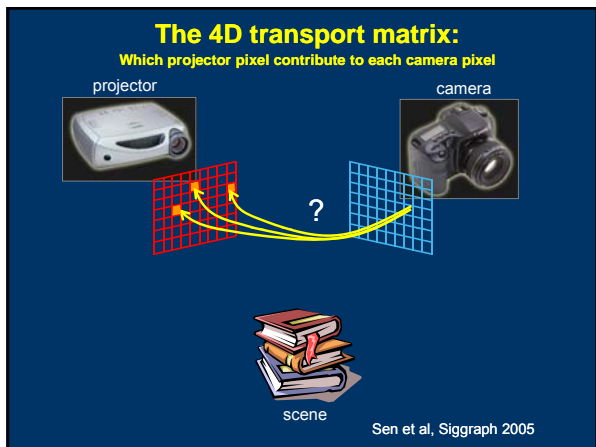
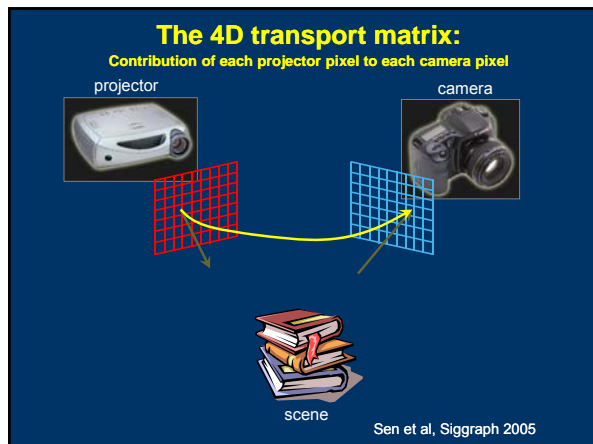
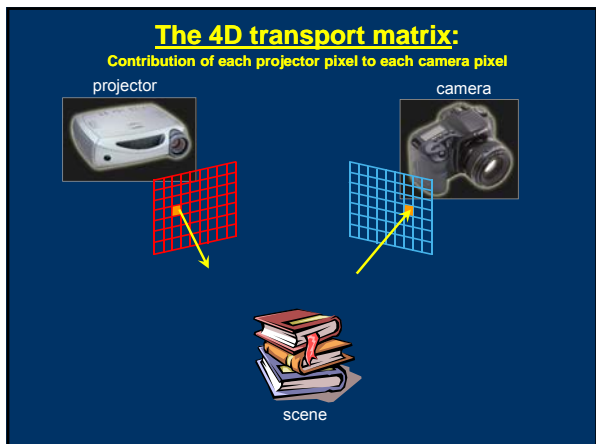
Ramesh Raskar, Computational Illumination

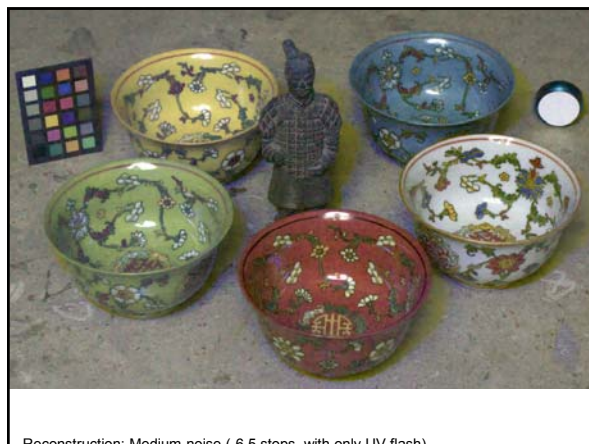
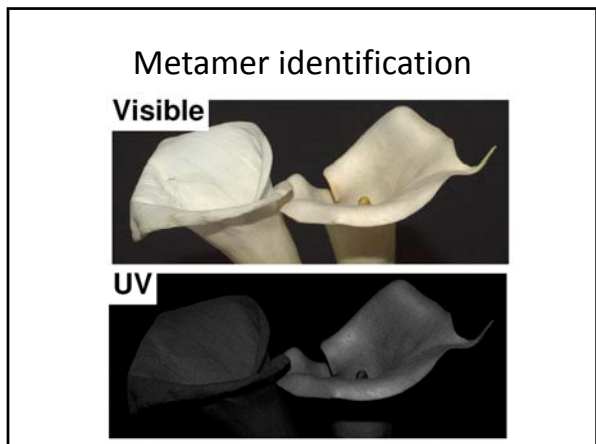
Computational Illumination:

Ramesh Raskar, Computational Illumination

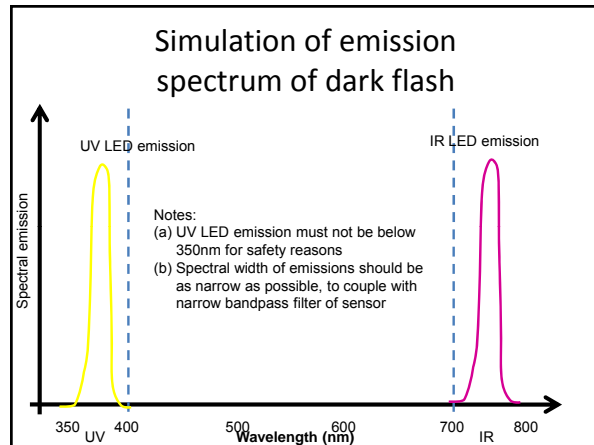
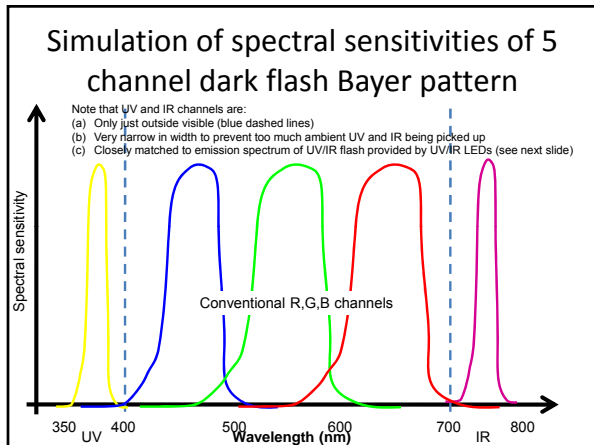
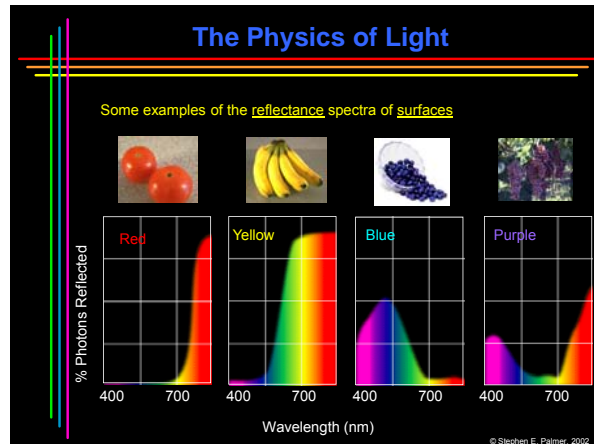
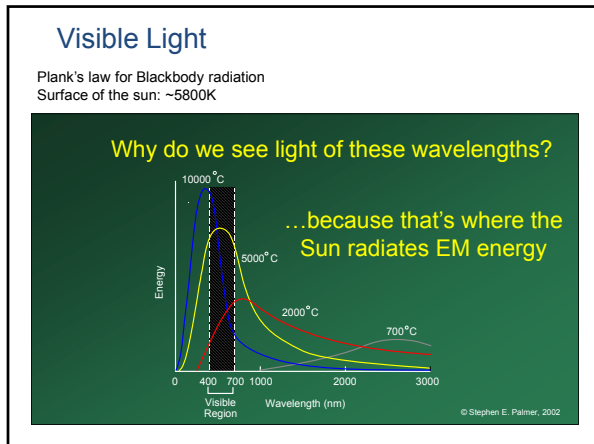
- Presence or Absence, Duration, Brightness
 - Flash/No-flash
- Light color/wavelength
- Light position
 - Multi-flash for depth edges
 - Programmable dome (image re-lighting and matting)
- Spatial Modulation
 - Dual Photography







Brief overview of Color



Dark flash design for cellphone/camera

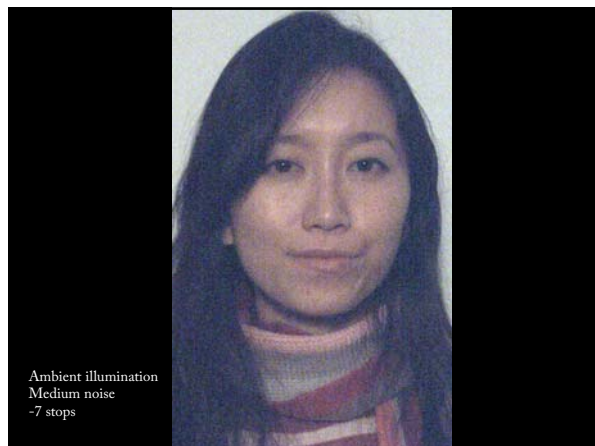
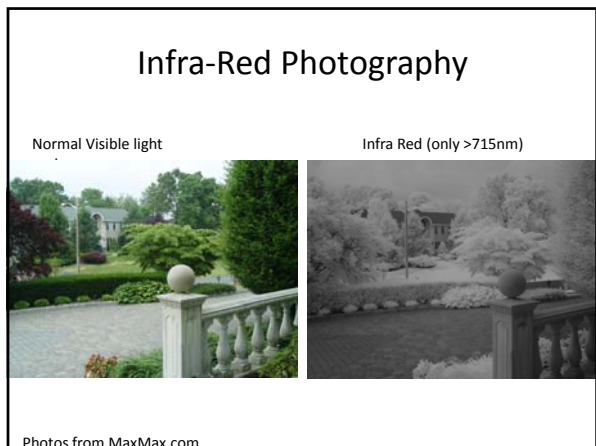
- Array of White LEDs, UV LEDs (shown in yellow) and IR LEDs (shown in magenta)
- White LEDs provided standard visible flash
- UV/IR LEDs provide dark flash
- LEDs are cheap/compact

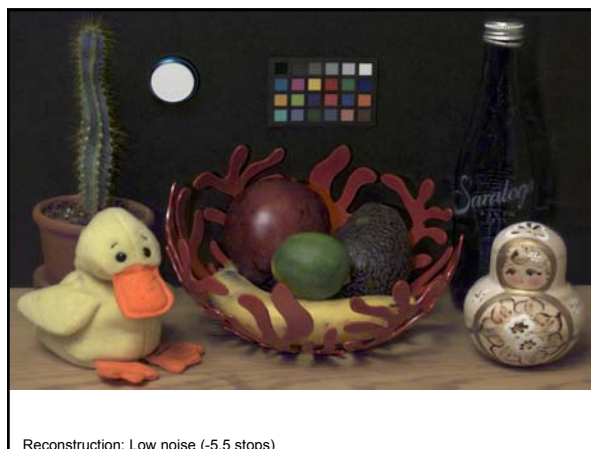
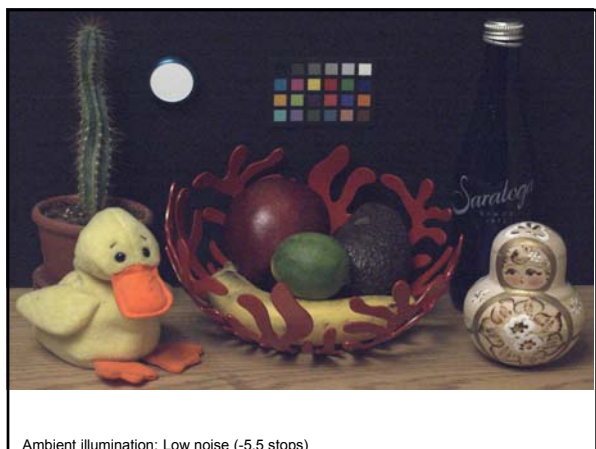
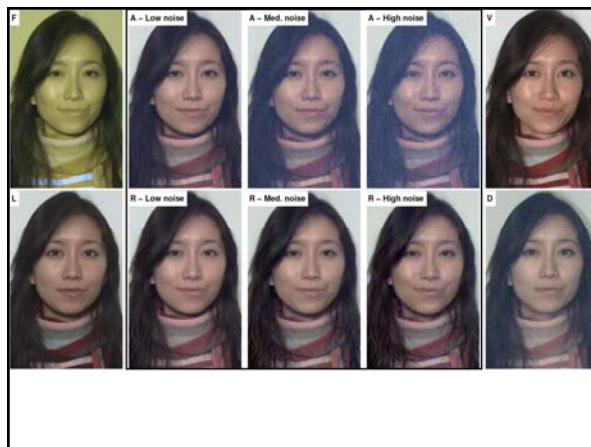
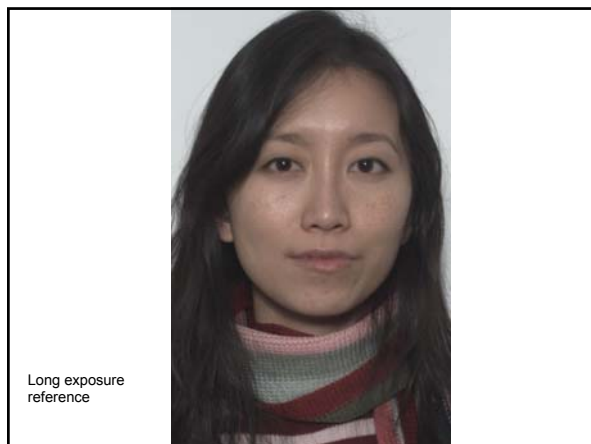
The diagram shows a 4x6 grid of circular LEDs. The colors are arranged in a repeating pattern: the first and third columns are white, the second column is yellow, and the fourth and sixth columns are magenta.

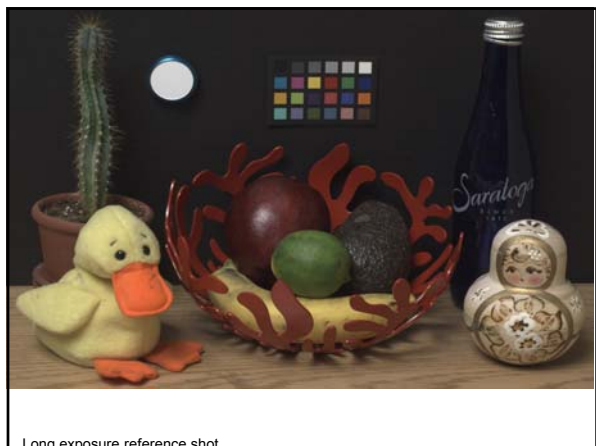
Ultra-Violet photography

The image shows a white flower on the left and its corresponding UV photograph on the right. In the UV image, the flower's petals appear blue and white, while the center is bright red, revealing details not visible in the standard photograph.

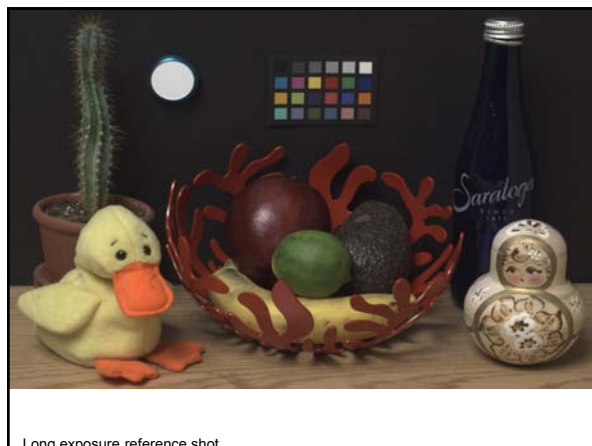
<http://www.naturfotograf.com/uvstart.html>
Potentilla anserina © Bjørn Rørslett/NN 2001



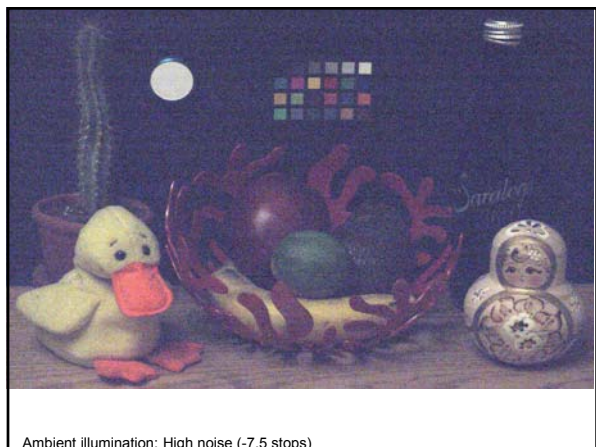




Long exposure reference shot



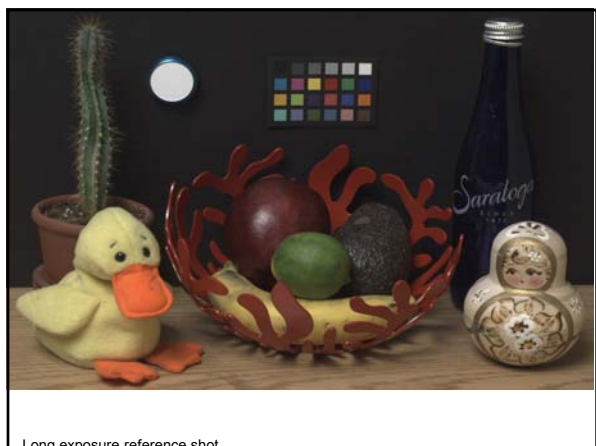
Long exposure reference shot



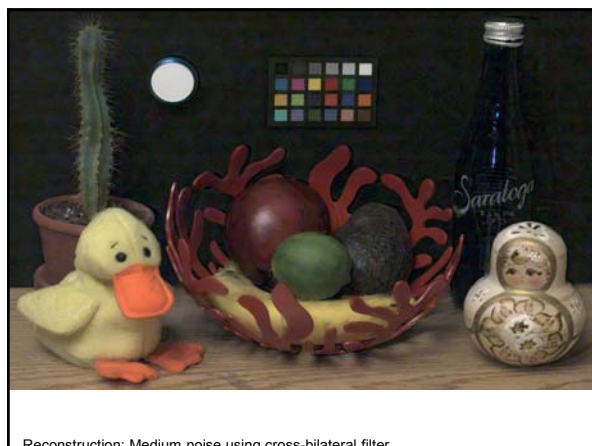
Ambient illumination: High noise (-7.5 stops)



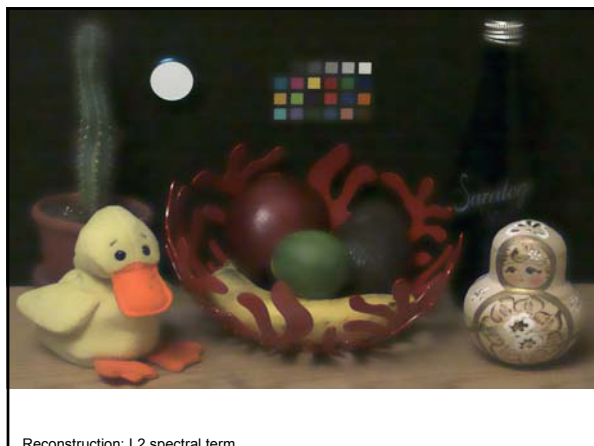
Reconstruction: High noise (-7.5 stops)



Long exposure reference shot



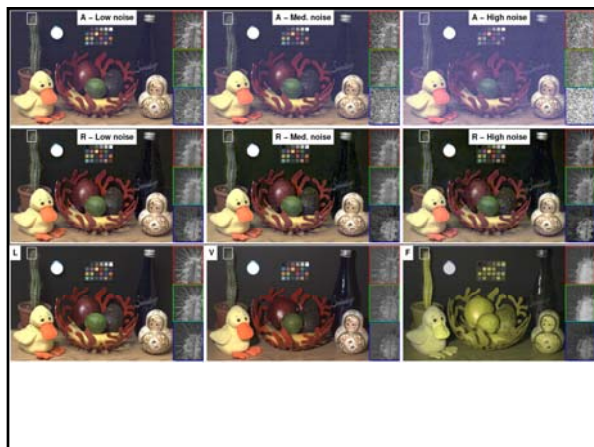
Reconstruction: Medium noise using cross-bilateral filter



Reconstruction: L2 spectral term



Reconstruction: Medium noise (-6.5 stops) with Noise Ninja denoising software



Ambient Illumination: Low noise (5.5 stops underexposed)



Reconstruction: Low noise (-5.5 stops)



Visible flash



Ambient illumination: High noise (7.5 stops underexposed)



Reconstruction: High noise (7.5 stops)



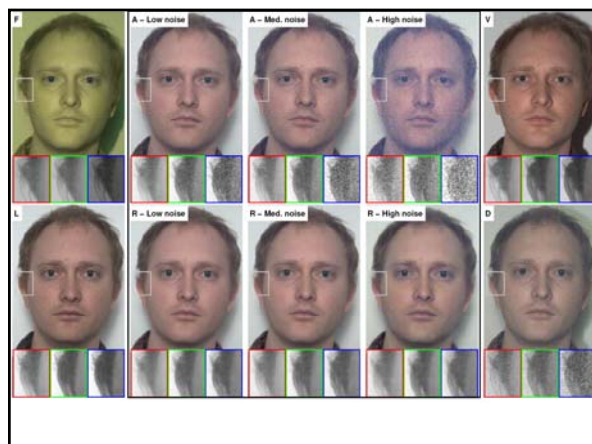
Visible flash

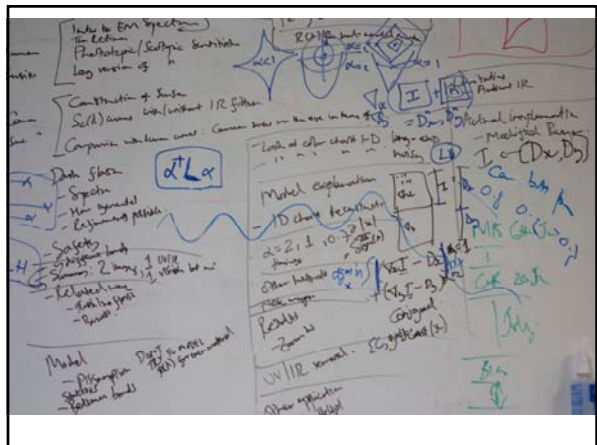
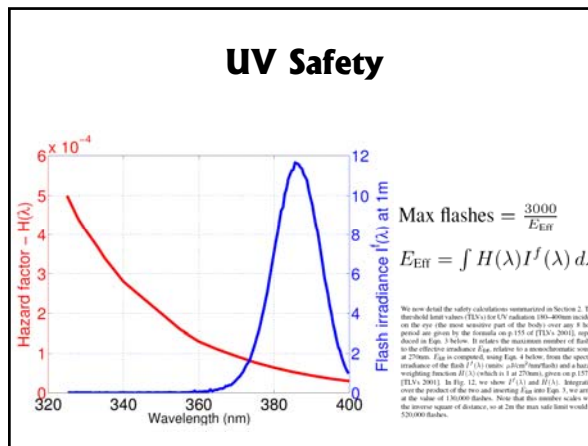


Ambient illumination
Low noise
-6 stops



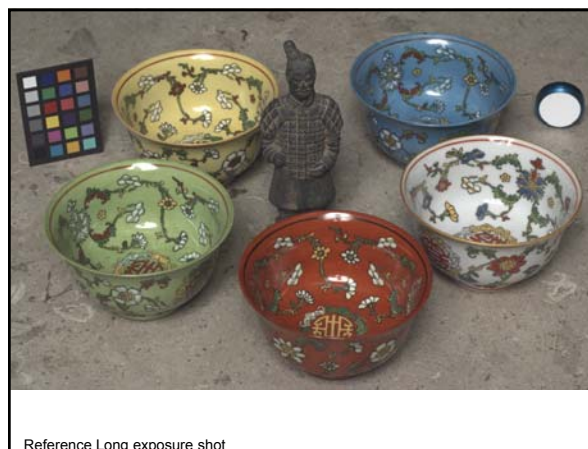
Reconstruction
Low noise
-6 stops





Cost function

- Alpha = 0.7 – sparse norm

$$\underset{R_j}{\operatorname{argmin}} \sum_p \left[\underbrace{\mu_j m(p) (R_j(p) - A_j(p))^2}_{\text{Likelihood}} + \underbrace{\kappa m(p) |\nabla R_j(p)|^\alpha}_{\text{Spatial}} + \underbrace{|\nabla R_j(p) - \nabla F_1(p)|^\alpha}_{\text{IR Spectral}} + \underbrace{|\nabla R_j(p) - \nabla F_3(p)|^\alpha}_{\text{UV Spectral}} \right]$$




Visible flash



UV/IR flash



Ambient illumination: Medium noise (-6.5 stops)



Reconstruction: Medium noise (-6.5 stops)



Reference Long exposure shot

