Lecture 8: Performance Evaluation

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What Are We trying to do?

- Measure, Report, and Summarize Performance
- Make intelligent choices

Why is some hardware better than others for different programs?

What factors of system performance are hardware related? (e.g., Do we need a new machine, or a new operating system?)

Does performance measure depends on application type?
Let’s Start with Two Simple Metrics

• Response time (aka Execution Time)
  – The time between the start and completion of a task
• Throughput
  – Total amount of work done in a given time

What is the relationship between execution time and throughput?
Computer Performance: TIME, TIME, TIME

• Response Time (latency)
  — How long does it take for my job to run?
  — How long does it take to execute a job?
  — How long must I wait for the database query?

• Throughput
  — How many jobs can the machine run at once?
  — What is the average execution rate?
  — How much work is getting done?
Try to solve this...

• Do the following changes to the computer system increase throughput, decrease response time, or both?
  – Replacing the processor with a faster version
  – Adding additional processors to a system that uses multiple processors for separate tasks.
Execution Time

- **Elapsed Time**
  - counts everything *(disk and memory accesses, I/O, etc.)*
  - a useful number, but often not good for comparison purposes

- **CPU time**
  - doesn't count I/O or time spent running other programs
  - can be broken up into system time, and user time

- **Our focus: user CPU time**
  - time spent executing the lines of code that are "in" our program
Execution Time (Elapsed Time)

- I/O Time
- CPU Time
  - User CPU Time
  - System CPU Time
- Disk and Memory time
For some program running on machine X,

\[
\text{Performance}_X = \frac{1}{\text{Execution time}_X}
\]

"X is n times faster than Y"

\[
\frac{\text{Performance}_X}{\text{Performance}_Y} = n
\]

- Example: time taken to run a program
  - 10s on A, 15s on B
  - Execution Time_B / Execution Time_A
    = 15s / 10s = 1.5
  - So A is 1.5 times faster than B
Clock Cycles

- Instead of reporting execution time in seconds, we often use cycles

\[
\frac{\text{seconds}}{\text{program}} = \frac{\text{cycles}}{\text{program}} \times \frac{\text{seconds}}{\text{cycle}}
\]

- Clock “ticks” indicate when to start activities (one abstraction):

- **cycle time** = time between ticks = seconds per cycle
- **clock rate (frequency)** = cycles per second (1 Hz. = 1 cycle/sec)

- A 4 Ghz. clock has a \( \frac{1}{4 \times 10^9} \times 10^{12} = 250 \text{ picoseconds (ps)} \) cycle time
How to Improve Performance

\[
\frac{\text{seconds}}{\text{program}} = \frac{\text{cycles}}{\text{program}} \times \frac{\text{seconds}}{\text{cycle}}
\]

So, to improve performance (everything else being equal) you can either (increase or decrease?)

- the # of required cycles for a program,
- the clock cycle time or, said another way, the clock rate.
\[
\frac{\text{seconds}}{\text{program}} = \frac{\text{cycles}}{\text{program}} \times \frac{\text{seconds}}{\text{cycle}}
\]

ET = Execution Time
CPI = Cycles Per Instruction
IC = Instruction Count
• *If two machines have the same ISA which of our quantities (e.g., clock rate, CPI, execution time, # of instructions, MIPS) will always be identical?*
How many cycles are required for a program?

- Could assume that number of cycles equals number of instructions

  ![Diagram](image)

  This assumption is incorrect, different instructions take different amounts of time on different machines.

  Why? hint: remember that these are machine instructions, not lines of C code
Different numbers of cycles for different instructions

- Multiplication takes more time than addition
- Floating point operations take longer than integer ones
- Accessing memory takes more time than accessing registers

- Important point: changing the cycle time often changes the number of cycles required for various instructions
Example

Our favorite program runs in 10 seconds on computer A, which has a 4 GHz. clock. We are trying to help a computer designer build a new machine B, that will run this program in 6 seconds. The designer can use new (or perhaps more expensive) technology to substantially increase the clock rate, but has informed us that this increase will affect the rest of the CPU design, causing machine B to require 1.2 times as many clock cycles as machine A for the same program. What clock rate should we tell the designer to target?“
Now that we understand cycles

• A given program will require
  - some number of instructions (machine instructions)
  - some number of cycles
  - some number of seconds

• We have a vocabulary that relates these quantities:
  - cycle time (seconds per cycle)
  - clock rate (cycles per second)
  - \(\text{CPI} \) (cycles per instruction)
    
    a floating point intensive application might have a higher CPI
  - MIPS (millions of instructions per second)
    
    this would be higher for a program using simple instructions
Performance

- Performance is determined by execution time
- Do any of the other variables equal performance?
  - # of cycles to execute program?
  - # of instructions in program?
  - # of cycles per second?
  - average # of cycles per instruction?
  - average # of instructions per second?
CPI Example

• Suppose we have two implementations of the same instruction set architecture (ISA).

For some program,

Machine A has a clock cycle time of 250 ps and a CPI of 2.0

Machine B has a clock cycle time of 500 ps and a CPI of 1.2

What machine is faster for this program, and by how much?

\[
\begin{align*}
10^{-3} &= \text{milli}, & 10^{-6} &= \text{micro}, & 10^{-9} &= \text{nano}, & 10^{-12} &= \text{pico}, & 10^{-15} &= \text{femto}
\end{align*}
\]
A compiler designer is trying to decide between two code sequences for a particular machine. Based on the hardware implementation, there are three different classes of instructions: Class A, Class B, and Class C, and they require one, two, and three cycles (respectively).

The first code sequence has 5 instructions: 
2 of A, 1 of B, and 2 of C

The second sequence has 6 instructions: 
4 of A, 1 of B, and 1 of C.

Which sequence will be faster? How much?
What is the CPI for each sequence?
MIPS Example

Two different compilers are being tested for a 4 GHz. machine with three different classes of instructions: Class A, Class B, and Class C, which require one, two, and three cycles (respectively). Both compilers are used to produce code for a large piece of software.

The first compiler's code uses 5 million Class A instructions, 1 million Class B instructions, and 1 million Class C instructions.

The second compiler's code uses 10 million Class A instructions, 1 million Class B instructions, and 1 million Class C instructions.

Which sequence will be faster according to MIPS? Which sequence will be faster according to execution time?
For Multithreaded Programs

• Shall we use execution time or throughput? or both?

• IPC is not accurate here
  – small timing variations may lead to different execution time
  – Order at which threads enter critical section may vary
  – Different interrupt timing may lead to different scheduling decisions

The total number of instructions executed may be different across different runs!
For Multithreaded Programs

The total number of instructions executed may be different across different runs!

This effect increases with the number of cores

System-level code account for a significant fraction of the total execution time
Your Program Does Not Run in A Vacuum

- System software at least is there
- Multi-programming setting is very common in multicore settings
- Independent programs affect each other performance (why?)
Some Metrics About Multiprogramming

Normalized progress of program $i$

$$N P_i = \frac{T_i^{SP}}{T_i^{MP}}$$

Time when running in isolation

Time when running with other programs

System throughput

$$STP = \sum_{i=1}^{n} N P_i = \sum_{i=1}^{n} \frac{T_i^{SP}}{T_i^{MP}}$$

Higher-is-better metric
Some Metrics About Multiprogramming

Normalized Turnaround time of program $i$

$$NTT_i = \frac{T_i^{MP}}{T_i^{SP}}$$

Time when running with other programs

Time when running in isolation

Average normalized turnaround time

$$ANTT = \frac{1}{n} \sum_{i=1}^{n} NTT_i = \frac{1}{n} \sum_{i=1}^{n} \frac{T_i^{MP}}{T_i^{SP}}$$

Lower-is-better metric
Other Metrics

\[
IPC_{throughput} = \sum_{i=1}^{n} IPC_i
\]

\[
weighted_{speedup} = \sum_{i=1}^{n} \frac{IPC_i^{MP}}{IPC_i^{SP}}
\]

\[
hmean = \frac{n}{\sum_{i=1}^{n} \frac{IPC_i^{SP}}{IPC_i^{MP}}}
\]
Other Metrics

\[
STP = \sum_{i=1}^{n} NP_i = \sum_{i=1}^{n} \frac{T_i^{SP}}{T_i^{MP}}
\]

\[
ANTT = \frac{1}{n} \sum_{i=1}^{n} NTT_i = \frac{1}{n} \sum_{i=1}^{n} \frac{T_i^{MP}}{T_i^{SP}},
\]

\[
\text{weighted\_speedup} = \sum_{i=1}^{n} \frac{IPC_{i}^{MP}}{IPC_{i}^{SP}}
\]

\[
hmean = \frac{n}{\sum_{i=1}^{n} \frac{IPC_{i}^{SP}}{IPC_{i}^{MP}}}
\]
Harmonic Vs Arithmetic

• Both used to compute an average (i.e. combine several measures) of a metric.

• Assume the metric is computed $A/B$
  – If $A$ is weighted equally among all the benchmarks → then harmonic mean is meaningful.
  – If $B$ → arithmetic mean

• Example: Suppose we gathered IPC of several benchmarks and want to combine them
  – If we execute all benchmarks for the same amount of instructions (e.g. 1 billion instructions) → hmean
  – If we execute all the benchmarks for the same amount of cycles → arithmetic mean
What we saw for multiprogramming, can it be used in multithreading?
How to test the performance of a multicore system?
Benchmarks

- Performance best determined by running a real application
  - Use programs typical of expected workload
  - Or, typical of expected class of applications
  - e.g., compilers/editors, scientific applications, graphics, etc.
- Small benchmarks
  - nice for architects and designers
  - easy to standardize
- Parallel Benchmarks: PARSEC, Rodinia, SPLASH-2
- SPEC (System Performance Evaluation Cooperative)
  - companies have agreed on a set of real program and inputs
  - valuable indicator of performance (and compiler technology)
Role of Benchmarks

- help designer explore architectural designs
- identify bottlenecks
- compare different systems
- conduct performance prediction
Example: PARSEC

- **Princeton Application Repository for Shared-Memory Computers**
- Benchmark Suite for Chip-Multiprocessors
- Freely available at: http://parsec.cs.princeton.edu/
- **Objectives:**
  - Multithreaded Applications: Future programs must run on multiprocessors
  - Emerging Workloads: Increasing CPU performance enables new applications
  - Diverse: Multiprocessors are being used for more and more tasks
  - State-of-Art Techniques: Algorithms and programming techniques evolve rapidly
### Example: PARSEC

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<tr>
<th>Program</th>
<th>Application Domain</th>
<th>Parallelization</th>
</tr>
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<tbody>
<tr>
<td>Blackscholes</td>
<td>Financial Analysis</td>
<td>Data-parallel</td>
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<tr>
<td>Bodytrack</td>
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<td>Canneal</td>
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<td>Dedup</td>
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<td>Facesim</td>
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<td>Ferret</td>
<td>Similarity Search</td>
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<td>Fluidanimate</td>
<td>Animation</td>
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<td>Freqmine</td>
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<td>Streamcluster</td>
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<td>Swaptions</td>
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<td>Vips</td>
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<td>Data-parallel</td>
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<tr>
<td>X264</td>
<td>Media Processing</td>
<td>Pipeline</td>
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</tbody>
</table>
Example: Rodinia

- A Benchmark Suite for Heterogeneous Computing: multicore CPU and GPU
- University of Virginia

<table>
<thead>
<tr>
<th>Application / Kernel</th>
<th>Dwarf</th>
<th>Domain</th>
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<tbody>
<tr>
<td>K-means</td>
<td>Dense Linear Algebra</td>
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<td>Needleman-Wunsch</td>
<td>Dynamic Programming</td>
<td>Bioinformatics</td>
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<tr>
<td>HotSpot*</td>
<td>Structured Grid</td>
<td>Physics Simulation</td>
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<td>Back Propagation*</td>
<td>Unstructured Grid</td>
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<td>SRAD</td>
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<td>Leukocyte Tracking</td>
<td>Structured Grid</td>
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<td>Breadth-First Search*</td>
<td>Graph Traversal</td>
<td>Graph Algorithms</td>
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<tr>
<td>Stream Cluster*</td>
<td>Dense Linear Algebra</td>
<td>Data Mining</td>
</tr>
<tr>
<td>Similarity Scores*</td>
<td>MapReduce</td>
<td>Web Mining</td>
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</table>
My program is slow ...  
What to do?
What is a bottleneck?
Any code segment for which threads contend (i.e. wait)

Examples:

- **Amdahl’s serial portions**
  - Only one thread exists → on the critical path

- **Critical sections**
  - Ensure mutual exclusion → likely to be on the critical path if contended

- **Barriers**
  - Ensure all threads reach a point before continuing → the latest thread arriving is on the critical path

- **Pipeline stages**
  - Different stages of a loop iteration may execute on different threads, slowest stage makes other stages wait → on the critical path

Bottlenecks in Multithreaded Applications

... José A. Joao, M. Aater Suleman, Onur Mutlu, Yale N. Patt
Observation: Limiting Bottlenecks Change Over Time

A = full linked list; B = empty linked list

repeat
  Lock A
  Traverse list A
  Remove X from A
  Unlock A
  Compute on X
  Lock B
  Traverse list B
  Insert X into B
  Unlock B
until A is empty

32 threads

Lock A is limiter
Lock B is limiter

Contention (# of threads waiting)

Bottleneck Identification and Scheduling in Multithreaded Applications ... José A. Joao, M. Aater Suleman, Onur Mutlu, Yale N. Patt
Tools you can use for profiling

- http://valgrind.org/info/tools.html
- http://oprofile.sourceforge.net/about/
- http://www.rotateright.com/
Conclusions

- Performance evaluation is very important to assess programming quality as well as the underlying architecture and how they interact.
- The following capture some aspects of the system but do not represent overall performance: MIPS, #instructions, #cycles, frequency
- Execution time is what matters: system time, CPU time, I/O and memory time
- For parallel applications: system throughput and average normalized turn-around time are good measures.
- IPC (or CPI) is not a good measure for multithreaded applications